SHARP ASYMPTOTIC RESULTS FOR THIRD-ORDER LINEAR DELAY DIFFERENTIAL EQUATIONS

John R. Graef^{1,†}, Irena Jadlovská², and Ercan Tunç³

Abstract In the paper, the authors propose an effective Kneser-type oscillation test for Property A for linear third-order delay differential equations that ensures that any nonoscillatory solution converges to zero asymptotically. The result is sharp when applied to Euler-type delay differential equation and improves all existing results reported in the literature.

Keywords Third-order differential equation, delay, almost oscillation, oscillation, Property A.

MSC(2010) 34C10, 34K11.

1. Introduction

Consider the third-order linear delay differential equation

$$y'''(t) + q(t)y(\tau(t)) = 0, \quad t \ge t_0 > 0, \tag{1.1}$$

where $q(t) \in C([t_0, \infty))$ is nonnegative and does not eventually vanish identically, and the delay function $\tau(t) \in C([t_0, \infty))$ satisfies $\tau(t) \leq t$ and $\tau(t) \to \infty$ as $t \to \infty$.

By a solution of (1.1) we mean a three times differentiable real-valued function y satisfying (1.1) for all large t. We restrict our attention to those solutions of (1.1) that satisfy the condition $\sup \{|y(t)| : T \le t < \infty\} > 0$ for any large $T \ge t_0$, and we tacitly assume that equation (1.1) possesses such solutions.

As is customary, a nontrivial solution of (1.1) is termed *oscillatory* or *nonoscillatory* according to whether it does or does not have infinitely many zeros. Equation (1.1) is is called oscillatory if all its solutions are oscillatory.

The investigation of qualitative properties of (1.1) is important for applications since such equations are considered as valuable tools in the modelling of many phenomena in different areas of applied mathematics and physics (see [16]). In particular, oscillation theory of third-order differential equations with variable coefficients has attracted a great deal of attention over the last three decades as is evidenced by the extensive research in the area.

[†]The corresponding author. Email: John-Graef@utc.edu(J. R. Graef)

 $^{^{1}\}mathrm{Department}$ of Mathematics, University of Tennessee at Chattanooga, Chattanooga, TN 37403, USA

²Department of Mathematics and Theoretical Informatics, Faculty of Electrical Engineering and Informatics, Technical University of Kosice, Letna 9, 042 00 Kosice, Slovakia and Mathematical Institute, Slovak Academy of Sciences, Gresakova 6, 040 01 Kosice, Slovakia

³Department of Mathematics, Faculty of Arts and Sciences, Tokat Gaziosmanpaşa University, 60240, Tokat, Turkey

It follows from a classical result of Kiguradze [21, Lemma 1.1] that the set \mathcal{N} of all positive nonoscillatory solutions of (1.1) can be divided into the following two classes:

$$\mathcal{N}_0 = \{ y(t) : (\exists t_1 \ge t_0) (\forall t \ge t_1) (y(t) > 0, y'(t) < 0, y''(t) > 0) \}, \\ \mathcal{N}_2 = \{ y(t) : (\exists t_1 \ge t_0) (\forall t \ge t_1) (y(t) > 0, y'(t) > 0, y''(t) > 0) \}.$$

Solutions belonging to the class \mathcal{N}_0 are called Kneser solutions. It is known that in the absence of a delay in (1.1), i.e., if $\tau(t) = t$, the class \mathcal{N}_0 is always nonempty (see, e.g., [18]). Therefore, results for third-order equations have been often accomplished by introducing the concept of the so-called Property A. We say that equation (1.1) has *Property A* if any solution y of (1.1) is either oscillatory or is a Kneser type solution tending to zero as $t \to \infty$ (see [21]).

To name the situation where $\mathcal{N} = \mathcal{N}_0$, we will say equation (1.1) is *almost* oscillatory. On the other hand, if the class \mathcal{N}_2 is nonempty, we will say that (1.1) is nonoscillatory.

Comparison principles have been especially powerful tools in oscillation theory since Sturm's initial contribution to the subject. Their underlying feature is to deduce the oscillatory properties of the given equation from those of a simpler one whose oscillatory behavior is already known. Euler-type differential equations and their various generalizations often serve as suitable comparison equations. Perhaps the most familiar situation is the one for the second-order linear Euler equation

$$y''(t) + \frac{q_0}{t^2}y(t) = 0, \quad q_0 > 0, \tag{1.2}$$

which is oscillatory if and only if

$$q_0 > \max\{-x(x-1): 0 < x < 1\} = \frac{1}{4}.$$

In 1893, A. Kneser [22] was the first to use Sturmian comparison methods and equation (1.2) to show that the linear equation

$$y''(t) + q(t)y(t) = 0 (1.3)$$

is oscillatory if

$$\liminf_{t \to \infty} t^2 q(t) > \frac{1}{4}$$

and nonoscillatory if

$$\limsup_{t \to \infty} t^2 q(t) < \frac{1}{4}$$

An extension of Kneser's oscillation criterion to the third-order ordinary differential equation (which is the special case of (1.1) with $\tau(t) = t$)

$$y'''(t) + q(t)y(t) = 0 (1.4)$$

was given by M. Hanan in 1961 [17, Theorem 5.7] and essentially kindled the current interest in investigating the oscillatory and asymptotic behavior of third-order differential equations.

Using the third-order Euler equation

$$y'''(t) + \frac{q_0}{t^3}y(t) = 0, \quad q_0 > 0, \tag{1.5}$$

for comparison purposes, which is almost oscillatory if and only if

$$q_0 > \max\{-x(x-1)(x-2) : 1 < x < 2\} = \frac{2}{3\sqrt{3}}$$

Hanan showed that (1.4) is almost oscillatory if

$$\liminf_{t \to \infty} t^3 q(t) > \frac{2}{3\sqrt{3}} \tag{1.6a}$$

and nonoscillatory (in the sense that all its solutions are nonoscillatory) if

$$\limsup_{t \to \infty} t^3 q(t) < \frac{2}{3\sqrt{3}}.$$
(1.6b)

The constant $2/(3\sqrt{3})$ corresponding to 1/4 for the second-order equation (1.3) is the best possible for (1.4) in the sense that all solutions of (1.5) are nonoscillatory if $q_0 \leq 2/(3\sqrt{3})$.

A natural question that arises is how to extend Hanan's Kneser-type criterion (1.6) from the ordinary equation (1.4) to the delay equation (1.1). To test the strength of the results, we shall use the delay Euler-type equation

$$y'''(t) + \frac{q_0}{k^2 t^3} y(kt) = 0, \quad q_0 > 0, \quad k \in (0, 1].$$
(1.7)

Applying Mahfoud's comparison theorem [24, Theorem 1], we see that (1.7) is almost oscillatory if

$$q_0 > \frac{2}{3\sqrt{3}}.$$
 (1.8)

For nonoscillation, we use the trial solution $y(t) = t^x$, $x \in (1,2)$ to see that unbounded solutions $y \in \mathcal{N}_2$ of (1.7) exist if x satisfies the indicial equation

$$f(x) := -x(x-1)(x-2)k^{2-x} = q_0,$$
(1.9)

that is, if

$$q_0 \le \max\{f(x) : 1 < x < 2\} =: m_2. \tag{1.10}$$

Clearly, there is the gap $(m_2, 2/(3\sqrt{3})]$ between the almost oscillation and nonoscillation of (1.7) in case k < 1. To the best of our knowledge, this gap cannot be completely filled by any existing results for (1.1) obtained by different techniques; see the papers [1–6, 8–11, 13–15, 23, 26, 28] and the references cited therein or the recent monographs of Padhi and Pati [25] and Saker [27] for extensive bibliographies on the subject.

The purpose of the paper is to establish an efficient criterion for detecting Property A for equation (1.1) that is sharp in the sense that it gives a necessary and sufficient condition for the delay Euler equation (1.7) to be almost oscillatory (or, more precisely, to have Property A). Our motivation comes from the recent papers [12, 19, 20], where a similar technique lead to obtaining sharp oscillation results for second-order half-linear differential equations with deviating arguments. A major advantage of this technique is its potential for investigating more general nonlinear differential equations.

2. Main results

The main result in this paper is the following.

Theorem 2.1. Let

$$\lambda_* := \liminf_{t \to \infty} \frac{t}{\tau(t)}.$$

If

$$\liminf_{t \to \infty} \tau^2(t) t q(t) > \begin{cases} 0, & \text{for } \lambda_* = \infty, \\ M_2, & \text{for } \lambda_* < \infty, \end{cases}$$
(2.1)

where M_2 is defined by

$$M_2 := \max\left\{-x(x-1)(x-2)\lambda_*^{x-2} : 1 < x < 2\right\},\tag{2.2}$$

then equation (1.1) has Property A.

Note that for $\tau(t) = t$, Theorem 2.1 reduces to the oscillation part of Hanan's result [17, Theorem 5.7] (see (1.6)). Moreover, as an immediate consequence of Theorem 2.1 and the nonoscillation condition (1.10), we obtain the following sharp result for the delay Euler equation (1.7).

Corollary 2.1. The Euler equation (1.7) has Property A if and only if

$$q_0 > M_2 = m_2. (2.3)$$

Remark 2.1. The particular case $\lambda_* = \infty$ applies, for example, if the function τ is of the form $\tau(t) = t^k$, $k \in (0, 1)$. As an illustration of Theorem 2.1 in this special case, we can conclude that the equation

$$y'''(t) + \frac{q_0}{t^{1+2/k}} y\left(t^k\right) = 0, \quad q_0 > 0, \quad 0 < k < 1,$$
(2.4)

has Property A for any q_0 .

Remark 2.2. In many results for third-order delay differential equations including (1.1) as a particular case, the authors require that the delay function $\tau(t)$ is strictly increasing. This is not needed in Theorem 2.1.

Remark 2.3. In general, results in the literature consist of two independent conditions, the first one ensuring that any Kneser solution tends to zero, and the second one for the nonexistence of solutions in the class \mathcal{N}_2 . To the contrary, our Theorem 2.1 is a single-condition criterion guaranteeing the same property.

Open problem. It is known that the delay argument $\tau(t)$ can cause the oscillation of all solutions of (1.1), that is, $\mathcal{N}_0 = \mathcal{N}_2 = \emptyset$. In a recent work [7], the authors show that the delay Euler equation (1.7) is oscillatory if and only if

$$q_0 > \max\{m_0, m_2\}$$

where m_0 and m_2 are local maxima of f(x) defined by (1.9) on $(-\infty, 0)$ and (1, 2), respectively. In view of this, the open problem is to show whether

$$\liminf_{t \to \infty} \tau^2(t) t q(t) > \max\{M_0, M_2\},\$$

where $\lambda_* < \infty$ and

$$M_0 := \max \left\{ -x(x-1)(x-2)\lambda_*^{x-2} : -\infty < x < 0 \right\}.$$

is sufficient or not for the oscillation of (1.1).

2462

3. Auxiliary results and proof of the main theorem

We assume that all functional inequalities hold eventually, that is, they are satisfied for all t large enough. As usual, and without loss of generality, we can assume from now on that nonoscillatory solutions of (1.1) are eventually positive.

In the sequel, we will make use of the constants

$$\beta_* := \liminf_{t \to \infty} \frac{\tau^2(t)tq(t)}{2} \quad \text{and} \quad \lambda_* := \liminf_{t \to \infty} \frac{t}{\tau(t)}$$

The following lemmas require the positivity of β_* as does Theorem 2.1. Clearly, for any $\beta \in (0, \beta_*)$ and $\lambda \in (1, \lambda_*)$ for $\tau(t) < t$, and $\lambda = \lambda_*$ for $\tau(t) = t$, there is a $t_1 \ge t_0$ large enough such that

$$\frac{\tau^2(t)tq(t)}{2} \ge \beta \quad \text{and} \quad \frac{t}{\tau(t)} \ge \lambda, \quad t \ge t_1.$$
(3.1)

We will make use of these facts in our proofs.

Lemma 3.1. Assume that $\beta_* > 0$. If y is a solution of (1.1) belonging to \mathcal{N}_0 , then $\lim_{t\to\infty} y(t) = 0$.

Proof. Let $y(t) \in \mathcal{N}_0$ and choose $t_1 \geq t_0$ so that $y(\tau(t)) > 0$ on $[t_1, \infty)$. Clearly, there exists a finite number ℓ such that $\lim_{t\to\infty} y(t) = \ell \geq 0$. Assume that $\ell > 0$. Then there exists $t_2 \geq t_1$ such that $y(\tau(t)) \geq \ell$ for $t \geq t_2$. Using this and (3.1) in (1.1), we see that

$$-y^{\prime\prime\prime}(t) = q(t)y(\tau(t)) \geq \frac{2\beta}{\tau^2(t)t}y(\tau(t)) \geq \frac{2\beta\ell}{\tau^2(t)t} \geq \frac{2\beta\ell}{t^3}\frac{t^2}{\tau^2(t)} \geq \frac{2\beta\ell\lambda^2}{t^3}.$$

Integrating the above inequality twice from t to ∞ , we have

$$-y'(t) \ge \frac{\beta\ell\lambda^2}{t}.$$
(3.2)

Integrating (3.2) from t_2 to t, we arrive at

$$y(t_2) \ge y(t) + \beta \ell \lambda^2 \ln \frac{t}{t_2} \to \infty \text{ as } t \to \infty,$$

which contradicts the fact that y is bounded. Hence $\ell = 0$ and this proves the lemma.

In our next lemma, we prove some basic but important properties of solutions belonging to the class \mathcal{N}_2 .

Lemma 3.2. Assume that $\beta_* > 0$ and let y be a solution (1.1) belonging to \mathcal{N}_2 . Then for t sufficiently large:

- (i) $\lim_{t\to\infty} y(t) = \lim_{t\to\infty} y'(t) = \infty;$
- (ii) $\lim_{t\to\infty} y''(t) = \lim_{t\to\infty} y'(t)/t = \lim_{t\to\infty} y(t)/t^2 = 0;$
- (iii) y'(t)/t is decreasing and y'(t) > ty''(t);
- (iv) $y(t)/t^2$ is decreasing and y(t) > ty'(t)/2.

Proof. Let $y \in \mathcal{N}_2$ and choose $t_1 \ge t_0$ such that $y(\tau(t)) > 0$ for $t \ge t_1$.

(i) First, note that $\beta_* > 0$ implies

$$\int_{t_0}^{\infty} \tau^2(s)q(s)\mathrm{d}s = \infty \tag{3.3}$$

since

$$\int_{t_1}^t \tau^2(s)q(s)\mathrm{d}s \ge 2\beta \int_{t_1}^t \frac{\mathrm{d}s}{s} = 2\beta \ln \frac{t}{t_1} \to \infty \quad \text{as } t \to \infty.$$

Now y' is increasing and positive, so $y'(t) \ge y'(t_1) =: \ell$ for $t \ge t_1$. Integrating from t_1 to t, we obtain

$$y(t) \ge \ell(t - t_1). \tag{3.4}$$

Letting t to ∞ , it is obvious that $y \to \infty$. Employing (3.4) in (1.1) yields

$$-y'''(t) \ge \ell q(t)(\tau(t) - t_1)$$
(3.5)

and integrating (3.5) from t to ∞ , we obtain

$$y''(t) \ge \ell \int_t^\infty q(s)(\tau(s) - t_1) \mathrm{d}s.$$

Integrating the last inequality from t_1 to t, interchanging the order of integration, and using (3.3) in resulting inequality, we arrive at

$$y'(t) \ge \ell \int_{t_1}^t \int_u^\infty q(s)(\tau(s) - t_1) \mathrm{d}s \mathrm{d}u = \int_{t_1}^t q(s)(\tau(s) - t_1)(s - t_1) \mathrm{d}s$$
$$\ge \int_{t_1}^t q(s)(\tau(s) - t_1)^2 \mathrm{d}s \to \infty \quad \text{as} \quad t \to \infty$$

which finishes the proof of (i).

(ii) Since y'' is a positive decreasing function,

$$\lim_{t \to \infty} y''(t) = \ell \ge 0$$

If $\ell > 0$, then $y''(t) \ge \ell > 0$ and so $y(t) \ge \ell(t - t_1)^2/2$. Using this in (1.1), we have

$$y'''(t) \ge q(t)y(\tau(t)) \ge \frac{\ell}{2}q(t)(\tau(t) - t_1)^2.$$
(3.6)

Integrating from t_1 to t gives

$$y''(t) \ge \frac{\ell}{2} \int_{t_1}^t q(s)(\tau(s) - t_1)^2 \mathrm{d}s \to \infty \quad \text{as} \quad t \to \infty,$$

which is a contradiction. Hence, $\ell = 0$. Applying l'Hôspital's rule and using (i), we see that (ii) holds.

(iii) Again using the fact that y'' is positive and decreasing, it follows that

$$y'(t) = y'(t_1) + \int_{t_1}^t y''(s) \mathrm{d}s \ge y'(t_1) + y''(t)(t - t_1).$$

In view of (ii), there is a $t_2 > t_1$ such that $y'(t_1) > y''(t)t_1$ for $t \ge t_2$. Thus,

$$y'(t) > ty''(t), \quad t \ge t_2,$$

and consequently,

$$\left(\frac{y'(t)}{t}\right)' = \frac{y''(t)t - y'(t)}{t^2} < 0,$$

which proves (iii).

(iv) In view of the fact that y'(t)/t is a decreasing function tending to zero, we see that

$$y(t) = y(t_1) + \int_{t_1}^t \frac{y'(s)}{s} sds \ge y(t_1) + \frac{y'(t)}{t} \left(\frac{t^2}{2} - \frac{t_1^2}{2}\right)$$
$$= \frac{y'(t)t}{2} + y(t_1) - \frac{y'(t)t_1^2}{2t} > \frac{y'(t)t}{2}$$

for $t \ge t_3$ for some $t_3 \ge t_2$. Therefore,

$$\left(\frac{y(t)}{t^2}\right)' = \frac{y'(t)t^2 - 2ty(t)}{t^4} < 0,$$

which proves (iv) and completes the proof of the lemma.

Our next lemma provides some additional properties of solutions in the class \mathcal{N}_2 .

Lemma 3.3. Assume that $\beta_* > 0$ and $y \in \mathcal{N}_2$. Then, for any $\beta \in (0, \beta_*)$ and t sufficiently large:

- (v) $y'(t)/t^{1-\beta}$ is decreasing and $ty''(t) < (1-\beta)y'(t)$;
- (vi) $\beta < 1;$

(*vii*)
$$\lim_{t \to \infty} y'(t)/t^{1-\beta} = 0;$$

(viii) $y(t)/t^{2-\beta}$ is decreasing and $y(t) > y'(t)t/(2-\beta)$.

Proof. Let $y \in \mathcal{N}_2$ with $y(\tau(t)) > 0$ for $t \ge t_1 \ge t_0$. (v) Define the function

$$z(t) := y'(t) - ty''(t),$$

which is positive by (iii). Differentiating z, and using (1.1) and (3.1), we see that

$$z'(t) = (y' - ty'')' = -ty'''(t) = tq(t)y(\tau(t)) \ge 2\beta \frac{y(\tau(t))}{\tau^2(t)}.$$
(3.7)

Using (iv), we have

$$z'(t) \ge 2\beta \frac{y(t)}{t^2} \ge \beta \frac{y'(t)}{t}$$

for $t \ge t_2$ for some $t_2 \ge t_1$. Integrating from t_2 to t and using the fact that y'(t)/t is decreasing (see (iii)), there exists $t_3 \ge t_2$ such that

$$z(t) = z(t_2) + \beta \int_{t_2}^t \frac{y'(s)}{s} \mathrm{d}s \ge z(t_2) + \beta \frac{y'(t)}{t}(t - t_2) > \beta y'(t), \quad t \ge t_3.$$
(3.8)

That is,

$$ty''(t) < (1 - \beta)y'(t), \quad t \ge t_3.$$

Hence, for $t \geq t_3$,

$$\left(\frac{y'(t)}{t^{1-\beta}}\right)' = \frac{y''(t)t^{1-\beta} - (1-\beta)t^{-\beta}y'(t)}{t^{2(1-\beta)}} = \frac{y''(t)t - (1-\beta)y'(t)}{t^{2-\beta}} < 0, \qquad (3.9)$$

so part (v) holds.

Part (vi) clearly holds in view of (v) and (iii).

To prove (vii), it suffices to show that there is an $\varepsilon > 1$ such that

$$\left(\frac{y'(t)}{t^{1-\varepsilon\beta}}\right)' < 0 \tag{3.10}$$

for large t. Using (3.9), we see that for any $k \in (0, 1)$ and t sufficiently large, say $t \ge t_4 \ge t_3$,

$$y(t) = y(t_1) + \int_{t_1}^t \frac{y'(s)}{s^{1-\beta}} s^{1-\beta} ds$$

$$\geq y(t_1) + \frac{y'(t)}{t^{1-\beta}} \int_{t_1}^t s^{1-\beta} ds$$

$$= y(t_1) + \frac{y'(t)}{t^{1-\beta}} \frac{t^{2-\beta} - t_1^{2-\beta}}{2-\beta} \geq k \frac{y'(t)t}{2-\beta},$$
(3.11)

which implies

$$\left(\frac{y}{t^{(2-\beta)/k}}\right)' \le 0, \quad t \ge t_4$$

Employing the above monotonicity in (3.7) gives

$$z'(t) \ge 2\beta \frac{y(\tau(t))}{\tau^2(t)} = 2\beta \frac{y(\tau(t))\tau^{(2-\beta)/\!k}(t)}{\tau^{2+(2-\beta)/\!k}(t)} \ge 2\beta \frac{y(t)\tau^{(2-\beta)/\!k}(t)}{t^{(2-\beta)/\!k}\tau^2(t)} = 2\beta \frac{y(t)}{t^2} \left(\frac{t}{\tau(t)}\right)^{2-(2-\beta)/\!k}.$$

If we choose $k > (2 - \beta)/2$, then

$$\left(\frac{t}{\tau(t)}\right)^{2-(2-\beta)/k} \ge \lambda^{2-(2-\beta)/k} \ge 1$$

and using (3.11), we have

$$z'(t) \ge 2\beta \frac{y(t)}{t^2} \ge \frac{2\beta k}{2-\beta} \frac{y'(t)}{t}.$$
 (3.12)

Integrating the last inequality from t_4 to t and using (iii), we see that there exists $t_5 > t_4$ such that

$$z(t) \ge z(t_3) + \frac{2\beta k}{2-\beta} \frac{y'(t)}{t}(t-t_3) > \frac{2\beta k}{2-\beta} y'(t), \quad t \ge t_5.$$

In view of the definition of z, we conclude that

$$ty''(t) < \left(1 - \frac{2\beta k}{2 - \beta}\right)y'(t),$$

which implies that (3.10) holds with $\varepsilon = 2k/(2-\beta) > 1$. This proves (vii).

(viii) Using (vii) in (3.11), there exists $t_6 > t_5$ such that

$$y(t_1) - \frac{y'(t)}{t^{1-\beta}} \frac{t_1^{2-\beta}}{2-\beta} > 0, \quad t \ge t_6,$$

and so (3.11) becomes

$$(2-\beta)y(t) > y'(t)t, \quad t \ge t_6,$$
 (3.13)

which implies

$$\left(\frac{y(t)}{t^{2-\beta}}\right)' = \frac{y'(t)t^{2-\beta} - (2-\beta)t^{1-\beta}y(t)}{t^{2(2-\beta)}} = \frac{y'(t)t - (2-\beta)y(t)}{t^{3-\beta}} < 0$$

for $t \ge t_6$. This proves (viii) and finishes the proof of the lemma.

Lemma 3.4. Assume that $\beta_* > 0$ and $\lambda_* = \infty$. Then $\mathcal{N}_2 = \emptyset$.

Proof. Suppose, to the contrary, that $y \in \mathcal{N}_2 \neq \emptyset$ and let $t_1 \geq t_0$ be such that $y(\tau(t)) > 0$ for $t \geq t_1$. Since $\lambda_* = \infty$, for any $\lambda > 1$, there exists $t_\lambda \geq t_1$ such that $t/\tau(t) \geq \lambda$ for $t \geq t_\lambda$. From (3.7), (viii), and (3.1), for $t \geq t_2 \geq t_\lambda$,

$$z'(t) \ge 2\beta \frac{y(\tau(t))}{\tau^2(t)} \ge 2\beta \frac{y(t)}{t^2} \left(\frac{t}{\tau(t)}\right)^{\beta} \ge 2\beta \lambda^{\beta} \frac{y(t)}{t^2} > \frac{2}{2-\beta} \beta \lambda^{\beta} \frac{y'(t)}{t}.$$
 (3.14)

As λ can be arbitrarily large, we can choose it such that $\lambda^{\beta} > (2-\beta)/2\beta$. Therefore,

$$z'(t) > \frac{y'(t)}{t}.$$

Integrating and using the fact that y'(t)/t is decreasing, we obtain

$$z(t) \ge z(t_1) + \frac{y'(t)}{t}(t - t_1),$$

so z(t) > y'(t) for t sufficiently large, say $t \ge t_2$ for some $t_2 \ge t_1$. This implies ty''(t) < 0, which is a contradiction, and completes the proof of the lemma. \Box

In view of Lemma 3.4, from this point forward it is reasonable to assume that λ_* is a finite constant so that $\mathcal{N}_2 \neq \emptyset$. It is then possible to initiate an iterative procedure that will improve the monotonicity results in Lemma 3.3 and that in turn will lead to a sharp oscillation result for equation (1.1). To this end, let us define the sequence $\{\beta_n\}_{n \in \mathbb{N}_0}$ by

$$\beta_0 := \beta_*, \qquad \beta_n := \frac{2\beta_0 \lambda_*^{\beta_{n-1}}}{(2 - \beta_{n-1})(1 - \beta_{n-1})}.$$
(3.15)

By induction, it is easy to verify that if $\beta_i < 1$ for i = 1, 2, ..., n, then β_{n+1} exists and

$$\frac{\beta_{n+1}}{\beta_n} = \ell_n > 1, \tag{3.16}$$

where

$$\ell_0 := \frac{\beta_1}{\beta_0} = \frac{2\lambda_*^{\beta_0}}{(2-\beta_0)(1-\beta_0)} > 1,$$

$$\ell_n := \frac{\beta_{n+1}}{\beta_n} = \frac{\lambda_*^{\beta_n} (2 - \beta_{n-1}) (1 - \beta_{n-1})}{\lambda_*^{\beta_{n-1}} (2 - \beta_n) (1 - \beta_n)} > 1.$$

The following lemma is an iterative version of Lemma 3.3.

Lemma 3.5. Assume that $\beta_* > 0$ and y is a solution of (1.1) belonging to the class \mathcal{N}_2 . Then for any $\varepsilon_n \in (0, 1)$ and sufficiently large t:

$$\begin{split} &(I)_n \ y'(t)/t^{1-\varepsilon_n\beta_n} \ is \ decreasing \ and \ ty''(t) < (1-\varepsilon_n\beta_n)y'(t); \\ &(II)_n \ \varepsilon_n\beta_n < 1; \\ &(III)_n \ \lim_{t\to\infty} y'(t)/t^{1-\varepsilon_n\beta_n} = 0; \\ &(IV)_n \ y(t)/t^{2-\varepsilon_n\beta_n} \ is \ decreasing \ and \ y(t) > y'(t)t/(2-\varepsilon_n\beta_n). \end{split}$$

Proof. Let $y \in \mathcal{N}_2$ with $y(\tau(t)) > 0$ for $t \ge t_1$ for some $t_1 \ge t_0$. We will proceed by induction on n. For n = 0, the conclusion follows from Lemma 3.3, where $\varepsilon_0 = \beta/\beta_*$ and $\lim_{\beta \to \beta_*} \varepsilon_0 = 1$.

Next, assume that $(I)_n - (IV)_n$ hold for $n \ge 1$ for $t \ge t_n \ge t_1$. We need to show that they each hold for n + 1.

 $(I)_n$ Using (viii) and (3.1) in (3.7), we have

$$\begin{aligned} z'(t) &= (y' - ty'')' \ge 2\varepsilon_0 \beta_0 \frac{y(\tau(t))}{\tau^2(t)} \\ &= 2\varepsilon_0 \beta_0 \frac{y(\tau(t))}{\tau^{2-\varepsilon_n \beta_n}(t) \tau^{\varepsilon_n \beta_n}(t)} \\ &\ge 2\varepsilon_0 \beta_0 \frac{y(t)}{t^2} \frac{t^{\varepsilon_n \beta_n}}{\tau^{\varepsilon_n \beta_n}(t)} \\ &\ge 2\varepsilon_0 \beta_0 \lambda^{\varepsilon_n \beta_n} \frac{y(t)}{t^2} \\ &\ge \frac{2\varepsilon_0 \beta_0 \lambda^{\varepsilon_n \beta_n}}{2-\varepsilon_n \beta_n} \frac{y'(t)}{t}. \end{aligned}$$

Integrating from t_n to t and using (v) and (vii) in the resulting inequality, we see that there exists $t'_n > t_n$ such that

$$\begin{aligned} z(t) &\geq z(t_n) + \frac{2\varepsilon_0\beta_0\lambda^{\varepsilon_n\beta_n}}{2 - \varepsilon_n\beta_n} \int_{t_n}^t \frac{y'(s)}{s^{1-\varepsilon_n\beta_n}s^{\varepsilon_n\beta_n}} \mathrm{d}s \\ &\geq z(t_n) + \frac{2\varepsilon_0\beta_0\lambda^{\varepsilon_n\beta_n}}{(2 - \varepsilon_n\beta_n)(1 - \varepsilon_n\beta_n)} \frac{y'(t)}{t^{1-\varepsilon_n\beta_n}} \left(t^{1-\varepsilon_n\beta_n} - t_n^{1-\varepsilon_n\beta_n}\right) \\ &> \frac{2\varepsilon_0\beta_0\lambda^{\varepsilon_n\beta_n}}{(2 - \varepsilon_n\beta_n)(1 - \varepsilon_n\beta_n)}y'(t) \\ &= \varepsilon_{n+1}\beta_{n+1}y'(t), \quad t \geq t'_n, \end{aligned}$$

where

$$\varepsilon_{n+1} = \varepsilon_0 \frac{\lambda^{\varepsilon_n \beta_n}}{\lambda_*^{\beta_n}} \frac{(2 - \beta_n)(1 - \beta_n)}{(2 - \varepsilon_n \beta_n)(1 - \varepsilon_n \beta_n)}, \quad n \in \mathbb{N}_0.$$

Clearly,

$$\lim_{(\lambda \to \lambda_*)(\beta \to \beta_0)} \varepsilon_{n+1} = 1,$$

which proves $(I)_n$.

 $(II)_n$ This clearly holds in view of $(I)_n$ and (iii).

 $(\text{III})_n$ As for the case n = 0, it will suffice to show that there is $\varepsilon > 1$ such that

$$\left(\frac{y'(t)}{t^{1-\varepsilon\varepsilon_n\beta_n}}\right)' < 0. \tag{3.17}$$

Using (I)_n, we see that for any $k \in (0,1)$, there exists $t''_n \ge t'_n$ so that

$$y(t) = y(t_n) + \int_{t_n}^t \frac{y'(s)}{s^{1-\varepsilon_n\beta_n}} s^{1-\varepsilon_n\beta_n} ds$$

$$\geq y(t_n) + \frac{y'(t)}{t^{1-\varepsilon_n\beta_n}} \int_{t_n}^t s^{1-\varepsilon_n\beta_n} ds$$

$$= y(t_n) + \frac{y'(t)}{t^{1-\varepsilon_n\beta_n}} \frac{t^{2-\varepsilon_n\beta_n} - t_n^{2-\varepsilon_n\beta_n}}{2-\varepsilon_n\beta_n} \geq k \frac{y'(t)t}{2-\varepsilon_n\beta_n}, \quad t \geq t''_n, \quad (3.18)$$

that is,

$$\left(\frac{y}{t^{(2-\varepsilon_n\beta_n)/k}}\right)' < 0. \tag{3.19}$$

Then (3.7) and (3.19) imply

$$z'(t) \geq 2\varepsilon_0 \beta_0 \frac{y(\tau(t))}{\tau^2(t)}$$

$$= 2\varepsilon_0 \beta_0 \frac{y(\tau(t))\tau^{(2-\varepsilon_n\beta_n)/k}(t)}{\tau^{2+(2-\varepsilon_n\beta_n)/k}(t)}$$

$$\geq 2\varepsilon_0 \beta_0 \frac{y(t)}{t^{(2-\varepsilon_n\beta_n)/k}} \frac{\tau^{(2-\varepsilon_n\beta_n)/k}(t)}{\tau^2(t)}$$

$$= 2\varepsilon_0 \beta_0 \frac{y(t)}{t^2} \frac{\tau^{(2-\varepsilon_n\beta_n)/k}(t)}{\tau^2(t)} \frac{t^2}{t^{(2-\varepsilon_n\beta_n)/k}}$$

$$= 2\varepsilon_0 \beta_0 \frac{y(t)}{t^2} \left(\frac{t}{\tau(t)}\right)^{2-(2-\varepsilon_n\beta_n)/k}.$$
(3.20)

Now take $k > (2 - \varepsilon_n \beta_n)/2$. Then again by (iv),

$$z'(t) \ge 2\varepsilon_0\beta_0\frac{y(t)}{t^2} \ge \frac{2\varepsilon_0\beta_0k}{2-\varepsilon_n\beta_n}\frac{y'(t)}{t}.$$

Integrating from t''_n to t and using (ii), we have

$$z(t) \ge z(t''_n) + \frac{2\varepsilon_0\beta_0k}{2-\varepsilon_n\beta_n}\frac{y'(t)}{t}(t-t''_n) > \frac{2\varepsilon_0\beta_0k}{2-\varepsilon_n\beta_n}y'(t), \quad t \ge t''_n,$$

for some $t_n^{\prime\prime\prime} \ge t_n^{\prime\prime}$. Therefore,

$$ty''(t) < \left(1 - \frac{2\varepsilon_0\beta_0k}{2 - \varepsilon_n\beta_n}\right)y'(t),$$

and so (3.17) holds, where $\varepsilon = 2k/(2 - \varepsilon_n \beta_n) > 1$. This proves $(III)_n$.

 $(IV)_n$ From (3.18),

$$(2 - \varepsilon_n \beta_n) y(t) > y'(t)t$$

and so

$$\left(\frac{y(t)}{t^{2-\varepsilon_n\beta_n}}\right)' = \frac{y'(t)t^{2-\varepsilon_n\beta_n} - (2-\varepsilon_n\beta_n)t^{1-\varepsilon_n\beta_n}y(t)}{t^{2(2-\varepsilon_n\beta_n)}} = \frac{y'(t)t - (2-\varepsilon_n\beta_n)y(t)}{t^{3-\varepsilon_n\beta_n}} < 0,$$

completing the proof of the lemma.

As a consequence of the above lemmas, we can prove the main result in our paper, namely, Theorem 2.1.

Proof of Theorem 2.1. Assume that y is a nonoscillatory solution of (1.1) such that $y(\tau(t)) > 0$ for $t \ge t_1$ for some $t_1 \ge t_0$. Then either $y \in \mathcal{N}_0$ or $y \in \mathcal{N}_2$. By condition (2.1), $\beta_* > 0$, so if $y \in \mathcal{N}_0$, then by Lemma 3.1, $\lim_{t\to\infty} y(t) = 0$.

Now if $y \in \mathcal{N}_2$, we need to consider two cases, namely, $\lambda_* = \infty$ or $\lambda_* < \infty$. If $\lambda_* = \infty$, then by Lemma 3.4 we see that $\mathcal{N}_2 = \emptyset$, and so (1.1) has Property A.

Finally, assume that $\lambda_* < \infty$. We claim that

$$\beta_{n-1} < 1, \quad n \in \mathbb{N}. \tag{3.21}$$

From (II)_n, $\varepsilon_n \beta_n < 1$. Since $\varepsilon_n \in (0, 1)$ can be chosen arbitrarily, set $\varepsilon_n > 1/\ell_n$, where ℓ_n is defined by (3.16). Then,

$$1 > \varepsilon_n \beta_n = \varepsilon_n \ell_n \beta_{n-1} > \beta_{n-1},$$

which proves the claim. In view of (3.21), we conclude that the sequence $\{\beta_n\}_{n=0}^{\infty}$ defined by (3.15) is increasing and bounded from above, that is, there exists a finite limit

$$\lim_{n \to \infty} \beta_n = y_i$$

where $y \in (0, 1)$ is a root of the equation

$$y(2-y)(1-y)\lambda_*^{-y} = 2\beta_0.$$

Set x = 2 - y. Then $x \in (1, 2)$ satisfies

$$-x(1-x)(2-x)\lambda_*^{x-2} = 2\beta_0.$$
(3.22)

However, condition (2.1) implies that (3.22) does not possess positive solutions. Hence, $\mathcal{N}_2 = \emptyset$ and the proof is complete.

As a final remark, we wish to mention that one of the reviewers asked if it would be possible to obtain corresponding non-improvable bounds for solutions in the class \mathcal{N}_0 . This would in fact be an interesting problem to investigate. The biggest barrier to applying the approach used here is that a lower non-zero bound for a positive solution belonging to the class \mathcal{N}_0 is not known due to the alternating signs of its derivatives. If such a bound could be determined, then what the reviewer suggests might be possible.

References

 R. P. Agarwal, M. F. Aktas and A. Tiryaki, On oscillation criteria for third order nonlinear delay differential equations, Arch. Math. (Brno), 2009, 45(1), 1–18.

2470

- [2] R. P. Agarwal, M. Bohner, T. Li and C. Zhang, *Hille and Nehari type criteria for third-order delay dynamic equations*, J. Difference Equ. Appl., 2013, 19(10), 1563–1579.
- [3] R. P. Agarwal, M. Bohner, T. Li and C. Zhang, Oscillation of third-order nonlinear delay differential equations, Taiwanese J. Math., 2013, 17(2), 545– 558.
- [4] M. Aktaş, A. Tiryaki and A. Zafer, Oscillation criteria for third-order nonlinear functional differential equations, Appl. Math. Lett., 2010, 23(7), 756–762.
- [5] B. Baculíková and J. Džurina, Oscillation of third-order functional differential equations, Electron. J. Qual. Theory Differ. Equ., 2010, (43), 1–10.
- [6] B. Baculíková and J. Džurina, Oscillation of third-order nonlinear differential equations, Appl. Math. Lett., 2011, 24(4), 466–470.
- [7] B. Baculíková and J. Džurina, Oscillation of the third order Euler differential equation with delay, Math. Bohem., 2014, 139(4), 649–655.
- [8] B. Baculíková, E. M. Elabbasy, S. H. Saker and J. Džurina, Oscillation criteria for third-order nonlinear differential equations, Math. Slovaca, 2008, 58(2), 201–220.
- M. Bohner, S. R. Grace and I. Jadlovská, Oscillation criteria for third-order functional differential equations with damping, Electron. J. Differential Equations, 2016, 2016(215).
- [10] T. Candan and R. S. Dahiya, Oscillation of third order functional differential equations with delay, in Proceedings of the Fifth Mississippi State Conference on Differential Equations and Computational Simulations (Mississippi State, MS, 2001), 10 of Electron. J. Differ. Equ. Conf., Southwest Texas State Univ., San Marcos, TX, 2003, 79–88.
- [11] M. Cecchi, Z. Došlá and M. Marini, Disconjugate operators and related differential equations, in Proceedings of the 6th Colloquium on the Qualitative Theory of Differential Equations (Szeged, 1999), Proc. Colloq. Qual. Theory Differ. Equ., Electron. J. Qual. Theory Differ. Equ., Szeged, 2000, 4, 17.
- [12] J. Džurina and I. Jadlovská, A sharp oscillation result for second-order halflinear noncanonical delay differential equations, Electron. J. Qual. Theory Differ. Equ., 2020, (46), 1–14.
- [13] E. M. Elabbasy, T. S. Hassan and B. M. Elmatary, Oscillation criteria for third order delay nonlinear differential equations, Electron. J. Qual. Theory Differ. Equ., 2012, 5, 11.
- [14] S. R. Grace, Oscillation criteria for third order nonlinear delay differential equations with damping, Opuscula Math., 2015, 35(4), 485–497.
- [15] S. R. Grace, R. P. Agarwal, R. Pavani and E. Thandapani, On the oscillation of certain third order nonlinear functional differential equations, Appl. Math. Comput., 2008, 202(1), 102–112.

- [16] J. K. Hale, Functional Differential Equations, Springer-Verlag, New York, 1971. Applied Mathematical Sciences.
- [17] M. Hanan, Oscillation criteria for third-order linear differential equations, Pacific J. Math., 1961, 11(3), 919–944.
- [18] P. Hartman and A. Wintner, Linear differential and difference equations with monotone solutions, Amer. J. Math., 1953, 75(4), 731–743.
- [19] I. Jadlovská, Oscillation criteria of kneser-type for second-order half-linear advanced differential equations, Appl. Math. Lett., 2020, 106354.
- [20] I. Jadlovská and J. Džurina, Kneser-type oscillation criteria for second-order half-linear delay differential equations, Appl. Math. Comput., 2020, 380, 125289.
- [21] I. T. Kiguradze and T. A. Chanturia, Asymptotic properties of solutions of nonautonomous ordinary differential equations, 89 of Mathematics and its Applications (Soviet Series), Kluwer Academic Publishers Group, Dordrecht, 1993. Translated from the 1985 Russian original.
- [22] A. Kneser, Untersuchungen über die reellen nullstellen der integrale linearer differentialgleichungen, Math. Ann., 1893, 42(3), 409–435.
- [23] T. Li, C. Zhang, B. Baculí ková and J. Džurina, On the oscillation of thirdorder quasi-linear delay differential equations, Tatra Mt. Math. Publ., 2011, 48, 117–123.
- [24] W. Mahfoud, Comparison theorems for delay differential equations, Pacific J. Math., 1979, 83(1), 187–197.
- [25] S. Padhi and S. Pati, Theory of third-order differential equations, Springer, New Delhi, 2014.
- [26] S. Saker, Oscillation criteria of hille and nehari types for third-order delay differential equations, Comm. Appl. Anal., 2007, 11(3–4), 451–468.
- [27] S. Saker, Oscillation Theory of Delay Differential and Difference Equations: Second and Third Orders., LAP Lambert Academic Publishing, 2010.
- [28] S. H. Saker and J. Džurina, On the oscillation of certain class of third-order nonlinear delay differential equations, Math. Bohem., 2010, 135(3), 225–237.