

EXISTENCE AND MULTIPLICITY OF SIGN-CHANGING SOLUTIONS FOR THE DISCRETE PERIODIC PROBLEMS WITH MINKOWSKI-CURVATURE OPERATOR*

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Abstract We are concerned with the discrete periodic problems with Minkowski-curvature operator

$$\begin{cases} -\nabla\left(\frac{\Delta u(t)}{\sqrt{1-(\Delta u(t))^2}}\right) = \lambda g(t, u(t)), & t \in \mathbb{T}, \\ u(0) = u(T), u(1) = u(T+1), \end{cases} \quad (P)$$

where $T > 2$ is an integer, $\mathbb{T} := \{1, 2, \dots, T\}$, $\hat{\mathbb{T}} = \{0, 1, \dots, T, T+1\}$, $\mathbb{Z} := \{\dots, -1, 0, 1, \dots\}$, $g : \mathbb{Z} \times \mathbb{R} \rightarrow \mathbb{R}$ is continuous, $g_0 := \lim_{s \rightarrow 0} \frac{g(t, s)}{s} = +\infty$ uniformly for $t \in \hat{\mathbb{T}}$, g is T -periodic respect to t , $\lambda \in (0, \infty)$ is a parameter. We show that (P) has multiple odd sign-changing solutions and multiple even sign-changing solutions when $g(t, \cdot)$ is odd. The proof of our main result is based upon bifurcation techniques.

Keywords Minkowski-curvature operator, discrete periodic problem, odd solutions, even solutions.

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1. Introduction

Let $T > 2$ be an integer, $\mathbb{T} := [1, T]_{\mathbb{Z}} = \{1, 2, \dots, T\}$, $\hat{\mathbb{T}} := [0, T+1]_{\mathbb{Z}} = \{0, 1, \dots, T, T+1\}$, $\mathbb{Z} := \{\dots, -1, 0, 1, \dots\}$.

Define Δ and ∇ by

$$\Delta u(t) = u(t+1) - u(t), \quad \nabla u(t) = u(t) - u(t-1),$$

respectively. In this paper, we are concerned with the discrete periodic problems with Minkowski-curvature operator

$$\begin{cases} -\nabla\left(\frac{\Delta u(t)}{\sqrt{1-(\Delta u(t))^2}}\right) = \lambda g(t, u(t)), & t \in \mathbb{T}, \\ u(0) = u(T), u(1) = u(T+1), \end{cases} \quad (1.1)$$

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where $g : \mathbb{Z} \times \mathbb{R} \rightarrow \mathbb{R}$ is continuous, g is T -periodic respect to t , $\lambda \in (0, \infty)$ is a parameter. Assume that $g(t, \cdot)$ is odd and $g_0 := \lim_{s \rightarrow 0} \frac{g(t, s)}{s} = +\infty$ uniformly for $t \in \hat{\mathbb{T}}$. A *solution* of (1.1) is a function $u : \hat{\mathbb{T}} \rightarrow \mathbb{R}$ such that $\max_{t \in \hat{\mathbb{T}}} |\Delta u(t)| < 1$ and u satisfies (1.1).

The equation in (1.1) is the one-dimensional discrete version of the following

$$-\operatorname{div}\left(\frac{\operatorname{grad} u}{\sqrt{1-|\operatorname{grad} u|^2}}\right) = \lambda g(x, u) \quad \text{in } \Omega, \quad (1.2)$$

where $u \mapsto -\operatorname{div}\left(\frac{\operatorname{grad} u}{\sqrt{1-|\operatorname{grad} u|^2}}\right)$ in turn is usually meant as a mean-curvature operator in Lorentz-Minkowski spaces, Ω is a bounded domain in \mathbb{R}^N , with a boundary $\partial\Omega$ of class C^2 .

The existence and multiplicity of solutions for the prescribed mean curvature equations with Dirichlet boundary conditions and the discrete analogue have been widely discussed by various methods, see [9, 10, 12, 15, 25] and the references therein.

In [14] some general solvability results for (1.2) with Dirichlet boundary conditions were proved under the assumption that the function g is globally bounded. Yet, as all spacelike solutions of the Dirichlet problem are uniformly bounded by the quantity $\frac{1}{2}d(\Omega)$, with $d(\Omega)$ the diameter of Ω , one can always reduce to that situation by truncation, see Coelho et al. [9, 10].

Nevertheless it should be observed that the situation differs substantially for periodic solutions of (1.2). In the continuous case, existence and multiplicity of periodic solutions for the equations with mean-curvature operator have been studied extensively, see Benevieri, Marcos do Ó and de Medeiros [3], Bereanu, Jebelean and Mawhin [4], Bereanu and Mawhin [5], Bereanu and Zamora [7], Bosecaggin and Feltrin [8].

However, there are many differences, even essential differences, between the difference equation and the corresponding differential equation. From the definition of Strogatz [28], chaos sensitivity depends on initial conditions. That is shown that nearby trajectories diverge exponentially. Continuous systems in a 2-dimensional phase space cannot experience such a divergence, hence chaotic behaviors can only be observed in deterministic continuous systems with a phase space of dimension 3, at least. On the other hand, in a discrete map it is well known that chaos occurs also in one-dimension. Therefore, discrete chaotic systems exhibit chaos whatever their dimension.

In addition, unlike the continuous case, the discrete linear eigenvalue problem

$$\begin{cases} -\nabla(\Delta u(t)) = \lambda u(t), & t \in \mathbb{T}, \\ u(0) = u(T), & u(1) = u(T+1) \end{cases} \quad (1.3)$$

has only a finite number of eigenvalues.

Let

$$N := \begin{cases} \frac{T}{2}, & \text{as } T \text{ is even,} \\ \frac{T-1}{2}, & \text{as } T \text{ is odd.} \end{cases}$$

From [19] and [20], the eigenvalues of (1.3) are the following

$$0 = \lambda_0 < \lambda_1 < \lambda_2 < \cdots < \lambda_N.$$

The eigenspace corresponding to λ_0 is $\text{span}\{1\}$, the eigenspace corresponding to λ_j , $j \in [1, N-1]_{\mathbb{Z}}$ is

$$M_j = \text{span}\left\{\cos \frac{2j\pi t}{T}, \sin \frac{2j\pi t}{T}\right\}, \quad t \in \mathbb{T},$$

and the eigenspace corresponding to λ_N is

$$\begin{aligned} M_N &= \text{span}\left\{\cos \frac{2N\pi t}{T}, \sin \frac{2N\pi t}{T}\right\}, \quad t \in \mathbb{T}, \quad T \text{ is odd,} \\ M_N &= \text{span}\left\{\cos \frac{2N\pi t}{T}\right\} = \text{span}\{\cos \pi t\}, \quad t \in \mathbb{T}, \quad T \text{ is even.} \end{aligned}$$

Semilinear discrete boundary value problems was studied by Atici and Cabada [1], Atici, Cabada and Otero-Espinar [2], Henderson and Thompson [16], Ma and Ma [19, 20]. For example, Atici and Cabada [1] concerned with proving the existence of positive solutions of a periodic boundary value problem for a discrete nonlinear equation

$$\begin{cases} -\Delta[p(n-1)\Delta u(n-1)] + q(n)u(n) = \lambda f(n, u(n)), & n \in [1, N]_{\mathbb{Z}}, \\ u(0) = u(N), \quad p(0)\Delta u(0) = p(N)\Delta u(N), \end{cases} \quad (1.4)$$

where f is a continuous function on \mathbb{R} . Under certain conditions of f , they obtained that there exists at least one positive solution of (1.4) for λ belonging to a given interval.

Existence and multiplicity of solutions for discrete problems with periodic boundary condition involving mean curvature operator have been studied by some authors, see Bereanu and Thompson [6], Mawhin [22, 23] and the references therein. In particular, Bereanu and Thompson [6] considered the forced equation involving the discrete φ -Laplacian

$$D\varphi(Dx_k) = h_k \quad (2 \leq k \leq n-1), \quad x_1 = x_n, \quad Dx_1 = Dx_{n-1}, \quad (1.5)$$

where φ can be the mean curvature operator and $h = (h_2, \dots, h_{n-1})$ satisfies $\sum_{k=2}^{n-1} h_k = 0$. They obtained the result as following.

Theorem A. *Assume that there exist numbers α, β such that*

$$f_k(\alpha) \geq 0 \geq f_k(\beta) \quad (2 \leq k \leq n-1).$$

Then problem (1.5) has at least one solution with $\alpha \leq x_k \leq \beta$ ($1 \leq k \leq n$).

In fact, most people only obtain the existence of positive solutions, or even the existence of solutions. Very little is known about existence and multiplicity of sign-changing periodic solutions for the problem (1.1). The likely reason is that the multiplicity of higher eigenvalues, $\lambda_k (k \in \{1, 2, \dots, N-1\})$, is even. However, the key of Rabinowitz global bifurcation theorem is $\dim M_k = 1$, see Rabinowitz [26, 27].

In order to apply the bifurcation techniques, we have to work in

$$E_1 := \{u \in H \mid u(-t) = -u(t), t \in \mathbb{Z}\}$$

and

$$E_2 := \{u \in H \mid u(-t) = u(t), t \in \mathbb{Z}\},$$

which are two subspaces of

$$H := \{u : \mathbb{Z} \rightarrow \mathbb{R} \mid u \text{ is } T\text{-periodic}\}.$$

The above method of constructing invariant subspaces is motivated by Coron [11] and Marlin [21].

Therefore, the purpose of this paper is to use the bifurcation techniques to investigate the existence and multiplicity of sign-changing solutions for (1.1), which is a discrete periodic problem with mean curvature operators in the Minkowski space.

Due to $g_0 = +\infty$, the global bifurcation techniques cannot be used directly in the case. Therefore, we referred to [18] and applied some properties of the superior limit of a certain infinity collection of connected sets. In addition, we also made some estimates on the properties of solutions of (1.1), and proved the existence of a *priori bound* for the solutions of (1.1).

For other nonlinear boundary value problems with odd nonlinearity g , see Naito and Tanaka [24], Garcia-Huidobro and Ubilla [13].

Assume that $g(t, \cdot)$ is odd for all $t \in \hat{\mathbb{T}}$, and satisfies either

(H1) there exists $0 < s_0 < \infty$ such that

$$\begin{aligned} g(t, s) &> 0 \quad \text{for all } 0 < s < s_0, \quad t \in \hat{\mathbb{T}}, \\ g(t, s_0) &= 0 \quad \text{for all } t \in \hat{\mathbb{T}}, \\ g(t, s) &< 0 \quad \text{for all } s > s_0, \quad t \in \hat{\mathbb{T}} \end{aligned}$$

or

(H2) $g(t, s) \geq 0, s \in [0, \infty), t \in \hat{\mathbb{T}}$.

Theorem 1.1. *Assume that*

$$g_0 := \lim_{s \rightarrow 0} \frac{g(t, s)}{s} = +\infty \quad (1.6)$$

uniformly for $t \in \hat{\mathbb{T}}$. Then

- (i) *for any $k \in [1, N-1]_{\mathbb{Z}}$, $\nu \in \{+, -\}$, there exists a connected component $\mathcal{C}_k^\nu \subset \mathbb{R} \times E_1$ of sign-changing solutions of (1.1) joins $(0, 0)$ with infinity in λ direction, and any solution $(\lambda, u) \in \mathcal{C}_k^\nu$ satisfies $\max_{t \in \hat{\mathbb{T}}} |u(t)| < \frac{T}{2}$;*
- (ii) *for any $k \in [1, N]_{\mathbb{Z}}$, $\nu \in \{+, -\}$, if g satisfies the condition (H1), then there exists a connected component $\mathcal{D}_k^\nu \subset \mathbb{R} \times E_2$ of sign-changing solutions of (1.1) joins $(0, 0)$ with infinity in λ direction, and any solution $(\lambda, v) \in \mathcal{D}_k^\nu$ satisfies $\max_{t \in \hat{\mathbb{T}}} |v(t)| \leq s_0$;*
- (iii) *for any $k \in [1, N]_{\mathbb{Z}}$, $\nu \in \{+, -\}$, if g satisfies the condition (H2), then there exists a connected component $\mathcal{D}_k^\nu \subset \mathbb{R} \times E_2$ of sign-changing solutions of (1.1) joins $(0, 0)$ with infinity in λ direction, and any solution $(\lambda, v) \in \mathcal{D}_k^\nu$ satisfies $\max_{t \in \hat{\mathbb{T}}} |v(t)| < T$.*

By a *component* of solution set \mathcal{S} we mean a continuum which is maximal with respect to inclusion ordering.

Corollary 1.1. *Assume that*

$$g_0 := \lim_{s \rightarrow 0} \frac{g(t, s)}{s} = +\infty$$

uniformly for $t \in \hat{\mathbb{T}}$. Then

- (i) *for any $\lambda \in (0, +\infty)$, $k \in [1, N-1]_{\mathbb{Z}}$, $\nu \in \{+, -\}$, (1.1) has odd solutions u_k^ν such that u_k^ν change their sign $2k-1$ times in \mathbb{T} and $u_k^- = -u_k^+$.*
- (ii) *for any $\lambda \in (0, +\infty)$, $k \in [1, N]_{\mathbb{Z}}$, $\nu \in \{+, -\}$, if g satisfies either (H1) or (H2), then (1.1) has even solutions v_k^ν such that v_k^ν change their sign $2k$ times in \mathbb{T} and $v_k^- = -v_k^+$.*

2. Preliminary results

Definition 2.1 ([17]). Let $y : \hat{\mathbb{T}} \rightarrow \mathbb{R}$. If $y(t) = 0$, then t is a zero of $y(t)$. If $y(t) = 0$ and $y(t+1)y(t-1) < 0$, then t is a simple zero of $y(t)$. If $y(t)y(t+1) < 0$, then $s = \frac{ty(t+1)-(t+1)y(t)}{y(t+1)-y(t)}$ is called a nodal point of $y(t)$. The simple zero and the nodal point are called the simple generalized zero of $y(t)$.

The following two lemmas concerning the spectrum properties of the discrete linear problem (1.3). They were established by Ma and Ma [19, 20].

Lemma 2.1 ([19, 20]). *The following are true:*

- (i) $\sum_{t=1}^T \cos \frac{2k\pi t}{T} \sin \frac{2k\pi t}{T} = 0, \begin{cases} k = 1, 2, \dots, N, & T \text{ is odd,} \\ k = 1, 2, \dots, N-1, & T \text{ is even;} \end{cases}$
- (ii) $\sum_{t=1}^T \sin \frac{2k\pi t}{T} = 0, \begin{cases} k = 1, 2, \dots, N, & T \text{ is odd,} \\ k = 1, 2, \dots, N-1, & T \text{ is even;} \end{cases}$
- (iii) $\sum_{t=1}^T \sin \frac{2j\pi t}{T} \sin \frac{2k\pi t}{T} = 0, \begin{cases} j \neq k, j, k = 1, 2, \dots, N, & T \text{ is odd,} \\ j \neq k, j, k = 1, 2, \dots, N-1, & T \text{ is even;} \end{cases}$
- (iv) $\sum_{t=1}^T \cos \frac{2j\pi t}{T} \cos \frac{2k\pi t}{T} = 0, \quad j \neq k, \quad j, k = 1, 2, \dots, N.$

Set $\varphi_0 = 1$,

$$\varphi_k(t) = \cos \frac{2k\pi t}{T} / \left\| \cos \frac{2k\pi t}{T} \right\|, \quad k = 1, 2, \dots, N,$$

$$\psi_k(t) = \sin \frac{2k\pi t}{T} / \left\| \sin \frac{2k\pi t}{T} \right\|, \quad k = 1, 2, \dots, N.$$

Then

$$\|\varphi_k\| = 1, \quad \|\psi_k\| = 1, \quad k = 1, 2, \dots, N.$$

Lemma 2.2 ([19, 20]). *The φ_k and ψ_k defined in Lemma 2.1 satisfy the following*

- (i) $\varphi_k (k = 1, 2, \dots, N)$ changes its sign $2k$ times in \mathbb{T} ;

- (ii) $\psi_k(k = 1, 2, \dots, N$ when T is odd, $k = 1, 2, \dots, N - 1$ when T is even) changes its sign $2k - 1$ times in \mathbb{T} .

Definition 2.2 ([29]). Let X be a Banach space and $\{C_n \mid n = 1, 2, \dots\}$ be a family of subsets of X . Then the superior limit \mathcal{D} of C_n is defined by

$$\mathcal{D} := \limsup_{n \rightarrow \infty} C_n = \{x \in X \mid \exists \{n_i\} \subset \mathbb{N} \text{ and } x_{n_i} \in C_{n_i} \text{ such that } x_{n_i} \rightarrow x\}.$$

Lemma 2.3 ([18]). Let X be a Banach space, and let $\{C_n\}$ be a family of connected subsets of X . Assume that

- (a) there exist $z_n \in C_n, n = 1, 2, \dots$, and $z^* \in X$, such that $z_n \rightarrow z^*$;
 (b) $\lim_{n \rightarrow \infty} r_n = \infty$, where $r_n = \sup\{\|x\| : x \in C_n\}$;
 (c) for every $R > 0$, $\cup_{n=1}^{\infty} C_n \cap B_R$ is a relatively compact set of X , where

$$B_R = \{x \in X \mid \|x\| \leq R\}.$$

Then there exists an unbounded component C in \mathcal{D} and $z^* \in C$.

Lemma 2.4. For any sign-changing solution u of (1.1), if u is odd, then

$$\|u\| := \max_{t \in \hat{\mathbb{T}}} |u(t)| < \frac{T}{2}.$$

Proof. If $u(0) = u(T) = \|u\|$, then $\|u\| = 0$. The conclusion is clearly correct. If $u(0) = u(T) \neq \|u\|$, we suppose that $|u(t_0)| = \|u\|$, $t_0 \in \hat{\mathbb{T}} \setminus \{0, T, T+1\}$ (Let $t_0 = 1$ if $|u(T+1)| = |u(1)| = \|u\|$).

(i) Assume that $u(t_0) > 0$. Due to u is a sign-changing solution of (1.1), then $|\Delta u(t)| < 1$ for any $t \in \hat{\mathbb{T}}$ and

$$\begin{aligned} u(t_0) - u(0) &= \sum_{i=0}^{t_0-1} (u(i+1) - u(i)) = \sum_{i=0}^{t_0-1} \Delta u(i) \leq \sum_{i=0}^{t_0-1} |\Delta u(i)| < \sum_{i=0}^{t_0-1} 1 = t_0, \\ u(T) - u(t_0) &= \sum_{i=t_0}^{T-1} (u(i+1) - u(i)) = \sum_{i=t_0}^{T-1} \Delta u(i) \geq \sum_{i=t_0}^{T-1} -|\Delta u(i)| > \sum_{i=t_0}^{T-1} -1 = t_0 - T. \end{aligned}$$

Therefore,

$$u(t_0) < 0 + \frac{t_0 - (t_0 - T)}{2} < \frac{T}{2}.$$

(ii) Assume that $u(t_0) < 0$. Similarly,

$$|u(t_0)| < \frac{T}{2}.$$

Hence, the proof is completed. \square

Lemma 2.5. Let $u : \hat{\mathbb{T}} \rightarrow \mathbb{R}$ such that $\|\Delta u(t)\| < 1$. Then for any $t \in \hat{\mathbb{T}}$,

$$\begin{aligned} &\nabla \left(\frac{\Delta u(t)}{\sqrt{1 - (\Delta u(t))^2}} \right) \\ &= \nabla(\Delta u(t)) \left[\frac{\sqrt{1 - (\Delta u(t-1))^2} \sqrt{1 - (\Delta u(t))^2} + 1 + \Delta u(t-1) \Delta u(t)}{\sqrt{1 - (\Delta u(t))^2} \sqrt{1 - (\Delta u(t-1))^2} [\sqrt{1 - (\Delta u(t))^2} + \sqrt{1 - (\Delta u(t-1))^2}]} \right]. \end{aligned}$$

Proof. By a simple calculation,

$$\nabla\left(\frac{u(t)}{v(t)}\right) = \frac{\nabla u(t)v(t-1) - u(t-1)\nabla v(t)}{v(t)v(t-1)},$$

and

$$\nabla(\sqrt{1 - (\Delta u(t))^2}) = \frac{-\nabla(\Delta u(t))[\Delta u(t) + \Delta u(t-1)]}{\sqrt{1 - (\Delta u(t))^2} + \sqrt{1 - (\Delta u(t-1))^2}}.$$

Then

$$\begin{aligned} & \nabla\left(\frac{\Delta u(t)}{\sqrt{1 - (\Delta u(t))^2}}\right) \\ &= \frac{\nabla(\Delta u(t))\sqrt{1 - (\Delta u(t-1))^2} - \Delta u(t-1)\nabla(\sqrt{1 - (\Delta u(t))^2})}{\sqrt{1 - (\Delta u(t))^2}\sqrt{1 - (\Delta u(t-1))^2}} \\ &= \nabla(\Delta u(t))\left[\frac{\sqrt{1 - (\Delta u(t-1))^2} + \Delta u(t-1)}{\sqrt{1 - (\Delta u(t))^2}\sqrt{1 - (\Delta u(t-1))^2}}\right] \\ &= \nabla(\Delta u(t))\left[\frac{\sqrt{1 - (\Delta u(t-1))^2}\sqrt{1 - (\Delta u(t))^2} + 1 + \Delta u(t-1)\Delta u(t)}{\sqrt{1 - (\Delta u(t))^2}\sqrt{1 - (\Delta u(t-1))^2}[\sqrt{1 - (\Delta u(t))^2} + \sqrt{1 - (\Delta u(t-1))^2}]}\right]. \end{aligned}$$

□

Lemma 2.6. Assume that g satisfies the condition (H1). Then for any even sign-changing solution u of (1.1),

$$\max_{t \in \mathbb{T}} u(t) \leq s_0 \quad \text{and} \quad \min_{t \in \mathbb{T}} u(t) \geq -s_0.$$

Proof. *Claim.* For all $t \in \hat{\mathbb{T}}$,

$$\nabla(\Delta u(t)) < 0 \quad \text{if } u(t) \in (-\infty, -s_0) \cup (0, s_0); \quad (2.1)$$

$$\nabla(\Delta u(t)) > 0 \quad \text{if } u(t) \in (-s_0, 0) \cup (s_0, +\infty). \quad (2.2)$$

Assume that there exists $\bar{t} \in \mathbb{T}$ such that $u(\bar{t}) \in (-\infty, -s_0) \cup (0, s_0)$ and $\nabla(\Delta u(\bar{t})) \geq 0$. Then

$$-\nabla\left(\frac{\Delta u(\bar{t})}{\sqrt{1 - (\Delta u(\bar{t}))^2}}\right) = \lambda g(\bar{t}, u(\bar{t})) > 0.$$

From Lemma 2.5 and the fact

$$\left[\frac{\sqrt{1 - (\Delta u(\bar{t}-1))^2}\sqrt{1 - (\Delta u(\bar{t}))^2} + 1 + \Delta u(\bar{t}-1)\Delta u(\bar{t})}{\sqrt{1 - (\Delta u(\bar{t}))^2}\sqrt{1 - (\Delta u(\bar{t}-1))^2}[\sqrt{1 - (\Delta u(\bar{t}))^2} + \sqrt{1 - (\Delta u(\bar{t}-1))^2}]}\right] > 0,$$

then

$$\nabla(\Delta u(\bar{t})) < 0.$$

This is a contradiction.

Obviously, (2.2) can be proved by the similar method. Therefore, the claim is proved to be true.

Next, we will show that $\max_{t \in \hat{\mathbb{T}}} u(t) \leq s_0$.

Case 1. $\max_{t \in \hat{\mathbb{T}}} u(t) = u(0)$.

Assume that $u(0) > s_0$. Then from (2.2),

$$\nabla(\Delta u(0)) = u(1) - 2u(0) + u(-1) > 0.$$

Due to u is even, then

$$u(1) - 2u(0) + u(-1) = 2(u(1) - u(0)) > 0.$$

This is a contradiction with $\max_{t \in \hat{\mathbb{T}}} u(t) = u(0)$.

Case 2. $\max_{t \in \hat{\mathbb{T}}} u(t) = u(t_0)$, $t_0 \in \mathbb{T}$.

Assume that $u(t_0) > s_0$. Due to $u(t_0) = \max_{t \in \hat{\mathbb{T}}} u(t)$, then

$$\left(u(t_0 + 1) - u(t_0)\right) + \left(u(t_0 - 1) - u(t_0)\right) = \nabla(\Delta u(t_0)) \leq 0.$$

This is a contradiction with (2.2).

Similarly, $\min_{t \in \hat{\mathbb{T}}} u(t) \geq -s_0$. The proof is completed. \square

Lemma 2.7. Assume that $g(t, \cdot)$ is odd for all $t \in \hat{\mathbb{T}}$, $g(t, s) \geq 0, s \in [0, \infty), t \in \hat{\mathbb{T}}$. Then for any nonconstant solution u of (1.1),

$$\|u\| < T.$$

Proof. *Claim.* u is a solution with the change of sign in $\hat{\mathbb{T}}$.

Suppose on the contrary that $u(t) > 0, t \in \hat{\mathbb{T}}$. Then $g(t, u) \geq 0$ and $\nabla(\Delta u(t)) \leq 0$ for all $t \in \hat{\mathbb{T}}$. This suggests that

$$\Delta u(t) - \Delta u(t-1) \leq 0, \quad t \in \hat{\mathbb{T}},$$

that is $\Delta u(0) \geq \Delta u(t) \geq \Delta u(T)$, $t \in \mathbb{T}$.

By a simple calculation, the boundary conditions in (1.1) are equivalent to the boundary conditions

$$u(0) = u(T), \quad \Delta u(0) = \Delta u(T).$$

Since u is a nonconstant solution that satisfies the boundary condition $\Delta u(0) = \Delta u(T)$, then for any $t \in \mathbb{T}$,

$$\Delta u(0) = \Delta u(t) = \Delta u(T) = c,$$

where $c \in \mathbb{R} \setminus \{0\}$. This contradicts with the boundary conditions $u(0) = u(T)$. Similarly, $u(t) < 0, t \in \hat{\mathbb{T}}$ can derive a contradiction. Therefore, the claim is proved to be true.

Assume that $\max_{t \in \hat{\mathbb{T}}} u(t) = u(t_1)$, $\min_{t \in \hat{\mathbb{T}}} u(t) = u(t_2)$. Then $u(t_2) < 0 < u(t_1)$ and

$$u(t_1) - u(t_2) = \sum_{i=t_2}^{t_1-1} \Delta u(i) \leq \sum_{i=0}^{T-1} |\Delta u(i)| \leq T.$$

Obviously,

$$\begin{aligned} \|u\| &= u(t_1) \leq u(t_2) + T < T \quad \text{if } |u(t_1)| \geq |u(t_2)|, \\ \|u\| &= -u(t_2) \leq T - u(t_1) < T \quad \text{if } |u(t_1)| < |u(t_2)|. \end{aligned}$$

The proof is completed. \square

3. Proof of the main results

Let $\sigma \in (0, 1)$ such that $\lambda\sigma \in (0, \infty)$. Let $H := \{u : \mathbb{Z} \rightarrow \mathbb{R} \mid u \text{ is } T\text{-periodic}\}$, whose norm is denoted by

$$\|u\| := \max_{t \in \hat{\mathbb{T}}} |u(t)|.$$

Define the operator $L : D(L) \rightarrow H$,

$$(Lu)(t) = -\nabla(\Delta u(t)) + \lambda\sigma u(t),$$

where $D(L) = \{u : \mathbb{Z} \rightarrow \mathbb{R} \mid u \text{ satisfies } u(0) - u(T) = u(1) - u(T+1) = 0\}$.

We introduce two subspaces of H which will play important roles in the proofs.

(I) Let E_1 be a subspace of H defined by

$$E_1 = \{u \in H \mid u \text{ satisfies } u(-t) = -u(t), t \in \mathbb{Z}\}. \quad (3.1)$$

For any $t \in \hat{\mathbb{T}}$, E_1 is invariant by $g(t, \cdot)$: let $u \in E_1$ such that $g(t, u) \in H$, then $g(t, u) \in E_1$.

Let L_1 be the linear operator of E_1 defined by

$$\begin{aligned} D(L_1) &= D(L) \cap E_1, \\ L_1 u &= Lu. \end{aligned}$$

The eigenvalue of L_1 are $\lambda_k + \lambda\sigma$, $k = 1, 2, \dots, N-1$, and the eigenfunction corresponding to $\lambda_k + \lambda\sigma$ is ψ_k . E_1 is invariant by L_1 : let $u \in D(L_1) = D(L) \cap E_1$ such that $L_1 u \in H$, then $L_1 u \in E_1$.

(II) Let E_2 be a subspace of H defined by

$$E_2 = \{u \in H \mid u \text{ satisfies } u(-t) = u(t), t \in \mathbb{Z}\}.$$

For any $t \in \hat{\mathbb{T}}$, E_2 is invariant by $g(t, \cdot)$: let $u \in E_2$ such that $g(t, u) \in H$, then $g(t, u) \in E_2$.

Let L_2 be the linear operator of E_2 defined by

$$\begin{aligned} D(L_2) &= D(L) \cap E_2, \\ L_2 u &= Lu. \end{aligned}$$

The eigenvalue of L_2 are $\lambda_k + \lambda\sigma$, $k = 1, 2, \dots, N$, and the eigenfunction corresponding to $\lambda_k + \lambda\sigma$ is φ_k . E_2 is invariant by L_2 : let $u \in D(L_2) = D(L) \cap E_2$ such that $L_2 u \in H$, then $L_2 u \in E_2$.

We define $g^{[n]} : \hat{\mathbb{T}} \times \mathbb{R} \rightarrow \mathbb{R}$ by

$$g^{[n]}(t, s) = \begin{cases} g(t, s), & |s| \in (\frac{1}{n}, \infty), t \in \hat{\mathbb{T}}, \\ ng(t, \frac{1}{n})s, & |s| \in [0, \frac{1}{n}], t \in \hat{\mathbb{T}}. \end{cases}$$

Then $g^{[n]} \in C(\hat{\mathbb{T}} \times \mathbb{R}, \mathbb{R})$ with $g^{[n]}(t, \cdot)$ is odd, and $(g^{[n]})_0 := \lim_{s \rightarrow 0} \frac{g^{[n]}(t, s)}{s} = ng(t, 1/n) > 0$. By (1.6), it follows that $\lim_{n \rightarrow \infty} (g^{[n]})_0 = +\infty$ uniformly in $t \in \hat{\mathbb{T}}$.

Define $q : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ by

$$q(y, z) = \begin{cases} \frac{\sqrt{1-y^2}\sqrt{1-z^2}[\sqrt{1-y^2}+\sqrt{1-z^2}]}{\sqrt{1-z^2}\sqrt{1-y^2+1+zy}}, & |y| < 1, |z| < 1, \\ 0, & \max\{|y|, |z|\} \geq 1. \end{cases} \quad (3.2)$$

From Lemma 2.5, it can be verified that (1.1) is equivalent to

$$\begin{cases} -\nabla(\Delta u(t)) = \lambda g(t, u)q(\Delta u(t), \Delta u(t-1)), & t \in \hat{\mathbb{T}}, \\ u(0) = u(T), \quad u(1) = u(T+1). \end{cases} \quad (3.3)$$

Now let us consider the auxiliary family of the equations

$$\begin{cases} -\nabla(\Delta u(t)) = \lambda g^{[n]}(t, u)q(\Delta u(t), \Delta u(t-1)), & t \in \hat{\mathbb{T}}, \\ u(0) = u(T), \quad u(1) = u(T+1). \end{cases} \quad (3.4)$$

Let $\zeta \in C(\hat{\mathbb{T}} \times \mathbb{R})$ be such that

$$g^{[n]}(t, u) = (g^{[n]})_0 u + \zeta^{[n]}(t, u) = ng(t, 1/n)u + \zeta^{[n]}(t, u).$$

Note that

$$\lim_{|s| \rightarrow 0} \frac{\zeta^{[n]}(t, s)}{s} = 0 \quad (3.5)$$

uniformly for $t \in \hat{\mathbb{T}}$.

Let $\tilde{q}(y, z) = q(y, z) - 1$, $(y, z) \in \mathbb{R}^2$. Because

$$\sqrt{1-x^2} = 1 - x^2 + o(x^2), \quad x \rightarrow 0.$$

From (3.2), a simple calculation would give the following

$$\tilde{q}(y, z) = \frac{-2y^2 - 2z^2 - zy + o(y^2) + o(z^2)}{2 - z^2 - y^2 + zy + o(y^2) + o(z^2)}.$$

Then

$$\lim_{\|\Delta u\| \rightarrow 0} \frac{\tilde{q}(\Delta u(t), \Delta u(t-1))}{\|\Delta u\|} = 0. \quad (3.6)$$

3.1. In the subspace E_1 of H

Let us consider

$$\begin{aligned} (L_1 u)(t) = & \lambda \left((g^{[n]})_0 + \sigma \right) u(t) + \lambda \left[\left((g^{[n]})_0 + \sigma + \frac{\zeta^{[n]}(t, u)}{u} \right) \tilde{q}(\Delta u(t), \Delta u(t-1)) \right. \\ & \left. + \frac{\zeta^{[n]}(t, u)}{u} u(t) \right] \end{aligned} \quad (3.7)$$

as a bifurcation problem from the trivial solution $u \equiv 0$.

Eq. (3.7) can be converted to the equivalent equation

$$\begin{aligned} u(t) &:= \lambda \sum_{i=0}^T G(t, i) \left[\left((g^{[n]})_0 + \sigma \right) u(i) \right. \\ &\quad \left. + \left(((g^{[n]})_0 + \sigma + \frac{\zeta^{[n]}(i, u(i))}{u(i)}) \tilde{q}(\Delta u(i), \Delta u(i-1)) + \frac{\zeta^{[n]}(i, u(i))}{u(i)} \right) u(i) \right] \\ &= \lambda L_1^{-1} \left[\left((g^{[n]})_0 + \sigma \right) u(\cdot) \right] (t) \\ &\quad + \lambda L_1^{-1} \left[\left(((g^{[n]})_0 + \sigma + \frac{\zeta^{[n]}(\cdot, u(\cdot))}{u(\cdot)}) \tilde{q} + \frac{\zeta^{[n]}(\cdot, u(\cdot))}{u(\cdot)} \right) u(\cdot) \right] (t), \end{aligned}$$

where $G(t, i)$ is the Green function of $-\nabla(\Delta u(t)) + \lambda \sigma u(t) = 0$ with the periodic boundary condition.

Define the operator $\mathcal{H}_1 : \mathbb{R} \times \hat{\mathbb{T}} \times E_1 \rightarrow E_1$ by

$$\mathcal{H}_1(\lambda, t, u) = \lambda L_1^{-1} \left(\left(((g^{[n]})_0 + \sigma + \frac{\zeta^{[n]}(t, u)}{u}) \tilde{q} + \frac{\zeta^{[n]}(t, u)}{u} \right) u \right).$$

Obviously, \mathcal{H}_1 is completely continuous. From (3.5) and (3.6), for any $t \in \hat{\mathbb{T}}$,

$$\lim_{\|u\| \rightarrow 0} \frac{\|\mathcal{H}_1(\lambda, t, u)\|}{\|u\|} = 0$$

uniformly in λ of any bounded set.

In what follows, we use the terminology of Rabinowitz [26, 27]. For $k \in \{1, 2, \dots, N-1\}$, let S_k^+ denote the set of functions in E_1 which have exactly $2k-1$ simple generalized zeros in \mathbb{T} and $u(0) = 0, u(1) > 0$. Set $S_k^- = -S_k^+$, and $S_k = S_k^+ \cup S_k^-$. They are disjoint and open in E_1 . Finally, let $\Phi_k^\pm = \mathbb{R} \times S_k^\pm$ and $\Phi_k = \mathbb{R} \times S_k$.

The results of Rabinowitz [26, 27] for (3.7) can be stated as follows: For each integer $k \in \{1, 2, \dots, N-1\}$, $\nu \in \{+, -\}$, there exists a continuum $(\mathcal{C}^{[n]})_k^\nu \subseteq \Phi_k^\nu$ of solutions of (3.7) joining $(\frac{\lambda_k + \lambda\sigma}{(g^{[n]})_0 + \sigma}, 0)$ to infinity in Φ_k^ν . Moreover, $(\mathcal{C}^{[n]})_k^\nu \setminus \{(\frac{\lambda_k + \lambda\sigma}{(g^{[n]})_0 + \sigma}, 0)\} \subset \Phi_k^\nu$.

Proof of Theorem 1.1(i). Let us verify that $\{(\mathcal{C}^{[n]})_k^\nu\}$ satisfies all of the conditions of Lemma 2.3. Since

$$\lim_{n \rightarrow \infty} \frac{\lambda_k + \lambda\sigma}{(g^{[n]})_0 + \sigma} = \lim_{n \rightarrow \infty} \frac{\lambda_k + \lambda\sigma}{ng(t, 1/n) + \sigma} = 0$$

uniformly for $t \in \hat{\mathbb{T}}$. Condition (a) in Lemma 2.3 is satisfied with $z^* = (0, 0)$. Obviously

$$r_n = \sup\{|\lambda| + \|y\| \mid (\lambda, y) \in (\mathcal{C}^{[n]})_k^\nu\} = \infty,$$

and accordingly, (b) holds. (c) can be deduced directly from the Arzela-Ascoli Theorem and the definition of $g^{[n]}$. Therefore, the superior limit of $\{(\mathcal{C}^{[n]})_k^\nu\}$, i.e. \mathcal{D} , contains an unbounded connected component \mathcal{C}_k^ν with $(0, 0) \in \mathcal{C}_k^\nu$.

Let $(\mu_n, u_n) \in \mathcal{C}_k^\nu$ satisfy

$$\mu_n + \|u_n\| \rightarrow \infty.$$

Then $u_n \in E_1$ is odd. From Lemma 2.4, $\|u_n\| < \frac{T}{2}$. Therefore,

$$\sup\{|\lambda| \mid (\lambda, u_n) \in \mathcal{C}_k^\nu\} = \infty.$$

The proof is completed. \square

Proof of Corollary 1.1(i). From the proof of Theorem 1.1(i), we have

$$(\lambda, u) \in \mathcal{C}_k^\nu \subset \Phi_k^\nu \subset \mathbb{R} \times E_1.$$

Then for any $\lambda \in (0, +\infty)$, $k \in \{1, 2, \dots, N-1\}$, $\nu \in \{+, -\}$, (1.1) has odd solutions u_k^ν such that u_k^ν change their sign $2k-1$ times in \mathbb{T} and $u_k^- = -u_k^+$. \square

3.2. In the subspace E_2 of H

Let us consider

$$\begin{aligned} (L_2 v)(t) = & \lambda \left((g^{[n]})_0 + \sigma \right) v(t) + \lambda \left(((g^{[n]})_0 + \sigma + \frac{\zeta^{[n]}(x, v)}{v}) \tilde{q}(\Delta v(t), \Delta v(t-1)) \right. \\ & \left. + \frac{\zeta^{[n]}(x, v)}{v} \right) v(t) \end{aligned} \quad (3.8)$$

as a bifurcation problem from the trivial solution $v \equiv 0$.

For $k \in \{1, 2, \dots, N\}$, let \tilde{S}_k^+ denote the set of functions in E_2 which have exactly $2k$ simple generalized zeros in \mathbb{T} and $v(0) > 0$. Set $\tilde{S}_k^- = -\tilde{S}_k^+$, and $\tilde{S}_k = \tilde{S}_k^+ \cup \tilde{S}_k^-$. They are disjoint and open in E_2 . Finally, let $\Psi_k^\pm = \mathbb{R} \times \tilde{S}_k^\pm$ and $\Psi_k = \mathbb{R} \times \tilde{S}_k$.

Similarly, for each $k \in \{1, 2, \dots, N\}$, $\nu \in \{+, -\}$, there exists a continuum $(\mathcal{D}^{[n]})_k^\nu \subseteq \Psi_k^\nu$ of solutions of (3.8) joining $(\frac{\lambda_k + \lambda\sigma}{(g^{[n]})_0 + \sigma}, 0)$ to infinity in Ψ_k^ν . Moreover, $(\mathcal{D}^{[n]})_k^\nu / \{(\frac{\lambda_k + \lambda\sigma}{(g^{[n]})_0 + \sigma}, 0)\} \subset \Psi_k^\nu$.

Proof of Theorem 1.1(ii). From Lemma 2.3, the superior limit of $\{(\mathcal{D}^{[n]})_k^\nu\}$, i.e. \mathcal{D} , contains an unbounded connected component \mathcal{D}_k^ν with $(0, 0) \in \mathcal{D}_k^\nu$.

Since g satisfies condition (H1) and $v_n \in E_2$ is an even function, then from Lemma 2.6,

$$\max_{t \in \mathbb{T}} v_n(t) \leq s_0 \quad \text{and} \quad \min_{t \in \mathbb{T}} v_n(t) \geq -s_0.$$

That is $\|v_n\| \leq s_0$. Therefore,

$$\sup\{\lambda | (\lambda, v_n) \in \mathcal{D}_k^\nu\} = \infty.$$

The proof is completed. \square

Proof of Theorem 1.1(iii). From Lemma 2.3, the superior limit of $\{(\mathcal{D}^{[n]})_k^\nu\}$, i.e. \mathcal{D} , contains an unbounded connected component \mathcal{D}_k^ν with $(0, 0) \in \mathcal{D}_k^\nu$.

Since g satisfies condition (H2) and $v_n \in \tilde{S}_k^+$ is a nonconstant solution. Then from Lemma 2.7, $\|v_n\| < T$. Therefore,

$$\sup\{\lambda | (\lambda, v_n) \in \mathcal{D}_k^\nu\} = \infty.$$

The proof is completed. \square

Proof of Corollary 1.1(ii). If g satisfies either (H1) or (H2), we can proved $\|v_n\| < \max\{s_0, T\}$. From the proof of Theorem 1.1(ii) and (iii), we have

$$(\lambda, v) \in \mathcal{D}_k^\nu \subset \Psi_k^\nu \subset \mathbb{R} \times E_2.$$

Therefore, for any $\lambda > 0$, $k \in \{1, 2, \dots, N\}$, $\nu \in \{+, -\}$, (1.1) has even solutions v_k^ν such that v_k^ν change their sign $2k$ times in \mathbb{T} and $v_k^- = -v_k^+$. \square

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