# POSITIVE AND SIGN-CHANGING SOLUTIONS FOR THE FRACTIONAL KIRCHHOFF EQUATION WITH CRITICAL GROWTH* 

Qiu-Ying Peng ${ }^{1}$, Zeng-Qi $\mathrm{Ou}^{1}$ and Ying $\mathrm{Lv}^{1, \dagger}$


#### Abstract

We are interested in the existence of positive and sign-changing solutions for a fractional Kirchhoff equation. Under some mild conditions on the potentials $V$ and $h$, using variational methods, we prove the existence of positive ground state solutions and least energy sign-changing solutions.


Keywords Fractional Kirchhoff equation, variational method, positive solution, sign-changing solution.

MSC(2010) 34C37, 58E05, 70H05.

## 1. Introduction and main results

The paper is to study the following fractional Kirchhoff equation

$$
\begin{equation*}
\left(a+b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} d x\right)(-\Delta)^{s} u+V(x) u=h(x)|u|^{p-2} u+|u|^{2_{s}^{*}-2} u \text { in } \mathbb{R}^{3} \tag{1.1}
\end{equation*}
$$

where $a, b>0, s \in\left(\frac{3}{4}, 1\right)$ and $p \in\left(4,2_{s}^{*}\right)$ with $2_{s}^{*}=\frac{6}{3-2 s}$. The potential functions $V(x)$ and $h(x)$ can be nonconstant, indefinite in sign and nonradial. Specifically, if we denote $V^{-}(x):=\max \{-V(x), 0\}$, conditions are as follows:
$\left(V_{1}\right) \quad V^{-} \in L^{\frac{2_{s}^{*}}{2_{s}^{*}-2}}\left(\mathbb{R}^{3}\right), \int_{\mathbb{R}^{3}}\left|V^{-}(x)\right|^{\frac{2_{s}^{*}}{2_{s}^{*}-2}} d x<S^{\frac{2_{s}^{*}}{2_{s}^{2}-2}}$, where $S$ denotes the best Sobolev constant:

$$
S:=\inf _{u \in D^{s, 2}\left(\mathbb{R}^{3}\right) \backslash\{0\}} \frac{\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} d x}{\left(\int_{\mathbb{R}^{3}}|u|^{2_{s}^{*}} d x\right)^{\frac{2}{2_{s}^{*}}}} ;
$$

$\left(V_{2}\right)$ There exist $\gamma>0, C_{v}>0$, such that

$$
V(x) \leq V_{\infty}-C_{v} e^{-\gamma|x|} \text { for a.e. } x \in \mathbb{R}^{3}, \text { where } V_{\infty}:=\lim _{|x| \rightarrow+\infty} V(x)>0
$$

(h) $\quad h(x) \in C\left(\mathbb{R}^{3}\right)$, there exist $\theta>0, C_{h}>0$, such that

$$
h(x) \geq h_{\infty}-C_{h} e^{-\theta|x|} \text { for a.e. } x \in \mathbb{R}^{3}, \text { where } h_{\infty}:=\lim _{|x| \rightarrow+\infty} h(x)>0 .
$$

[^0]The fractional Laplacian $(-\Delta)^{s}$ is a nonlocal operator which is defined by

$$
(-\Delta)^{s} u(x)=C_{N, s} P . V \cdot \int_{\mathbb{R}^{N}} \frac{u(x)-u(y)}{|x-y|^{N+2 s}} \mathrm{~d} y=C_{N, s} \lim _{\varepsilon \rightarrow 0^{+}} \int_{\mathbb{R}^{N} \backslash B_{\varepsilon}(x)} \frac{u(x)-u(y)}{|x-y|^{N+2 s}} \mathrm{~d} y,
$$

where $u \in S\left(\mathbb{R}^{N}\right)$, which stands for the Schwartz space of rapidly decaying $C^{\infty}$ functions. P.V. denotes the Cauchy principle value and $C_{N, s}$ denotes a normalization constant. This operator arises in the description of various phenomena in applied sciences, such as phase transitions, materials science, conservation laws, minimal surfaces, water waves, optimization, plasma physics and so on, see [5] and references therein for more detailed introduction.

When $s=1$, problem 1.1 is related to the classical Kirchhoff problem:

$$
\begin{equation*}
-\left(a+b \int_{\mathbb{R}^{3}}|\nabla u|^{2} d x\right) \Delta u+V(x) u=f(x, u) \quad \text { in } \mathbb{R}^{3} . \tag{1.2}
\end{equation*}
$$

For the existence of sign-changing solutions to Kirchhoff problem like (1.2), we refer to $[1,17,20]$ and references therein. For the critical situation, Xu and Chen [21] proved the existence of positive and sign-changing solutions with variational method.

When $a=1$ and $b=0$, problem (1.1) is related to the usual fractional Schrödinger problem:

$$
\begin{equation*}
(-\Delta)^{s} u+V(x) u=f(x, u) \quad \text { in } \mathbb{R}^{3} . \tag{1.3}
\end{equation*}
$$

As we know, the path integral over Lévy-like quantum mechanics paths allows one to develop a generalization of quantum mechanics; namely, if the path integral over Brownian trajectories leads to the classical Schrödinger equation, then the path integral over Lévy trajectories leads to the fractional Schrödinger equation. The fractional Schrödinger equation is a fundamental equation in the study of particles on stochastic fields modeled by Lévy processes, which occur widely in physics, chemistry and biology. Therefore, the fractional Schrödinger problem like (1.3) has been extensively investigated. Concerning the existence of sign-changing solutions for it, we refer to $[11,13,18]$. Li etc [13] showed that problem (1.3) with $f(x, u)=$ $f(u)$ has a positive ground state solution and a sign-changing solution. When $f(x, u)=|u|^{p-1} u$ where $p \in\left(1,2_{s}^{*}-1\right)$, Wang and Zhou [18] obtained a radial signchanging solution. For the critical situation, [11] proved the existence of infinitely many non-radial sign-changing solutions.

The usual fractional Kirchhoff problem is as follows:

$$
\begin{equation*}
\left(a+b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} d x\right)(-\Delta)^{s} u+V(x) u=f(x, u) \quad \text { in } \mathbb{R}^{3} . \tag{1.4}
\end{equation*}
$$

Recently, Fiscella and Valdinoci [7] first proposed a stationary Kirchhoff model involving the fractional Laplacian. Then, many papers have been devoted to studying the existence of solutions for fractional Kirchhoff like equation (1.4), see [6, $9,15,16$, 22 ] and the references therein. We must point out that there are a few results on the existence of sign-changing solutions, see [2, 4, 10, 12]. Cheng and Gao [2] used the constraint variational method and quantitative deformation lemma to obtain a least energy nodal solution. Chen etc [4] studied the existence and asymptotic behavior of sign-changing solutions in low dimensions. Luo etc [12] proved a ground
state sign-changing solution in bounded domains. The recent one, Isernia [10] used a minimization argument and a quantitative deformation lemma to establish the existence of least energy sign-changing solutions.

To the authors' knowledge, there is no result on the existence of least energy sign-changing solutions for problem (1.1). One of the main difficulties is the presence of nonlocal term $\left(a+b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} d x\right)(-\triangle)^{s} u$, the other is the critical term that makes the problem complicated due to the lack of compactness.

In order to prove the existence of positive solutions: Firstly, through the Ekeland Variational Principle, we get a Palais-Smale sequence on the Nehari manifold. Later to overcome the problem of the lack of compactness, we use some comparison arguments about the minimax level of energy functional and that of the limit problem, here the conditions $\left(V_{2}\right),(h)$ play the important role. On the other hand, the existence of sign-changing solutions is usually studied on the Nodal manifold. People used to use the method of a finite dimensional space to approximate infinite dimensional space or the quantitative deformation lemma to prove it. However in our paper, we try to seek a minimizer of the energy functional over a manifold $\mathcal{N}^{*}$, which is a variant of Nodal Nehari manifold. Setting $\left\|u^{ \pm}\right\|^{2}=\int_{\mathbb{R}^{3}}\left(a\left|(-\Delta)^{\frac{s}{2}} u^{ \pm}\right|^{2}+V(x)\left(u^{ \pm}\right)^{2}\right) d x$, the manifold $\mathcal{N}^{*}$ is as follows:

$$
\mathcal{N}^{*}=\left\{u \in X \backslash\{0\}: f\left(u^{+}\right)=f\left(u^{-}\right)=1\right\}
$$

where

$$
\begin{aligned}
& f\left(u^{+}\right)=\frac{\int_{\mathbb{R}^{3}} h(x)\left|u^{+}\right|^{p} \mathrm{~d} x+\int_{\mathbb{R}^{3}}\left|u^{+}\right|^{2_{s}^{*}} \mathrm{~d} x}{\left\|u^{+}\right\|^{2}+b \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u\right|^{2} \mathrm{~d} x \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u^{+}\right|^{2} \mathrm{~d} x}, \quad \text { with } u^{+}:=\max \{u, 0\}, \\
& f\left(u^{-}\right)=\frac{\int_{\mathbb{R}^{3}} h(x)\left|u^{-}\right|^{p} \mathrm{~d} x+\int_{\mathbb{R}^{3}}\left|u^{-}\right|^{2_{s}^{*}} \mathrm{~d} x}{\left\|u^{-}\right\|^{2}+b \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u\right|^{2} \mathrm{~d} x \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u^{-}\right|^{2} \mathrm{~d} x}, \quad \text { with } u^{-}:=\min \{u, 0\}
\end{aligned}
$$

Then we show the minimum of the energy functional on the manifold $\mathcal{N}^{*}$ is the sign-changing solution of problem (1.1).

From the above arguments, to overcome the lack of compactness, we are going to consider the limit problem of (1.1), namely

$$
\begin{equation*}
\left(a+b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} d x\right)(-\Delta)^{s} u+V_{\infty} u=h_{\infty}|u|^{p-2} u+|u|^{2_{s}^{*}-2} u \tag{1.5}
\end{equation*}
$$

Argued as in [9], we can easily prove the limit problem (1.5) has a positive ground state solution $w$. Thus if one set $\alpha:=\left(a+b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} w\right|^{2} d x\right)^{\frac{1}{2 s}}$, we can state the main results of this paper.

Theorem 1.1. Assume $\left(V_{1}\right)-\left(V_{2}\right)$, $(h)$ hold and $s \in\left(\frac{3}{4}, 1\right), p \in\left(4,2_{s}^{*}\right)$. If $\gamma<\theta<\frac{p \sqrt{V_{\infty}}}{\alpha}$, the problem (1.1) possesses a positive ground state solution.

Theorem 1.2. Assume $\left(V_{1}\right)-\left(V_{2}\right)$, $(h)$ hold and $s \in\left(\frac{3}{4}, 1\right)$, $p \in\left(4,2_{s}^{*}\right)$. If $\gamma<\min \left\{\theta, \frac{\sqrt{V_{\infty}}}{\alpha}\right\}, \theta<\frac{p \sqrt{V_{\infty}}}{\alpha}$, the problem (1.1) possesses a least energy signchanging solution.

Remark 1.1. The conditions on the exponent $\gamma$ and $\theta$ are of technical nature, which will appear when trying to localize the minimax level (of the energy functional) in the correct compactness range. Moreover, for sign-changing solution, it needs a stronger restrictions on the exponent $\gamma$.

## Notations:

- $L^{p}\left(\mathbb{R}^{3}\right), p \in[1,+\infty)$ is the Lebesgue space with the norm $\|u\|_{p}=\left(\int_{\mathbb{R}^{3}}|u|^{p} d x\right)^{\frac{1}{p}}$.
- $D^{s, 2}\left(\mathbb{R}^{3}\right)$ is the completion of $C_{0}^{\infty}\left(\mathbb{R}^{3}\right)$ endowed with the norm
$\|u\|_{D^{s, 2}}^{2}=\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} d x$.
- $H^{s}\left(\mathbb{R}^{3}\right)$ is the usual fractional Sobolev space endowed with the nature norm

$$
\|u\|_{H^{s}\left(\mathbb{R}^{3}\right)}^{2}=\int_{\mathbb{R}^{3}}\left(\left|(-\Delta)^{\frac{s}{2}} u\right|^{2}+|u|^{2}\right) d x
$$

- In this paper, because of the presence of potential $V$, we denote the fractional Sobolev space for problem (1.1) as follows

$$
X=\left\{u \in H^{s}\left(\mathbb{R}^{3}\right): \int_{\mathbb{R}^{3}}\left(a\left|(-\Delta)^{\frac{s}{2}} u\right|^{2}+V(x) u^{2}\right) d x<\infty\right\}
$$

defined the norm in $X$ by

$$
\|u\|^{2}=\int_{\mathbb{R}^{3}}\left(a\left|(-\Delta)^{\frac{s}{2}} u\right|^{2}+V(x) u^{2}\right) d x
$$

By [13], we know $X$ is continuously embedded into $L^{p}\left(\mathbb{R}^{3}\right)$ for $p \in\left[2,2_{s}^{*}\right]$.

- $C, C_{i}$ denote various positive constants, which may vary from line to line.


## 2. Positive solution

The energy functional associated with problem (1.1) is defined by

$$
I(u)=\frac{1}{2}\|u\|^{2}+\frac{b}{4}\left(\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} d x\right)^{2}-\frac{1}{p} \int_{\mathbb{R}^{3}} h(x)|u|^{p} d x-\frac{1}{2_{s}^{*}} \int_{\mathbb{R}^{3}}|u|^{2_{s}^{*}} d x
$$

obviously, $I \in C^{1}(X, \mathbb{R})$ and the critical points of $I$ are the weak solutions of problem (1.1).

Thought this paper, we denote

$$
\|u\|_{\infty}^{2}:=\int_{\mathbb{R}^{3}}\left(a\left|(-\Delta)^{\frac{s}{2}} u\right|^{2}+V_{\infty} u^{2}\right) d x
$$

the energy functional associated with limit problem (1.5) is given by

$$
I_{\infty}(u)=\frac{1}{2}\|u\|_{\infty}^{2}+\frac{b}{4}\left(\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} d x\right)^{2}-\frac{1}{p} \int_{\mathbb{R}^{3}} h_{\infty}|u|^{p} d x-\frac{1}{2_{s}^{*}} \int_{\mathbb{R}^{3}}|u|^{2_{s}^{*}} d x
$$

The functional $I(u)$ and $I_{\infty}(u)$ are respectively restricted on the following manifold $\mathcal{N}, \mathcal{N}_{\infty}$ :

$$
\begin{aligned}
& \mathcal{N}=\left\{u \in X \backslash\{0\}:\left\langle I^{\prime}(u), u\right\rangle=0\right\}, m=\inf _{u \in \mathcal{N}} I(u) \\
& \mathcal{N}_{\infty}=\left\{u \in X \backslash\{0\}:\left\langle I_{\infty}^{\prime}(u), u\right\rangle=0\right\}, m_{\infty}=\inf _{u \in \mathcal{N}_{\infty}} I(u)
\end{aligned}
$$

Lemma 2.1. The limit problem (1.5) has a positive solution $w \in X$ such that $I_{\infty}(w)=m_{\infty}$. Moreover, if we set $\alpha:=\left(a+b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} w\right|^{2} d x\right)^{\frac{1}{2 s}}$, then for any $\delta \in\left(0, \sqrt{V_{\infty}}\right)$, there exists $C=C(\delta)>0$ such that

$$
w(x) \leq C e^{-\frac{\delta}{\alpha}|x|}, \quad \forall x \in \mathbb{R}^{3}
$$

Proof. By (h), the existence of $w$ is similar to section 2 in [9]. It's easy to see $\alpha^{2 s}=a+b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} w\right|^{2} d x$. Because the integral range of $b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} w\right|^{2} d x$ is $\mathbb{R}^{3}$, we know $b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} w\right|^{2} d x$ is a constant no matter $w$ is $w(x)$ or $w(\alpha x)$. For any $x \in \mathbb{R}^{3}$, let $v(x):=w(\alpha x)$, there holds

$$
\begin{aligned}
(-\Delta)^{s} v(x) & =\alpha^{2 s}(-\Delta)^{s} w(\alpha x) \\
& =h_{\infty}|w(\alpha x)|^{p-2} w(\alpha x)+|w(\alpha x)|^{2_{s}^{*}-2} w(\alpha x)-V_{\infty} w(\alpha x)
\end{aligned}
$$

Thus $(-\Delta)^{s} v+V_{\infty} v=h_{\infty}|v|^{p-2} v+|v|^{2_{s}^{*}-2} v$. By [8], we can get $v(x) \in L^{\infty}\left(\mathbb{R}^{3}\right)$ and $v(x)=w(\alpha x) \rightarrow 0$ as $|x| \rightarrow \infty$. So for any $0<\delta<\sqrt{V_{\infty}}$, there exists $R:=R(\delta)>0$, such that for $|x| \geq R$, we have $V_{\infty}-h_{\infty}|v|^{p-2}-|v|^{2_{s}^{*}-2} \geq \delta^{2}$. Then $(-\triangle)^{s} v+\delta^{2} v \leq 0$ for $|x| \geq R$. And there exists $M=M(\delta)>0$, such that $v(x) \leq M$ for $|x|=R$. Let $\bar{v}(x)=M \cdot e^{-\delta(|x|-R)}$, a direct calculation can drive that $(-\triangle)^{s} \bar{v}+\delta^{2} \bar{v} \geq 0$ for $x \neq 0$. The Maximum Principle implies that $v(x) \leq M \cdot e^{-\delta(|x|-R)}$ for $|x| \geq R$, thus $w(x) \leq C e^{-\frac{\delta}{\alpha}|x|}$.
Lemma 2.2. $\mathcal{N}$ is nonempty and it's a $C^{1}$ manifold. Moreover, $m=\inf _{u \in \mathcal{N}} I(u)>0$.
Proof. For $n \in \mathbb{N}$, we define $w_{n}(x):=w\left(x-x_{n}\right)$, where $w$ is given by Lemma 2.1 and $x_{n}:=(0,0, n)$. Since $w$ is a positive solution, we have $\int_{\mathbb{R}^{3}}\left|w_{n}\right|^{2_{s}^{*}} d x>0$. So $I\left(t w_{n}\right)>0$ for $t>0$ small and $I\left(t w_{n}\right)<0$ for t large. $I\left(t w_{n}\right)$ achieves its maximum at some $t_{n}>0$, thus $\left\langle I^{\prime}\left(t_{n} w_{n}\right),\left(t_{n} w_{n}\right)\right\rangle=0$, which implies $t_{n} w_{n} \in \mathcal{N} \neq \emptyset$. For any $u \in \mathcal{N}$,

$$
\left\langle I^{\prime}(u), u\right\rangle=\|u\|^{2}+b\left(\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} d x\right)^{2}-\int_{\mathbb{R}^{3}} h(x)|u|^{p} d x-\int_{\mathbb{R}^{3}}|u|^{2_{s}^{*}} d x=0
$$

By $(h)$ and Sobolev embedding theorems, it follows that

$$
\|u\|^{2} \leq \int_{\mathbb{R}^{3}} h(x)|u|^{p} d x+\int_{\mathbb{R}^{3}}|u|^{2_{s}^{*}} d x \leq C\|u\|^{p}+S^{-\frac{2_{s}^{*}}{2}}\|u\|^{2_{s}^{*}}
$$

since $p, 2_{s}^{*}>2$, there exists $\varrho>0$ such that

$$
\begin{equation*}
\|u\|^{2} \geq \varrho>0, \quad \forall u \in \mathcal{N} \tag{2.1}
\end{equation*}
$$

From $(h)$, for any $\varepsilon>0$, there exists $C(\varepsilon)>0$, such that for any $u \in \mathcal{N}$, we have

$$
\begin{equation*}
\|u\|^{2} \leq \int_{\mathbb{R}^{3}} h(x)|u|^{p} d x+\int_{\mathbb{R}^{3}}|u|^{2_{s}^{*}} d x \leq \varepsilon \int_{\mathbb{R}^{3}}|u|^{2} d x+C(\varepsilon) \int_{\mathbb{R}^{3}}|u|^{2_{s}^{*}} d x \tag{2.2}
\end{equation*}
$$

set $\varepsilon<\frac{1}{2}$, by Sobolev embedding theorem, one can conclude that there exists $C(S)>0$, such that

$$
\begin{equation*}
\left(\int_{\mathbb{R}^{3}}|u|^{2_{s}^{*}} d x\right)^{\frac{2}{2_{s}^{*}}} \leq C(S) \int_{\mathbb{R}^{3}}|u|^{2_{s}^{*}} d x \tag{2.3}
\end{equation*}
$$

hence $\int_{\mathbb{R}^{3}}|u|^{2_{s}^{*}} d x>C(S)^{\frac{2_{s}^{*}}{2-2_{s}^{*}}}>0, \quad \forall u \in \mathcal{N}$.
If we define $J: X \rightarrow \mathbb{R}$ where $J(u):=\left\langle I^{\prime}(u), u\right\rangle$, thus

$$
\left\langle J^{\prime}(u), u\right\rangle=(2-p)\|u\|^{2}+(4-p) b\left(\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} d x\right)^{2}
$$

$$
\begin{equation*}
+\left(p-2_{s}^{*}\right) \int_{\mathbb{R}^{3}}|u|^{2_{s}^{*}} d x<0 \tag{2.4}
\end{equation*}
$$

it follows from the Implicit Function Theorem that $\mathcal{N}$ is a $C^{1}$ manifold. Finally, if $u \in \mathcal{N}$, from (2.1) we have

$$
\begin{equation*}
I(u)=I(u)-\frac{1}{p}\left\langle I^{\prime}(u), u\right\rangle \geq\left(\frac{1}{2}-\frac{1}{p}\right)\|u\|^{2}>0, \tag{2.5}
\end{equation*}
$$

so $m=\inf _{u \in \mathcal{N}} I(u)>0$. The lemma is proved.
Lemma 2.3. $m<m_{\infty}$.
Proof. Let $w_{n}$ and $t_{n}$ be defined as in the proof of Lemma 2.2. Since $t_{n}>0$ and $t_{n} w_{n} \in \mathcal{N}$, there holds

$$
\begin{align*}
& t_{n}^{-2}\left\|w_{n}\right\|^{2}+b\left(\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} w_{n}\right|^{2} d x\right)^{2} \\
= & t_{n}^{p-4} \int_{\mathbb{R}^{3}} h(x)\left|w_{n}\right|^{p} d x+t_{n}^{2_{s}^{*}-4} \int_{\mathbb{R}^{3}}\left|w_{n}\right|^{2_{s}^{*}} d x, \tag{2.6}
\end{align*}
$$

which implies that $\left\{t_{n}\right\}$ is bounded. Otherwise if $\left\{t_{n}\right\} \rightarrow \infty$, the left-hand side of (2.6) is bounded, the right-hand side is unbounded, which is a contradiction. Thus there exists $t_{0} \geq 0$, such that $t_{n} \rightarrow t_{0}$, as $n \rightarrow \infty$. By (2.1), we have $0<C \leq\left\|t_{n} w_{n}\right\|^{2}=t_{n}^{2}\left\|w_{n}\right\|^{2}$, it's easy to see $t_{0}>0$.

Now we notice that

$$
\begin{align*}
m \leq I\left(t_{n} w_{n}\right) & =I_{\infty}\left(t_{n} w_{n}\right)+\frac{t_{n}^{2}}{2} \int_{\mathbb{R}^{3}}\left(V(x)-V_{\infty}\right) w_{n}^{2} d x+\frac{t_{n}^{p}}{p} \int_{\mathbb{R}^{3}}\left(h_{\infty}-h(x)\right) w_{n}^{p} d x \\
& :=I_{\infty}\left(t_{n} w_{n}\right)+\frac{t_{n}^{2}}{2} A_{n}+\frac{t_{n}^{p}}{p} D_{n} . \tag{2.7}
\end{align*}
$$

From Lemma 2.1, one has $w(x) \leq C e^{-\frac{\delta}{\alpha}|x|}$. Using $\left|x+x_{n}\right| \leq|x|+n$, we infer from $\left(V_{2}\right)$ that

$$
\begin{align*}
A_{n} & \leq \int_{\mathbb{R}^{3}}\left(-C_{v} e^{-\gamma|x|}\right) w_{n}^{2} d x=-C_{v} \int_{\mathbb{R}^{3}}\left(e^{-\gamma\left|x+x_{n}\right|}\right) w^{2} d x \\
& \leq-C_{v} e^{-\gamma n} \int_{\mathbb{R}^{3}}\left(e^{-\gamma|x|}\right) w^{2} d x \leq-C e^{-\gamma n} . \tag{2.8}
\end{align*}
$$

Since $\theta<\frac{p \sqrt{V_{\infty}}}{\alpha}$, we pick $\delta \in\left(\frac{\alpha \theta}{p}, \sqrt{V_{\infty}}\right)$ satisfying that $\theta<\frac{p \delta}{\alpha}$, then together with (h), $n-|x| \leq\left|x+x_{n}\right|$ we have

$$
\begin{align*}
D_{n} & \leq \int_{\mathbb{R}^{3}}\left(C_{h} e^{-\theta|x|}\right) w_{n}^{p} d x=C_{h} \int_{\mathbb{R}^{3}}\left(e^{-\theta\left|x+x_{n}\right|}\right) w^{p} d x \\
& \leq C_{h} e^{-\theta n} \int_{\mathbb{R}^{3}} e^{\left(\theta-\frac{p \delta}{\alpha}\right)|x|} d x \leq C e^{-\theta n} . \tag{2.9}
\end{align*}
$$

On the other hand let $g\left(t_{n}\right)=I_{\infty}\left(t_{n} w\right)$, where $\left\{t_{n}\right\}$ is bounded. Note that $g\left(t_{n}\right)$ has a unique critical point corresponding to its maximum. Since $g^{\prime}(1)=0$, this
critical point must be achieved at $t_{n}=1$, thus $\max _{t_{n} \geq 0} g\left(t_{n}\right)=\max _{t_{n} \geq 0} I_{\infty}\left(t_{n} w\right)=I_{\infty}(w)$.
From Lemma 2.1, we have

$$
\begin{equation*}
I_{\infty}\left(t_{n} w_{n}\right)=I_{\infty}\left(t_{n} w\right) \leq I_{\infty}(w)=m_{\infty} \tag{2.10}
\end{equation*}
$$

As a consequence, by (2.7)-(2.10),

$$
\begin{aligned}
m & \leq m_{\infty}-\frac{C t_{n}^{2}}{2} e^{-\gamma n}+\frac{C t_{n}^{p}}{p} e^{-\theta n} \\
& =m_{\infty}+e^{-\gamma n}\left(-\frac{C t_{n}^{2}}{2}+\frac{C t_{n}^{p}}{p} e^{(\gamma-\theta) n}\right)
\end{aligned}
$$

Recalling that $t_{n} \rightarrow t_{0}$ and $\gamma<\theta$, one can easily check that $m<m_{\infty}+o_{n}(1)$. Thus there exists $n_{0}>0$, when $n \geq n_{0}$, we have $m<m_{\infty}$.

Proof of Theorem 1.1. The Ekeland Variational Principle provides $\left\{u_{n}\right\} \subset$ $\mathcal{N}$ and $\left\{\lambda_{n}\right\} \subset \mathbb{R}$ such that $I\left(u_{n}\right) \rightarrow m, I^{\prime}\left(u_{n}\right)+\lambda_{n} J^{\prime}\left(u_{n}\right) \rightarrow 0$ with $J\left(u_{n}\right)=$ $\left\langle I^{\prime}\left(u_{n}\right), u_{n}\right\rangle$. Using (2.4), a standard argument shows that $I^{\prime}\left(u_{n}\right) \rightarrow 0$, thus $\left\{u_{n}\right\}$ is a Palais-Smale sequence of $I$. Moreover it follows from (2.5) that $\left\{u_{n}\right\}$ is bounded. Hence, along a subsequence still denoted by $\left\{u_{n}\right\}, u_{n} \rightharpoonup u_{0}$ in $X$. One can easily deduce that $I^{\prime}\left(u_{0}\right)=0$.

We claim that $u_{0} \neq 0$. Suppose for the contradiction that $u_{0} \equiv 0$, thus $u_{n} \rightharpoonup 0$ in $X$ and $u_{n} \rightarrow 0$ in $L_{l o c}^{q}\left(\mathbb{R}^{N}\right)$ for any $q \in\left[2,2_{s}^{*}\right)$, then $\left\|u_{n}\right\|_{\infty}^{2}=\left\|u_{n}\right\|^{2}+o_{n}(1)$. Since $\left\langle I^{\prime}\left(u_{n}\right), u_{n}\right\rangle=0$, by (2.9) one has

$$
\begin{equation*}
\left\|u_{n}\right\|_{\infty}^{2}+b\left(\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u_{n}\right|^{2} d x\right)^{2}=\int_{\mathbb{R}^{3}} h_{\infty}\left|u_{n}\right|^{p} d x+\int_{\mathbb{R}^{3}}\left|u_{n}\right|^{2_{s}^{*}} d x+o_{n}(1) . \tag{2.11}
\end{equation*}
$$

Similar to Lemma 2.2, there exists $t_{n}>0$ such that $t_{n} u_{n} \in \mathcal{N}_{\infty}$, namely

$$
t_{n}^{2}\left\|u_{n}\right\|_{\infty}^{2}+b t_{n}^{4}\left(\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u_{n}\right|^{2} d x\right)^{2}=t_{n}^{p} \int_{\mathbb{R}^{3}} h_{\infty}\left|u_{n}\right|^{p} d x+t_{n}^{2_{s}^{*}} \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{2_{s}^{*}} d x .(2.12)
$$

From (2.11)-(2.12), we have
$\left(t_{n}^{2}-t_{n}^{p}\right)\left\|u_{n}\right\|_{\infty}^{2}+b\left(t_{n}^{4}-t_{n}^{p}\right)\left(\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u_{n}\right|^{2} d x\right)^{2}+\left(t_{n}^{p}-t_{n}^{2_{s}^{*}}\right) \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{2_{s}^{*}} d x=o_{n}(1)$,
one can easily check that $t_{n} \rightarrow 1$ as $n \rightarrow+\infty$, it follows that

$$
\begin{aligned}
I_{\infty}\left(t_{n} u_{n}\right)= & I_{\infty}\left(t_{n} u_{n}\right)-\frac{1}{p}\left\langle I_{\infty}^{\prime}\left(t_{n} u_{n}\right), t_{n} u_{n}\right\rangle \\
= & \left(\frac{1}{2}-\frac{1}{p}\right) t_{n}^{2}\left\|u_{n}\right\|_{\infty}^{2}+\left(\frac{1}{4}-\frac{1}{p}\right) b t_{n}^{p}\left(\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u_{n}\right|^{2} d x+\right)^{2} \\
& +\left(\frac{1}{p}-\frac{1}{2_{s}^{*}}\right) t_{n}^{2_{s}^{*}} \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{2_{s}^{*}} d x \\
= & \left(\frac{1}{2}-\frac{1}{p}\right)\left\|u_{n}\right\|^{2}+\left(\frac{1}{4}-\frac{1}{p}\right) b\left(\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u_{n}\right|^{2} d x\right)^{2} \\
& +\left(\frac{1}{p}-\frac{1}{2_{s}^{*}}\right) \int_{\mathbb{R}^{3}}\left|u_{n}\right|^{2_{s}^{*}} d x+o_{n}(1)
\end{aligned}
$$

$$
\begin{aligned}
& =I\left(u_{n}\right)-\frac{1}{p}\left\langle I^{\prime}\left(u_{n}\right), u_{n}\right\rangle+o_{n}(1) \\
& =I\left(u_{n}\right)+o_{n}(1)
\end{aligned}
$$

On the other hand, by $t_{n} u_{n} \in \mathcal{N}_{\infty}$, we have $m_{\infty} \leq I_{\infty}\left(t_{n} u_{n}\right)$, so

$$
m_{\infty} \leq I_{\infty}\left(t_{n} u_{n}\right)=I\left(u_{n}\right)+o_{n}(1)=m+o_{n}(1)
$$

which contradicts Lemma 2.3, thus $u_{0} \neq 0$. What's more

$$
\begin{aligned}
m & \leq I\left(u_{0}\right)-\frac{1}{p}\left\langle I^{\prime}\left(u_{0}\right), u_{0}\right\rangle \\
& =\left(\frac{1}{2}-\frac{1}{p}\right)\left\|u_{0}\right\|^{2}+\left(\frac{1}{4}-\frac{1}{p}\right) b\left(\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u_{0}\right|^{2} d x\right)^{2}+\left(\frac{1}{p}-\frac{1}{2_{s}^{*}}\right) \int_{\mathbb{R}^{3}}\left|u_{0}\right|^{2_{s}^{*}} d x \\
& \leq \liminf _{n \rightarrow \infty}\left(I\left(u_{n}\right)-\frac{1}{p}\left\langle I^{\prime}\left(u_{n}\right), u_{n}\right\rangle\right)=m,
\end{aligned}
$$

obviously $I\left(u_{0}\right)=m$, which shows $u_{0}$ is a ground state solution.
Considering $\widetilde{u}=\left|u_{0}\right|$, we can easily conclude that $I(\widetilde{u})=I\left(u_{0}\right)=m$ and $\widetilde{u} \in \mathcal{N}$. Hence $I^{\prime}(\widetilde{u})=\lambda J^{\prime}(\widetilde{u})$ for some $\lambda \in \mathbb{R}$, where $J(\widetilde{u})=\left\langle I^{\prime}(\widetilde{u}), \widetilde{u}\right\rangle$. By (2.4), we have $\left\langle J^{\prime}(\widetilde{u}), \widetilde{u}\right\rangle<0$ and $\left\langle I^{\prime}(\widetilde{u}), \widetilde{u}\right\rangle=0$, it follows that $\lambda=0$. Thus $\widetilde{u} \geq 0$ is a nonnegative ground state solution of problem (1.1). By the strong maximum principle we see that $\widetilde{u}$ is a positive solution of problem (1.1).
Remark 2.1. If $\widetilde{u}$ is the positive solution given by Theorem 1.1, as in the proof of Lemma 2.1, we can verify that, for any $\mu>0$, there exists $C=C(\mu)>0$, such that $\widetilde{u}(x) \leq C e^{-\mu|x|}, \quad \forall x \in \mathbb{R}^{3}$.

## 3. Sign-changing solution

In this section, we consider the existence of sign-changing solutions for problem (1.1). Define the functional $f\left(u^{+}\right), f\left(u^{-}\right)$on $X$ by
$f\left(u^{+}\right)=\frac{\int_{\mathbb{R}^{3}} h(x)\left|u^{+}\right|^{p} \mathrm{~d} x+\int_{\mathbb{R}^{3}}\left|u^{+}\right|^{2_{s}^{*}} \mathrm{~d} x}{\left\|u^{+}\right\|^{2}+b \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u\right|^{2} \mathrm{~d} x \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u^{+}\right|^{2} \mathrm{~d} x}, \quad$ where $u^{+}:=\max \{u, 0\}$,
$f\left(u^{-}\right)=\frac{\int_{\mathbb{R}^{3}} h(x)\left|u^{-}\right|^{p} \mathrm{~d} x+\int_{\mathbb{R}^{3}}\left|u^{-}\right|^{2_{s}^{*}} \mathrm{~d} x}{\left\|u^{-}\right\|^{2}+b \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u\right|^{2} \mathrm{~d} x \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u^{-}\right|^{2} \mathrm{~d} x}, \quad$ where $u^{-}:=\min \{u, 0\}$.
Then we define

$$
\begin{aligned}
& \mathcal{N}^{*}=\left\{u \in X \backslash\{0\}: f\left(u^{+}\right)=f\left(u^{-}\right)=1\right\} \\
& U=\left\{u \in X \backslash\{0\}:\left|f\left(u^{ \pm}\right)-1\right|<\frac{1}{2}\right\}
\end{aligned}
$$

Lemma 3.1 (Miranda Theorem [14]). Let $G=\left\{x \in \mathbb{R}^{n}:\left|x_{i}\right|<L\right.$, for $1 \leq i \leq$ $n\}$ and suppose that the mapping $F=\left(f_{1}, f_{2}, \ldots, f_{n}\right): \bar{G} \rightarrow \mathbb{R}^{n}$ is continuous on the closure $\bar{G}$ of $G$ such that $F(x) \neq \theta=(0,0, \ldots, 0)$ for $x$ on the boundary $\partial G$ of $G$, and
(i) $f_{i}\left(x_{1}, x_{2}, \ldots, x_{i-1},-L, x_{i+1}, \ldots, x_{n}\right) \geq 0 \quad$ for $1 \leq i \leq n$;
(ii) $f_{i}\left(x_{1}, x_{2}, \ldots, x_{i-1},+L, x_{i+1}, \ldots, x_{n}\right) \leq 0 \quad$ for $1 \leq i \leq n$.

Then $F(x)=\theta$ has a solution in $G$.
Lemma 3.2. For $u \in U$, there exists $C>0$, such that $\int_{\mathbb{R}^{3}}\left|u^{ \pm}\right|^{2_{s}^{*}} \mathrm{~d} x \geq C>0$.
Proof. For $u \in U$, we have

$$
\begin{aligned}
\frac{1}{2}\left\|u^{ \pm}\right\|^{2} & \leq \frac{1}{2}\left\|u^{ \pm}\right\|^{2}+\frac{1}{2} b\left(\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u^{ \pm}\right|^{2} d x\right)^{2} \\
& <\int_{\mathbb{R}^{3}} h(x)\left|u^{ \pm}\right|^{p} d x+\int_{\mathbb{R}^{3}}\left|u^{ \pm}\right|^{2_{s}^{*}} d x
\end{aligned}
$$

Then similar to (2.2)-(2.3), we can derive that there exists $C>0$, such that $\int_{\mathbb{R}^{3}}\left|u^{ \pm}\right|^{2_{s}^{*}} \mathrm{~d} x \geq C>0, \quad \forall u \in U$.
Lemma 3.3. Let $u \in \mathcal{N}^{*}$ and define $h_{u}(t, s):=I\left(t u^{+}+s u^{-}\right)$, where $t, s \geq 0$, then $h_{u}$ attains its maximum at the point $(1,1) \in \mathbb{R}^{2}$.

Proof. For $u \in \mathcal{N}^{*}$, we have

$$
\begin{aligned}
h_{u}(t, s)= & \frac{1}{2}\left\|t u^{+}+s u^{-}\right\|^{2}+\frac{b}{4}\left(\int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}}\left(t u^{+}+s u^{-}\right)\right|^{2} \mathrm{~d} x\right)^{2} \\
& -\frac{1}{p} \int_{\mathbb{R} 3} h(x)\left|t u^{+}+s u^{-}\right|^{p} \mathrm{~d} x-\frac{1}{2_{s}^{*}} \int_{\mathbb{R} 3}\left|t u^{+}+s u^{-}\right|^{2_{s}^{*}} \mathrm{~d} x
\end{aligned}
$$

because $\lim _{(t, s) \rightarrow+\infty} h_{u}(t, s)=-\infty$, it follows that the maximum is attained at some point $\left(t_{0}, s_{0}\right) \in[0,+\infty)^{2}$.
Claim 1. $s_{0}, t_{0}>0$.
By contradiction, we assume that $s_{0}=0$. However, since $h_{u}(0,0)=0$ and $h_{u}(t, s)$ reaches its maximum at the point $\left(t_{0}, s_{0}\right)$, we have $t_{0}>0$. Furthermore, one can conclude that $I\left(s u^{-}\right)>0$ for $s>0$ small, thus

$$
\begin{aligned}
h_{\mathrm{u}}\left(t_{0}, 0\right) & =I\left(t_{0} u^{+}\right) \\
& <I\left(t_{0} u^{+}\right)+I\left(s u^{-}\right)+b t_{0}^{2} s^{2} \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u^{+}\right|^{2} \mathrm{~d} x \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u^{-}\right|^{2} \mathrm{~d} x \\
& =h_{\mathrm{u}}\left(t_{0}, s\right),
\end{aligned}
$$

but $h_{u}(t, s)$ reaches its maximum at point $\left(t_{0}, s_{0}\right)$, it follows that $s_{0}>0$. A similar argument shows that $t_{0}>0$.
Claim 2. $s_{0}, t_{0} \in(0,1]$.
Since the case $s_{0} \leq 1$ is analogous to $t_{0} \leq 1$, without loss of generality, we just need to prove that $t_{0} \leq 1$. Recalling that $I\left(t u^{+}+s u^{-}\right)$reaches its maximum at the point $\left(t_{0}, s_{0}\right)$, thus we have $\left\langle I^{\prime}\left(t_{0} u^{+}+s_{0} u^{-}\right), t_{0} u^{+}\right\rangle=0$. Suppose that $s_{0} \leq t_{0}$, then

$$
\begin{aligned}
& t_{0}^{2}\left\|u^{+}\right\|^{2}+b t_{0}^{4} \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u\right|^{2} \mathrm{~d} x \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u^{+}\right|^{2} \mathrm{~d} x \\
\geq & t_{0}^{2}\left\|u^{+}\right\|^{2}+b t_{0}^{4}\left(\int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u^{+}\right|^{2} \mathrm{~d} x\right)^{2} \\
& +b t_{0}^{2} s_{0}^{2} \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u^{-}\right|^{2} \mathrm{~d} x \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u^{+}\right|^{2} \mathrm{~d} x
\end{aligned}
$$

$$
\begin{equation*}
=t_{0}^{p} \int_{\mathbb{R} 3} h(x)\left|u^{+}\right|^{p} \mathrm{~d} x+t_{0}^{2_{s}^{*}} \int_{\mathbb{R} 3}\left|u^{+}\right|^{2_{s}^{*}} \mathrm{~d} x, \tag{3.1}
\end{equation*}
$$

which implies that

$$
\begin{align*}
& t_{0}^{-2}\left\|u^{+}\right\|^{2}+b \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u\right|^{2} \mathrm{~d} x \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u^{+}\right|^{2} \mathrm{~d} x \\
\geq & t_{0}^{p-4} \int_{\mathbb{R} 3} h(x)\left|u^{+}\right|^{p} \mathrm{~d} x+t_{0}^{2_{s}^{*}-4} \int_{\mathbb{R} 3}\left|u^{+}\right|^{2_{s}^{*}} \mathrm{~d} x . \tag{3.2}
\end{align*}
$$

Furthermore, for $u \in \mathcal{N}^{*}$, we have

$$
\begin{equation*}
\left\|u^{+}\right\|^{2}+b \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u\right|^{2} \mathrm{~d} x \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} u^{+}\right|^{2} \mathrm{~d} x=\int_{\mathbb{R} 3} h(x)\left|u^{+}\right|^{p} \mathrm{~d} x+\int_{\mathbb{R}_{3}}\left|u^{+}\right|^{2_{s}^{*}} \mathrm{~d} x . \tag{3.3}
\end{equation*}
$$

By (3.2)-(3.3), we get

$$
\begin{equation*}
\left(t_{0}^{-2}-1\right)\left\|u^{+}\right\|^{2} \geq\left(t_{0}^{p-4}-1\right) \int_{\mathbb{R} 3} h(x)\left|u^{+}\right|^{p} \mathrm{~d} x+\left(t_{0}^{2_{s}^{*}-4}-1\right) \int_{\mathbb{R} 3}\left|u^{+}\right|^{2_{s}^{*}} \mathrm{~d} x \tag{3.4}
\end{equation*}
$$

thus $t_{0} \leq 1$. Otherwise if $t_{0}>1$, we must have $\left\|u^{+}\right\|^{2} \geq \int_{\mathbb{R} 3} h(x)\left|u^{+}\right|^{p} \mathrm{~d} x+$ $\int_{\mathbb{R} 3}\left|u^{+}\right|^{2_{s}^{*}} \mathrm{~d} x$, which contradicts with (3.3).

For the case $t_{0} \leq s_{0}$, it is sufficient to use $\left\langle I^{\prime}\left(t_{0} u^{+}+s_{0} u^{-}\right), s_{0} u^{-}\right\rangle=0$, and similar to the above discussion, we have $s_{0} \leq 1$.
Claim 3. $h_{u}$ does not attain its maximum in $(0,1]^{2} \backslash\{(1,1)\}$.
If $s_{0}<1$ or $t_{0}<1$, we have

$$
\begin{aligned}
h_{u}\left(t_{0}, s_{0}\right)= & I\left(t_{0} u^{+}+s_{0} u^{-}\right)-\frac{1}{p}\left\langle I^{\prime}\left(t_{0} u^{+}+s_{0} u^{-}\right),\left(t_{0} u^{+}+s_{0} u^{-}\right)\right\rangle \\
= & \left(\frac{1}{2}-\frac{1}{p}\right)\left(t_{0}^{2}\left\|u^{+}\right\|^{2}+s_{0}^{2}\left\|u^{-}\right\|^{2}\right) \\
& +\left(\frac{1}{4}-\frac{1}{p}\right) b\left(\int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}}\left(t_{0} u^{+}+s_{0} u^{-}\right)\right|^{2} \mathrm{~d} x\right)^{2} \\
& +\left(\frac{1}{p}-\frac{1}{2_{s}^{*}}\right) \int_{\mathbb{R}^{3}}\left|t_{0} u^{+}+s_{0} u^{-}\right|^{2_{s}^{*}} d x \\
< & h_{u}(1,1),
\end{aligned}
$$

which is absurd.
Following the idea of [3], we give some definitions. Denote $P$ the cone of nonnegative functions in $X$. Let $Q=[0,1] \times[0,1]$. Define

$$
\begin{aligned}
\Sigma:=\{ & \{\sigma \in C(Q, X) ; \sigma(t, 0)=0, \sigma(0, s) \in P, \sigma(1, s) \in-P, \\
& I(\sigma(t, 1)) \leq 0, f(\sigma(t, 1)) \geq 2, \forall t, s \in[0,1]\} .
\end{aligned}
$$

Choose $u \in X$ such that $u^{ \pm} \neq 0$. Let $\sigma(t, s)=k s(1-t) u^{+}+k s t u^{-}$, where $k>0, t, s \in[0,1]$. It is easy to check that $\sigma \in \Sigma$ for $k>0$ large enough.
Lemma 3.4. $\inf _{u \in \mathcal{N}^{*}} I(u)=\inf _{\sigma \in \Sigma} \sup _{u \in \sigma(Q)} I(u)$.

Proof. From the definition of $\Sigma$, for any $\sigma \in \Sigma, t \in[0,1]$, we have

$$
\begin{aligned}
& f\left(\sigma^{+}(t, 0)\right)+f\left(\sigma^{-}(t, 0)\right)-2=-2<0 \\
& f\left(\sigma^{+}(t, 1)\right)+f\left(\sigma^{-}(t, 1)\right)-2=f(\sigma(t, 1))-2 \geq 0
\end{aligned}
$$

On the other hand, for any $\sigma \in \Sigma, s \in[0,1]$, we have

$$
\begin{aligned}
& f\left(\sigma^{+}(0, s)\right)-f\left(\sigma^{-}(0, s)\right)=f\left(\sigma^{+}(0, s)\right) \geq 0 \\
& f\left(\sigma^{+}(1, s)\right)-f\left(\sigma^{-}(1, s)\right)=-f\left(\sigma^{-}(1, s)\right) \leq 0
\end{aligned}
$$

Then from Miranda theorem in [14], we conclude that for any $\sigma \in \Sigma$, there exists $(\bar{t}, \bar{s}) \in Q$ such that

$$
f\left(\sigma^{+}(\bar{t}, \bar{s})\right)-f\left(\sigma^{-}(\bar{t}, \bar{s})\right)=0=f\left(\sigma^{+}(\bar{t}, \bar{s})\right)+f\left(\sigma^{-}(\bar{t}, \bar{s})\right)-2
$$

thus $f\left(\sigma^{+}(\bar{t}, \bar{s})\right)=f\left(\sigma^{-}(\bar{t}, \bar{s})\right)=1$, which is $\sigma(\bar{t}, \bar{s}) \in \mathcal{N}^{*}$. So there holds

$$
\begin{equation*}
\inf _{\sigma \in \Sigma} \sup _{u \in \sigma(Q)} I(u) \geq \inf _{u \in \mathcal{N}^{*}} I(u) \tag{3.5}
\end{equation*}
$$

From Lemma 3.3, we know $I\left(t u^{+}+s u^{-}\right)$attains its maximum at the point $(t, s)=$ $(1,1)$, thus for every $u \in \mathcal{N}^{*}$, we have

$$
\begin{aligned}
I(u) & =I\left(u^{+}+u^{-}\right) \geq \sup _{\alpha, \beta \geq 0} I\left(\alpha u^{+}+\beta u^{-}\right) \\
& \geq \sup _{u \in \sigma(Q)} I(u) \geq \inf _{\sigma \in \Sigma} \sup _{u \in \sigma(Q)} I(u)
\end{aligned}
$$

which implies that

$$
\begin{equation*}
\inf _{\sigma \in \Sigma} \sup _{u \in \sigma(Q)} I(u) \leq \inf _{u \in \mathcal{N}^{*}} I(u) \tag{3.6}
\end{equation*}
$$

From (3.5)-(3.6), Lemma 3.4 holds.
Lemma 3.5. There is a sequence $\left\{u_{n}\right\} \subset U$ such that $I\left(u_{n}\right) \rightarrow c^{*}=\inf _{u \in \mathcal{N}^{*}} I(u)$ and $I^{\prime}\left(u_{n}\right) \rightarrow 0$.

Proof. Define $c^{*}=\inf _{u \in \mathcal{N}^{*}} I(u)$, consider a minimizing sequence $\left\{\bar{u}_{n}\right\} \subset \mathcal{N}^{*}$ and choose $\bar{\sigma}_{n} \in \Sigma$ such that $\bar{\sigma}_{n}(Q) \subset\left\{\alpha_{n} \bar{u}_{n}^{+}+\beta_{n} \bar{u}_{n}^{-}\right\}$where $\alpha_{n}, \beta_{n} \in[0,1]$, then by Lemma 3.4 we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \max _{u \in \bar{\sigma}_{n}(Q)} I(u)=\lim _{n \rightarrow \infty} I\left(\bar{u}_{n}\right)=c^{*} . \tag{3.7}
\end{equation*}
$$

By [3], we can derive that there exists $\left\{u_{n}\right\} \subset X$ such that

$$
\begin{equation*}
I\left(u_{n}\right) \rightarrow c^{*}, \quad I^{\prime}\left(u_{n}\right) \rightarrow 0 \quad \text { and } \quad \operatorname{dist}\left(u_{n}, \bar{\sigma}_{n}(Q)\right) \rightarrow 0 \tag{3.8}
\end{equation*}
$$

we just need to prove $\left\{u_{n}\right\} \subset U$ for $n$ large enough. By (3.7)-(3.8), there exists a sequence $\left\{v_{n}\right\}$, where $v_{n}=\alpha_{n} \bar{u}_{n}^{+}+\beta_{n} \bar{u}_{n}^{-} \in \bar{\sigma}_{n}(Q)$, such that

$$
\begin{equation*}
I\left(v_{n}\right) \rightarrow c^{*},\left\|v_{n}-u_{n}\right\| \rightarrow 0 \tag{3.9}
\end{equation*}
$$

From Lemma 3.2 , for any $\bar{u}_{n} \in \mathcal{N}^{*} \subset U, \int_{\mathbb{R}^{3}}\left|\bar{u}_{n}^{ \pm}\right|^{2_{s}^{*}} d x \geq C>0$, then by Sobolev embedding theorem, one has

$$
I\left(\bar{u}_{n}^{ \pm}\right)=I\left(\bar{u}_{n}^{ \pm}\right)-\frac{1}{p}\left\langle I^{\prime}\left(\bar{u}_{n}^{ \pm}\right), \bar{u}_{n}^{ \pm}\right\rangle \geq\left(\frac{1}{2}-\frac{1}{p}\right)\left\|\bar{u}_{n}^{ \pm}\right\|^{2} \geq\left(\frac{1}{2}-\frac{1}{p}\right) S^{2} C^{\frac{4}{2_{s}^{*}}}>0
$$

By (3.7), without loss of generality, we may assume that $I\left(\bar{u}_{n}^{+}\right) \rightarrow c_{1}^{*}>0, I\left(\bar{u}_{n}^{-}\right) \rightarrow$ $c_{2}^{*}>0$. Thanks to $\bar{u}_{n} \in \mathcal{N}^{*}$, we can easily conclude that

$$
\begin{aligned}
& I\left(\bar{u}_{n}^{+}\right) \geq I\left(\alpha_{n} \bar{u}_{n}^{+}\right)=I\left(v_{n}^{+}\right), \quad I\left(\bar{u}_{n}^{-}\right) \\
& \qquad \begin{aligned}
b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} \bar{u}_{n}^{+}\right|^{2} d x \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} \bar{u}_{n}^{-}-\right|^{2} d x & \geq I\left(v_{n}^{-}\right) \\
& =\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} \alpha_{n} \bar{u}_{n}^{+}\right|^{2} d x \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} \beta_{n} \bar{u}_{n}^{-}\right|^{2} d x \\
& \left|(-\Delta)^{\frac{s}{2}} v_{n}^{+}\right|^{2} d x \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} v_{n}^{-}\right|^{2} d x
\end{aligned}
\end{aligned}
$$

Furthermore

$$
\begin{aligned}
c^{*} & =\lim _{n \rightarrow \infty} I\left(\bar{u}_{n}\right) \\
& =\lim _{n \rightarrow \infty}\left[I\left(\bar{u}_{n}^{+}\right)+I\left(\bar{u}_{n}^{-}\right)+\frac{b}{2} \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} \bar{u}_{n}^{+}\right|^{2} d x \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} \bar{u}_{n}^{-}\right|^{2} d x\right] \\
& \geq \lim _{n \rightarrow \infty}\left[I\left(v_{n}^{+}\right)+I\left(v_{n}^{-}\right)+\frac{b}{2} \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} v_{n}^{+}\right|^{2} d x \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} v_{n}^{-}\right|^{2} d x\right] \\
& =\lim _{n \rightarrow \infty} I\left(v_{n}\right)=c^{*},
\end{aligned}
$$

so we have

$$
\begin{aligned}
& \lim _{n \rightarrow \infty} I\left(v_{n}^{+}\right)=\lim _{n \rightarrow \infty} I\left(\bar{u}_{n}^{+}\right)=c_{1}^{*}, \quad \lim _{n \rightarrow \infty} I\left(v_{n}^{-}\right)=\lim _{n \rightarrow \infty} I\left(\bar{u}_{n}^{-}\right)=c_{2}^{*}, \\
& b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} \bar{u}_{n}^{+}\right|^{2} d x \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} \bar{u}_{n}^{-}\right|^{2} d x=b \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} v_{n}^{+}\right|^{2} d x \int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} v_{n}^{-}\right|^{2} d x .
\end{aligned}
$$

By (3.9), $\left\|v_{n}^{ \pm}-u_{n}^{ \pm}\right\| \rightarrow 0$, so $\lim _{n \rightarrow \infty} I\left(u_{n}^{+}\right)=c_{1}^{*}>0$ and $\lim _{n \rightarrow \infty} I\left(u_{n}^{-}\right)=c_{2}^{*}>0$, which implies $u_{n}^{ \pm} \neq 0$. Moreover $I^{\prime}\left(u_{n}\right) \rightarrow 0$, we have $\left\langle I^{\prime}\left(u_{n}\right), u_{n}^{ \pm}\right\rangle=0$, thus $\left\{u_{n}\right\} \subset U$ for n large enough.

Lemma 3.6. Let $\left\{u_{n}\right\} \subset U$ be a sequence such that $\left\|u_{n}\right\|$ is bounded, $I\left(u_{n}\right) \rightarrow c^{*}$ and $I^{\prime}\left(u_{n}\right) \rightarrow 0$. There exists a subsequence of $\left\{u_{n}\right\}$, still denoted by $\left\{u_{n}\right\}$. We can assume that $u_{n} \rightharpoonup u$ weakly in $X$, thus $I^{\prime}(u)=0$. Set $v_{n}=u_{n}-u$, we have
(i) $c^{*} \geq I(u)+I_{\infty}\left(v_{n}\right)+o_{n}(1)$,
(ii) $\left\langle I_{\infty}^{\prime}\left(v_{n}\right), v_{n}\right\rangle \leq o_{n}(1)$.

Proof. For $v_{n}=u_{n}-u$, there hold $v_{n} \rightharpoonup 0$ weakly in $X$ and $v_{n} \rightarrow 0$ in $L_{l o c}^{p}\left(\mathbb{R}^{3}\right)$, thus $\left\|v_{n}\right\|_{\infty}^{2}=\left\|v_{n}\right\|^{2}+o_{n}(1)$, then by the Brezis-Lieb Lemma in [19], we get

$$
\begin{align*}
& \left\|v_{n}\right\|_{\infty}^{2}=\left\|v_{n}\right\|^{2}+o_{n}(1)=\left\|u_{n}\right\|^{2}-\|u\|^{2}+o_{n}(1) \\
& \int_{\mathbb{R}^{3}}\left|v_{n}\right|^{2_{s}^{*}} d x=\int_{\mathbb{R}^{3}}\left|u_{n}\right|^{2_{s}^{*}} d x-\int_{\mathbb{R}^{3}}|u|^{2_{s}^{*}} d x+o_{n}(1) \\
& \int_{\mathbb{R}^{3}} h(x)\left|v_{n}\right|^{p} \mathrm{~d} x=\int_{\mathbb{R}^{3}} h(x)\left|u_{n}\right|^{p} \mathrm{~d} x-\int_{\mathbb{R}^{3}} h(x)|u|^{p} \mathrm{~d} x+o_{n}(1) . \tag{3.10}
\end{align*}
$$

Combining ( $h$ ) with the third equality of (3.10), we have

$$
\begin{equation*}
\int_{\mathbb{R}^{3}} h_{\infty}\left|v_{n}\right|^{p} \mathrm{~d} x=\int_{\mathbb{R}^{3}} h(x)\left|u_{n}\right|^{p} \mathrm{~d} x-\int_{\mathbb{R}^{3}} h(x)|u|^{p} \mathrm{~d} x+o_{n}(1) \tag{3.11}
\end{equation*}
$$

However, let $\|u\|_{D^{s, 2}}^{2}:=\int_{\mathbb{R}^{3}}\left|(-\Delta)^{\frac{s}{2}} u\right|^{2} d x$, there holds

$$
\begin{align*}
\left\|u_{n}\right\|_{D^{s, 2}}^{4} & =\left(\|u\|_{D^{s, 2}}^{2}+\left\|v_{n}\right\|_{D^{s, 2}}^{2}+o_{n}(1)\right)^{2} \\
& \geq\|u\|_{D^{s, 2}}^{4}+\left\|v_{n}\right\|_{D^{s, 2}}^{4}+o_{n}(1) . \tag{3.12}
\end{align*}
$$

Combining (3.10)-(3.12), it's easy to see

$$
c^{*} \geq I(u)+I_{\infty}\left(v_{n}\right)+o_{n}(1) .
$$

On the other hand, from $u_{n} \rightharpoonup u$, we have $\left\langle u_{n}, u\right\rangle_{D^{s, 2}} \rightarrow\|u\|_{D^{s, 2}}^{2}$. By the BrezisLieb Lemma in [19], we get $\left\|v_{n}\right\|_{D^{s, 2}}^{2}=\left\|u_{n}\right\|_{D^{s, 2}}^{2}-\|u\|_{D^{s, 2}}^{2}+o_{n}(1)$.
Thus

$$
\begin{align*}
& \left\|v_{n}\right\|_{D^{s, 2}}^{4}-\left(\left\|u_{n}\right\|_{D^{s, 2}}^{4}-\|u\|_{D^{s, 2}}^{4}\right) \\
= & \left(\left\|u_{n}\right\|_{D^{s, 2}}^{2}+\|u\|_{D^{s, 2}}^{2}-2\left\langle u_{n}, u\right\rangle_{D^{s, 2}}\right)^{2}-\left\|u_{n}\right\|_{D^{s, 2}}^{4}+\|u\|_{D^{s, 2}}^{4} \\
= & 2\|u\|_{D^{s, 2}}^{4}-2\left\|u_{n}\right\|_{D^{s, 2}}^{2}\|u\|_{D^{s, 2}}^{2}+o_{n}(1) \\
= & 2\|u\|_{D^{s, 2}}^{4}-2\left(\left\|v_{n}\right\|_{D^{s, 2}}^{2}+\|u\|_{D^{s, 2}}^{2}\right)\|u\|_{D^{s, 2}}^{2}+o_{n}(1) \\
= & -2\left\|v_{n}\right\|_{D^{s, 2}}^{2}\|u\|_{D^{s, 2}}^{2}+o_{n}(1) \\
\leq & o_{n}(1) \tag{3.13}
\end{align*}
$$

By (3.10)-(3.11) and (3.13), there holds

$$
\left\langle I_{\infty}^{\prime}\left(v_{n}\right), v_{n}\right\rangle-\left(\left\langle I^{\prime}\left(u_{n}\right), u_{n}\right\rangle-\left\langle I^{\prime}(u), u\right\rangle\right) \leq o_{n}(1)
$$

together with $\left\langle I^{\prime}\left(u_{n}\right), u_{n}\right\rangle=0,\left\langle I^{\prime}(u), u\right\rangle=0$, we have $\left\langle I_{\infty}^{\prime}\left(v_{n}\right), v_{n}\right\rangle \leq o_{n}(1)$.
Lemma 3.7. If the sequence $\left\{u_{n}\right\} \subset U$ satisfies that $\left\|u_{n}\right\|$ is bounded, $I\left(u_{n}\right) \rightarrow$ $c^{*} \in\left(0, m+m_{\infty}\right)$ and $I^{\prime}\left(u_{n}\right) \rightarrow 0$, then $u_{n} \rightarrow u$ in $X$.

Proof. Since $\left\|u_{n}\right\|$ is bounded, there holds $u_{n} \rightharpoonup u$ in $X$ and $I^{\prime}(u)=0$. Set $v_{n}=u_{n}-u$, from Lemma 3.6, we have

$$
\begin{align*}
& c^{*} \geq I(u)+I_{\infty}\left(v_{n}\right)+o_{n}(1),  \tag{3.14}\\
& \left\langle I_{\infty}^{\prime}\left(v_{n}\right), v_{n}\right\rangle \leq o_{n}(1) \tag{3.15}
\end{align*}
$$

If $v_{n} \rightarrow 0$ strongly in $X$, then Lemma 3.7 holds. Now we consider $v_{n}$ converges weakly (and not strongly) to 0 in $X$. Then either $v_{n}^{+}$converges weakly (and not strongly) to 0 in $X$, or $v_{n}^{-}$converges weakly (and not strongly) to 0 in $X$. We will consider three cases as follows.
Case 1. $v_{n}^{+}$converges weakly (and not strongly) to 0 in $X, v_{n}^{-} \rightarrow 0$ strongly in $X$.
We claim that $u_{n} \rightharpoonup u \neq 0$ weakly in $X$. By contradiction, if $u=0$, then $u_{n}^{-}=$ $v_{n}^{-} \rightarrow 0$ strongly in $X$, from Lemma 3.2 , it's a contradiction with $\int_{\mathbb{R}^{3}}\left|u_{n}^{-}\right|^{2_{s}^{*}} \mathrm{~d} x \geq$ $C>0$. So $u_{n} \rightharpoonup u \neq 0$ weakly in $X$.

Note that $v_{n}^{+} \rightharpoonup 0$, there holds $\left\|v_{\mathrm{n}}^{+}\right\|_{\infty}^{2}=\left\|v_{\mathrm{n}}^{+}\right\|^{2}+o_{n}(1)$, then by (3.15), we have

$$
\begin{equation*}
\left\|v_{\mathrm{n}}^{+}\right\|^{2}+b\left(\int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} v_{\mathrm{n}}^{+}\right|^{2} \mathrm{~d} x\right)^{2} \leq \int_{\mathbb{R}^{3}} h_{\infty}\left|v_{n}^{+}\right|^{p} \mathrm{~d} x+\int_{\mathbb{R}^{3}}\left|v_{n}^{+}\right|^{2_{s}^{*}} \mathrm{~d} x+o_{n}(1) \tag{3.16}
\end{equation*}
$$

Similar to Lemma 2.2, there exists $t_{n} \in(0,+\infty)$ such that $t_{n} v_{n}^{+} \in \mathcal{N}_{\infty}$, namely

$$
\begin{equation*}
t_{n}^{2}\left\|v_{\mathrm{n}}^{+}\right\|^{2}+b t_{n}^{4}\left(\int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} v_{\mathrm{n}}^{+}\right|^{2} \mathrm{~d} x\right)^{2}=t_{n}^{p} \int_{\mathbb{R}^{3}} h_{\infty}\left|v_{n}^{+}\right|^{p} \mathrm{~d} x+t_{n}^{2_{s}^{*}} \int_{\mathbb{R}^{3}}\left|v_{n}^{+}\right|^{2_{s}^{*}} \mathrm{~d} x \tag{3.17}
\end{equation*}
$$

By (3.16)-(3.17), one has

$$
\begin{align*}
& \left(t_{n}^{2}-1\right) b\left(\int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} v_{\mathrm{n}}^{+}\right|^{2} \mathrm{~d} x\right)^{2} \\
\geq & \left(t_{n}^{p-2}-1\right) \int_{\mathbb{R}^{3}} h_{\infty}\left|v_{n}^{+}\right|^{p} \mathrm{~d} x+\left(t_{n}^{2_{s}^{*}-2}-1\right) \int_{\mathbb{R}^{3}}\left|v_{n}^{+}\right|^{2_{s}^{*}} \mathrm{~d} x \tag{3.18}
\end{align*}
$$

Since $v_{n}^{+}$converges weakly (and not strongly) to 0 in $L^{p}\left(\mathbb{R}^{3}\right)$, and by $(h)$ we can derive that $\lim _{n \rightarrow \infty} \int_{\mathbb{R}^{3}} h_{\infty}\left|v_{n}^{+}\right|^{p} \mathrm{~d} x>0$. Then from (3.17), it's easy to get

$$
\begin{equation*}
t_{n}^{2}\left\|v_{\mathrm{n}}^{+}\right\|^{2}+b t_{n}^{4}\left(\int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} v_{\mathrm{n}}^{+}\right|^{2} \mathrm{~d} x\right)^{2} \geq t_{n}^{2_{s}^{*}} \int_{\mathbb{R}^{3}}\left|v_{n}^{+}\right|^{2_{s}^{*}} \mathrm{~d} x \tag{3.19}
\end{equation*}
$$

Combining (3.16) with $(h)$, we know for any $\varepsilon>0$, there exists $C(\varepsilon)>0$ such that

$$
\begin{align*}
\left\|v_{\mathrm{n}}^{+}\right\|^{2}+b\left(\int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} v_{\mathrm{n}}^{+}\right|^{2} \mathrm{~d} x\right)^{2} & \leq \int_{\mathbb{R}^{3}} h_{\infty}\left|v_{n}^{+}\right|^{p}+\int_{\mathbb{R}^{3}}\left|v_{n}^{+}\right|^{2_{s}^{*}} \mathrm{~d} x+o_{n}(1) \\
& \leq \int_{\mathbb{R}^{3}} h(x)\left|v_{n}^{+}\right|^{p}+\int_{\mathbb{R}^{3}}\left|v_{n}^{+}\right|^{2_{s}^{*}} \mathrm{~d} x+o_{n}(1) \\
& \leq \varepsilon \int_{\mathbb{R}^{3}}\left|v_{n}^{+}\right|^{2}+C(\varepsilon) \int_{\mathbb{R}^{3}}\left|v_{n}^{+}\right|^{2_{s}^{*}} \mathrm{~d} x+o_{n}(1) . \tag{3.20}
\end{align*}
$$

In view of (3.19)-(3.20), one can derive that $\left\{t_{n}\right\}$ is bounded. Otherwise if $\left\{t_{n}\right\}$ is unbounded, from (3.19), we must have $\left\|v_{\mathrm{n}}^{+}\right\|^{2}+b\left(\int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} v_{\mathrm{n}}^{+}\right|^{2} \mathrm{~d} x\right)^{2}>\int_{\mathbb{R}^{3}}\left|v_{n}^{+}\right|^{2_{s}^{*}} \mathrm{~d} x$, which contradicts with (3.20). So there exists $t_{1} \geq 0$, such that $t_{n} \rightarrow t_{1}$ as $n \rightarrow \infty$. If $t_{1}>1$, by (3.18) there holds

$$
\lim _{n \rightarrow \infty} b\left(\int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} v_{\mathrm{n}}^{+}\right|^{2} \mathrm{~d} x\right)^{2}>\lim _{n \rightarrow \infty} \int_{\mathbb{R}^{3}} h_{\infty}\left|v_{n}^{+}\right|^{p} \mathrm{~d} x+\lim _{n \rightarrow \infty} \int_{\mathbb{R}^{3}}\left|v_{n}^{+}\right|^{2_{s}^{*}} \mathrm{~d} x
$$

which contradicts with (3.16), so $t_{n} \rightarrow t_{1} \leq 1$. On the other hand, let $s \in(0,+\infty)$, it's easy to see $I_{\infty}\left(s v_{n}^{+}\right)>0$ for $s>0$ small, $I_{\infty}\left(s v_{n}^{+}\right)<0$ for s large. Thus $I_{\infty}\left(s v_{n}^{+}\right)$ achieves its maximum at some $s>0$. Since $\left\langle I_{\infty}^{\prime}\left(t_{n} v_{n}^{+}\right), t_{n} v_{n}^{+}\right\rangle=0$, we know the maximum must be achieved at $s=t_{n}$, which implies $\max _{s \in(0,+\infty)} I_{\infty}\left(s v_{n}^{+}\right)=I_{\infty}\left(t_{n} v_{n}^{+}\right)$. Moveover

$$
\begin{aligned}
I_{\infty}\left(t_{n} v_{n}^{+}\right)= & I_{\infty}\left(t_{n} v_{n}^{+}\right)-\frac{1}{p}\left\langle I_{\infty}^{\prime}\left(t_{n} v_{n}^{+}\right),\left(t_{n} v_{n}^{+}\right)\right\rangle \\
= & \left(\frac{t_{n}^{2}}{2}-\frac{t_{n}^{p}}{p}\right)\left\|v_{\mathrm{n}}^{+}\right\|^{2}+b\left(\frac{t_{n}^{4}}{4}-\frac{t_{n}^{p}}{p}\right)\left(\int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} v_{\mathrm{n}}^{+}\right|^{2} \mathrm{~d} x\right)^{2} \\
& +\left(\frac{t_{n}^{2_{s}^{*}}}{2_{s}^{*}}-\frac{t_{n}^{p}}{p}\right) \int_{\mathbb{R}^{3}}\left|v_{n}^{+}\right|^{2_{s}^{*}} \mathrm{~d} x
\end{aligned}
$$

by $t_{n} \in(0,1]$, we can easily get $\max _{t_{n} \in(0,1]} I_{\infty}\left(t_{n} v_{n}^{+}\right)=I_{\infty}\left(v_{n}^{+}\right)$. Thus by (3.14) one has

$$
\begin{aligned}
c^{*} & \geq I(u)+I_{\infty}\left(v_{n}^{+}\right)+o_{n}(1) \\
& \geq I(u)+I_{\infty}\left(t_{n} v_{n}^{+}\right)+o_{n}(1) \\
& \geq m+m_{\infty}+o_{n}(1)
\end{aligned}
$$

which is a contradiction to $c^{*}<m+m_{\infty}$.
Case 2. $v_{n}^{-}$converges weakly (and not strongly) to 0 in $X, v_{n}^{+} \rightarrow 0$ strongly in $X$.
The proof is similar to Case 1.
Case 3. $v_{n}^{+}$converges weakly (and not strongly) to 0 in $X, v_{n}^{-}$converges weakly (and not strongly) to 0 in $X$.

Similar to the proof of Case 1, we can derive that there exists $t_{n}^{+}, s_{n}^{-} \in(0,+\infty)$ such that $t_{n}^{+} v_{n}^{+}, s_{n}^{-} v_{n}^{-} \in \mathcal{N}_{\infty}$ and $t_{n}^{+} \rightarrow t^{+} \leq 1, s_{n}^{-} \rightarrow s^{-} \leq 1$. Then by (3.14) and $m<m_{\infty}$ in Lemma 2.3, we have

$$
\begin{aligned}
c^{*} & >I_{\infty}\left(v_{n}\right)+o_{n}(1) \\
& >I_{\infty}\left(v_{n}^{+}\right)+I_{\infty}\left(v_{n}^{-}\right)+o_{n}(1) \\
& \geq I_{\infty}\left(t_{n}^{+} v_{n}^{+}\right)+I_{\infty}\left(s_{n}^{-} v_{n}^{-}\right)+o_{n}(1) \\
& \geq 2 m_{\infty}+o_{n}(1) \\
& >m+m_{\infty}+o_{n}(1),
\end{aligned}
$$

which is a contradiction to $c^{*}<m+m_{\infty}$.
Proof of Theorem 1.2. From Lemma 3.5, there is a sequence $\left\{u_{n}\right\} \subset U$ such that $I\left(u_{n}\right) \rightarrow c^{*}=\inf _{u \in \mathcal{N}^{*}} I(u)$ and $I^{\prime}\left(u_{n}\right) \rightarrow 0$. Then similar to (2.5), we can get $\left\|u_{n}\right\|$ is bounded. From Lemma 3.2, for $\left\{u_{n}\right\} \subset U$, we have $\int_{\mathbb{R}^{3}}\left|u_{n}^{ \pm}\right|^{2_{s}^{*}} \mathrm{~d} x \geq C>0$. Thus if $u_{n} \rightarrow u$ in $X$, then $I^{\prime}(u)=0, \int_{\mathbb{R}^{3}}\left|u^{ \pm}\right|^{2_{s}^{*}} \mathrm{~d} x \geq C>0$, which implies that $u$ is a sign-changing solution of (1.1). Now we prove $u_{n} \rightarrow u$ in $X$. From Lemma 3.7, we only need to prove that $c^{*}<m+m_{\infty}$.

Let $\widetilde{u}$ be the positive solution given by Theorem 1.1, and $w_{n}$ was defined in Lemma 2.2. For any $n \in \mathbb{N}, x \in \mathbb{R}^{3}$ and $(t, s) \in\left[\frac{1}{2}, 2\right]^{2}$, we define $\psi_{n}(x):=t \widetilde{u}(x)+$ $s w_{n}(x)$. We claim that there exists $n_{0} \in \mathbb{N}$, such that for any $n \geq n_{0}$ and $(t, s) \in$ $\left[\frac{1}{2}, 2\right]^{2}, I\left(\psi_{n}\right)<m+m_{\infty}$.

$$
\begin{equation*}
I\left(t \widetilde{u}+s w_{n}\right)=I(t \widetilde{u})+I_{\infty}\left(s w_{n}\right)+A_{n}+B_{n}+C_{n}+D_{n}+E_{n}+F_{n} . \tag{3.21}
\end{equation*}
$$

From Lemma 2.3, we have

$$
\begin{aligned}
& A_{n}=\frac{1}{2} s^{2} \int_{\mathbb{R}^{3}}\left(V(x)-V_{\infty}\right) w_{n}^{2} d x \leq-C_{1} e^{-\gamma n} \\
& D_{n}=\frac{1}{p} s^{p} \int_{\mathbb{R}^{3}}\left(h_{\infty}-h(x)\right) w_{n}^{p} d x \leq C_{2} e^{-\theta n}
\end{aligned}
$$

From Lemma 2.1 and Remark 2.1, there hold $\widetilde{u}(x) \leq C e^{-\mu x}, w(x) \leq C e^{-\frac{\delta}{\alpha} x}$. Since $\gamma<\frac{\sqrt{V_{\infty}}}{\alpha}$, let $\mu \in\left(\gamma, \frac{\sqrt{V_{\infty}}}{\alpha}\right)$, similar to (2.8)-(2.9) we can get

$$
E_{n}=-\frac{1}{p} \int_{\mathbb{R}^{3}} h(x)\left(\left|\psi_{n}\right|^{p}-|t \widetilde{u}|^{p}-\left|s w_{n}\right|^{p}\right) d x \leq-C_{3} e^{-\mu n}
$$

$$
F_{n}=-\frac{1}{2_{s}^{*}} \int_{\mathbb{R}^{3}}\left(\left|\psi_{n}\right|^{2_{s}^{*}}-|t \widetilde{u}|^{2_{s}^{*}}-\left|s w_{n}\right|^{2_{s}^{*}}\right) d x \leq-C_{4} e^{-\mu n}
$$

Note that $\left\langle I^{\prime}(\widetilde{u}), w_{n}\right)=0$, there holds

$$
\begin{aligned}
B_{n}= & s t \int_{\mathbb{R}^{3}} a\left|(-\triangle)^{\frac{s}{2}} \widetilde{u}\right| \mathrm{d} x \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} w_{n}\right| d x+s t \int_{\mathbb{R}^{3}} V(x) \widetilde{u} w_{n} d x \\
= & s t\left(\int_{\mathbb{R}^{3}} h(x)|\widetilde{u}|^{p-1} w_{n} d x+\int_{\mathbb{R}^{3}}|\widetilde{u}|^{2_{s}^{*}-1} w_{n} d x\right. \\
& \left.-b \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} \widetilde{u}\right|^{2} \mathrm{~d} x \cdot \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} \widetilde{u}\right| \mathrm{d} x \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} w_{n}\right|\right) \\
\leq & C_{5} e^{-\mu n} .
\end{aligned}
$$

For the convenience, let $\left\|w_{n}\right\|_{D^{s, 2}}^{2}:=\int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} w_{n}\right| d x$, by $\left\langle I_{\infty}^{\prime}\left(w_{n}\right), w_{n}\right\rangle=0$, we have
$a\left\|w_{n}\right\|_{D^{s, 2}}^{2}+b\left\|w_{n}\right\|_{D^{s, 2}}^{4}=\int_{\mathbb{R}^{3}} h_{\infty}\left|w_{n}\right|^{p} d x+\int_{\mathbb{R}^{3}}\left|w_{n}\right|^{2_{s}^{*}} d x-\int_{\mathbb{R}^{3}} V_{\infty}\left|w_{n}\right|^{2} d x<C e^{-\delta n}$,
thus $G_{n}:=\left\|w_{n}\right\|_{D^{s, 2}}^{2} \leq \frac{-a+\sqrt{a^{2}+4 C e^{-\delta n}}}{2 b} \rightarrow 0(n \rightarrow \infty)$, then

$$
\begin{aligned}
C_{n}= & \frac{b}{4}\left[4 t^{2} s^{2} \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} \widetilde{u}\right|^{2} \mathrm{~d} x \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} w_{n}\right|^{2} \mathrm{~d} x\right. \\
& +2 t^{2} s^{2}\left(\int_{\mathbb{R}^{3}}(-\triangle)^{\frac{s}{2}} \widetilde{u} \mathrm{~d} x \int_{\mathbb{R}^{3}}(-\triangle)^{\frac{s}{2}} w_{n} \mathrm{~d} x\right)^{2} \\
& +4 t^{3} s \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} \widetilde{u}\right|^{2} \mathrm{~d} x \int_{\mathbb{R}^{3}}(-\triangle)^{\frac{s}{2}} \widetilde{u} \mathrm{~d} x \int_{\mathbb{R}^{3}}(-\triangle)^{\frac{s}{2}} w_{n} \mathrm{~d} x \\
& \left.+4 t s^{3} \int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} w_{n}\right|^{2} \mathrm{~d} x \int_{\mathbb{R}^{3}}(-\triangle)^{\frac{s}{2}} \widetilde{u} \mathrm{~d} x \int_{\mathbb{R}^{3}}(-\triangle)^{\frac{s}{2}} w_{n} \mathrm{~d} x\right] \\
\leq & C_{6} G_{n}+C_{7} e^{-\mu n} .
\end{aligned}
$$

All the above inequalities can be replaced in (3.21) to provide

$$
\begin{aligned}
I\left(\psi_{n}\right) \leq & m+m_{\infty}-C_{1} e^{-r n}+C_{2} e^{-\theta n} \\
& -C_{3} e^{-\mu n}-C_{4} e^{-\mu n}+C_{5} e^{-\mu n}+C_{6} G_{n}+C_{7} e^{-\mu n}
\end{aligned}
$$

So we obtain the inequality $I\left(\psi_{n}\right) \leq m+m_{\infty}+o_{n}(1)$.
In view of the claim, to prove that $c^{*}<m+m_{\infty}$, it is sufficient to obtain $\left(t_{0}, s_{0}\right) \in\left[\frac{1}{2}, 2\right]^{2}$ such that $t_{0} \widetilde{u}(x)+s_{0} w_{n}(x) \in \mathcal{N}^{*}$. With this purpose, we define

$$
h^{ \pm}(t, s, n):=\left\langle I^{\prime}\left(t \widetilde{u}+s w_{n}\right),\left(t \widetilde{u}+s w_{n}\right)^{ \pm}\right\rangle .
$$

Since $w_{n} \rightharpoonup 0$ weakly in $X$, and $w$ is a solution of the limit problem, we can use $\left(V_{2}\right),(h)$ to conclude that

$$
\begin{aligned}
h^{-}(0,2, n) & =2^{2}\left\|w_{n}\right\|^{2}+2^{4} b\left(\int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} w_{n}\right|^{2}\right)^{2}-2^{p} \int_{\mathbb{R}^{3}} h(x) w_{n}^{p} \mathrm{~d} x-2^{2_{s}^{*}} \int_{\mathbb{R}^{3}} w_{n}^{2_{s}^{*}} \mathrm{~d} x \\
& =\left(2^{2}-2^{p}\right)\|w\|_{\infty}^{2}+b\left(2^{4}-2^{p}\right)\left(\int_{\mathbb{R}^{3}}\left|(-\triangle)^{\frac{s}{2}} w\right|^{2}\right)^{2}
\end{aligned}
$$

$$
+\left(2^{p}-2^{2_{s}^{*}}\right) \int_{\mathbb{R}^{3}} w^{2_{s}^{*}} \mathrm{~d} x+o_{n}(1)
$$

so $h^{-}(0,2, n)<0$ for n large. The same argument provides $h^{-}\left(0, \frac{1}{2}, n\right)>0$. Moreover by $\left\langle I^{\prime}(\widetilde{u}), \widetilde{u}\right\rangle=0$, we can conclude that

$$
h^{+}\left(\frac{1}{2}, 0, n\right)>0, \quad h^{+}(2,0, n)<0
$$

From Lemma 3.1(Miranda Theorem [14]), there exists $\left(t_{0}, s_{0}\right) \in\left[\frac{1}{2}, 2\right]^{2}$ such that $h^{ \pm}\left(t_{0}, s_{0}, n\right)=0$ for n large, which is equivalent to $t_{0} \widetilde{u}(x)+s_{0} w_{n}(x) \in \mathcal{N}^{*}$.

## Acknowledgements

The authors sincerely thank the editor and the referees for their many valuable comments and suggestions. This work is supported by Fundamental Research Funds for the Central Universities (XDJK2020B051).

## References

[1] A. M. Batista and M. F. Furtado, Solutions for a Schrödinger-Kirchhoff equation with indefinite potentials, Milan J. Math., 2018, 86(1), 1-14.
[2] K. Cheng and Q. Gao, Sign-changing solutions for the stationary Kirchhoff problems involving the fractional Laplacian in $\mathbb{R}^{N}$, Acta Mathematica Scientia., 2018, 38(6), 1712-1730.
[3] G. Cerami, S. Solimini and M. Struwe, Some existence results for superlinear elliptic boundary value problems involving critical exponents, J. Funct. Anal., 1986, 69(3), 289-306.
[4] S. Chen, X. Tang and F. Liao, Existence and asymptotic behavior of sign changing solutions for fractional Kirchhoff-type problems in low dimensions, NoDEA Nonlinear Differ. Equ. Appl., 2018, 25(5), 23.
[5] E. DiNezza, G. Palatucci and E. Valdinoci, Hitchhiker;s guide to the fractional Sobolev spaces, Bull. Sci. Math., 2012, 136(5), 521-573.
[6] A. Fiscella and P. Pucci, P-fractional Kirchhoff equations involving critical nonlinearities, Nonlinear Anal. Real World Appl., 2017, 35, 350-378.
[7] A. Fiscella and E. Valdinoci, A critical Kirchhoff type problem involving a nonlocal operator, Nonlinear Anal., 2014, 94, 156-170.
[8] D. Gilbarg and N. S. Trudinger, Elliptic Partial Differential Equations of Second Order, Reprint of the 1998 edition. Classics in Mathematics. SpringerVerlag, Berlin, 2001.
[9] W. Huang and X. Luo, Positive ground state solutions for fractional Kirchhoff type equations with critical growth, Math. Methods Appl., 2019, 42(3), 10181038.
[10] T. Isernia, Sign-changing solutions for a fractional Kirchhoff equation, Nolinear Anal., 2020, 190, 111623, 20.
[11] W. Long and J. Yang, Positive or sign-changing solutions for a critical semilinear nonlocal equation, Z. Angew. Math. Phys., 2016, 67(3), 30.
[12] X. Luo, X. Tang and Z. Gao, Ground state sign-changing solutions for fractional Kirchhoff equations in bounded domains, J. Math. Phys., 2018, 59(3), 15.
[13] Y. Li, D. Zhao and Q. Wang, Ground state solution and nodal solution for fractional nonlinear Schrödinger equation with indefinite potential, J. Math. Phys., 2019, 60(4), 15.
[14] C. Miranda, Un'osservazione sul teorema di Brouwer, Boll. Unione Mat. Ital., 1940, 19, 5-7.
[15] P. Pucci, M. Xiang and B. Zhang, Multiple solutions for nonhomogeneous Schrödinger-Kirchhoff type equations involving the fractional p-Laplacian in $R^{N}$, Calc. Var. Partial Differ. Eqs., 2015, 54(3), 2785-2806.
[16] S. Secchi, Ground state solutions for nonlinear fractional Schrödinger equations in $R^{N}$, J. Math. Phys., 2013, 54(3), 17.
[17] W. Shuai, Sign-changing solutions for a class of Kirchhoff-type problem in bounded domains, J. Diff. Eqs., 2015, 259(4), 1256-1274.
[18] Z. Wang and H. Zhou, Radial sign-changing solution for fractional Schrödinger equation, Discrete. Contin. Dyn. Syst., 2016, 36(1), 499-508.
[19] M. Willem, Minimax Theorems, Birkhäuser, Boston, 1996.
[20] M. Wu and F. Zhou, Nodal solutions for a Kirchhoff type problem in $\mathbb{R}^{N}$, Applied Mathematics Letters, 2019, 88, 58-63.
[21] L. Xu and H. Chen, Sign-changing solution to Schrödinger-Kirchhoff-type equations with critical exponent, Adv. Difference Equ., 2016, 121, 14.
[22] M. Xiang and F. Wang, Fractional Schrödinger-Poisson-Kirchhoff type systems involving critical nonlinearities, Nonlinear Anal., 2017, 164, 1-26.


[^0]:    ${ }^{\dagger}$ The corresponding author. Email address:ly0904@swu.edu.cn(Y. Lv)
    ${ }^{1}$ School of Mathematics and Statistics, Southwest University, Chongqing 400715, China
    *The authors were supported by Fundamental Research Funds for the Central Universities (XDJK2020B051).

