

# TRAVELING WAVE SOLUTIONS, POWER SERIES SOLUTIONS AND CONSERVATION LAWS OF THE NONLINEAR DISPERSION EQUATION

Yanzhi Ma<sup>1</sup> and Zenggui Wang<sup>1,†</sup>

**Abstract** In this paper, the nonlinear dispersive equation is investigated by Lie symmetry analysis theory and bifurcation theory. The infinitesimal generators of the equation are obtained by Lie symmetry analysis. Periodic peakon solutions, single period solutions and power series solutions of the equation are acquired. And the conservation laws are obtained by the Ibragimov's method.

**Keywords** Lie symmetry analysis, bifurcation, traveling wave solutions, power series solutions, conservation laws.

**MSC(2010)** 35Q53, 35C07, 35Q92.

## 1. Introduction

In 1993, Rosenau and Hyman [22] investigated the effect of nonlinear dispersion on patterns formation in liquid drops by introducing the following nonlinear dispersion  $K(m, n)$  equation

$$\psi_t + (\psi^m)_x + (\psi^n)_{xxx} = 0. \quad (1.1)$$

Thereafter, many scholars studied the exact solution of Eq. (1.1). In addition to studying Eq. (1.1) and its generalized equations [4, 6, 23], the solution of the following  $K(2, 2)$  equation

$$\psi_t + (\psi^2)_x + (\psi^2)_{xxx} = 0 \quad (1.2)$$

as the classical solution for the  $K(m, n)$  equation also deserves to be studied. In 1998, Ismail and Taha [10] obtained the numerical solution of Eq. (1.2) by the finite element and the finite difference method. Subsequently, in 2002, Wazwaz [24] acquired new soliton solutions of Eq.(1.2) by means of the Adomian decomposition method. In 2007, the Adomian method was optimized in [5, 9]. In [9], by the variational iteration method, the approximate numerical solutions of the  $K(2, 2)$  equation and the compacton solutions with initial conditions were obtained. Domairry [5] investigated the exact numerical solutions of the  $K(2, 2)$  equation by means of the homogeneous perturbation method. The above two methods can get the solutions of Eq. (1.2) without calculating the Adomian polynomial. Zhang and Li [28] gave the implicit loop soliton and periodic solutions of Eq. (1.2) by applying

<sup>†</sup>The corresponding author.

Email: 17860562208@163.com(Y. Ma), wangzenggui@lcu.edu.cn(Z. Wang)

<sup>1</sup>School of Mathematical Sciences, Liaocheng University, Liaocheng 252059, China

dynamical system theory and studied the asymptotic properties of the solutions. Li and Tang [11] used the same method to obtain the implicit analytical and loop solutions of Eq. (1.2) and discussed the convergence of the solutions. Yin and Tian [27] investigated more traveling wave solutions of the following  $K(2, 2)$  equation

$$\psi_t + \alpha(\psi^2)_x + (\psi^2)_{xxx} = 0 \quad (1.3)$$

by the qualitative analysis of Lenells, giving for the first time periodic compact solutions of Eq. (1.3). And they pointed out that the parameter  $\alpha$  has an important influence on the solutions of Eq. (1.3).

Many methods are used to study exact solutions of nonlinear dispersion equation, such as Riemann-Hilbert method [13, 16, 26], bifurcation method [14, 25], Jacobi elliptic function method [21], extend tanh method [2], Lie symmetry method [1, 3, 12] and so on [7, 17–20]. In this paper, explicit periodic peakon solutions, single period solutions and power series solutions of Eq. (1.3) are studied by the Lie symmetry analysis method and the bifurcation method.

This article is structured as follows. Section 2, the generators are obtained by Lie symmetric analysis method. Section 3, we obtained the phase portraits and the explicit traveling wave solutions by using the dynamical system method. Section 4, the power series solutions are constructed and the convergence of the solution is proved. Section 5, it is proven that Eq. (1.3) is nonlinearly self-adjoint and conservation laws [8, 15] are constructed.

## 2. Lie symmetrical analysis

In this section, Lie symmetry analysis is performed to obtain the generators. Eq. (1.3) also be written in the following form

$$\psi_t + \beta\psi\psi_x + 6\psi_x\psi_{xx} + 2\psi\psi_{xxx} = 0. \quad (2.1)$$

Consider the Lie group transformation of Eq. (2.1)

$$\begin{aligned} \tilde{x} &= x + \epsilon\zeta_x(x, t, \psi) + O(\epsilon^2), \\ \tilde{t} &= t + \epsilon\zeta_t(x, t, \psi) + O(\epsilon^2), \\ \tilde{\psi} &= \psi + \varsigma(x, t, \psi) + O(\epsilon^2), \end{aligned} \quad (2.2)$$

in which  $\zeta_x$ ,  $\zeta_t$ ,  $\varsigma$  are infinitesimal generators,  $\epsilon$  is one-parameter. The corresponding vector field is

$$\mathcal{X} = \zeta_x\partial_x + \zeta_t\partial_t + \varsigma\partial_\psi. \quad (2.3)$$

The third-order prolongation of  $\mathcal{X}$  is

$$pr^{(3)}\mathcal{X} = \zeta_x\frac{\partial}{\partial x} + \zeta_t\frac{\partial}{\partial t} + \varsigma\frac{\partial}{\partial\psi} + \varsigma^{xx}\frac{\partial}{\partial\psi_{xx}} + \varsigma^{xxx}\frac{\partial}{\partial\psi_{xxx}}. \quad (2.4)$$

The infinitesimal generators of (2.4) are represented as

$$\begin{aligned} \varsigma^{xx} &= D_{xx}(\varsigma - \zeta_x\psi_x - \zeta_t\psi_t) + \zeta_x\psi_{xxx} + \zeta_t\psi_{xxt}, \\ \varsigma^{xxx} &= D_{xxx}(\varsigma - \zeta_x\psi_x - \zeta_t\psi_t) + \zeta_x\psi_{xxxx} + \zeta_t\psi_{xxx t}. \end{aligned} \quad (2.5)$$

In addition,  $\zeta_x$ ,  $\zeta_t$ ,  $\varsigma$  satisfy the invariance condition

$$pr^{(3)}(\Delta)|_{\Delta=0} = 0, \quad (2.6)$$

where  $\Delta = \psi_t + \beta\psi\psi_x + 6\psi_x\psi_{xx} + 2\psi\psi_{xxx}$ .

Substituting (2.5) into (2.6) yields infinitesimal generators as following form

$$\zeta_x = c_3, \quad \zeta_t = c_1t + c_2, \quad \varsigma = -c_1\psi, \quad (2.7)$$

in which  $c_i$  ( $i=1, 2, 3$ ) are arbitrary constants. Then vector field of Eq. (2.1) is obtained

$$\mathcal{X}_1 = t\frac{\partial}{\partial t} - \psi\frac{\partial}{\partial \psi}, \quad \mathcal{X}_2 = \frac{\partial}{\partial t}, \quad \mathcal{X}_3 = \frac{\partial}{\partial x}. \quad (2.8)$$

Solving the system of equation for an initial value problem with the following form

$$\begin{cases} \frac{d}{d\varepsilon}(x^*, t^*, \psi^*) = w(x^*, t^*, \psi^*), \\ (x^*, t^*, \psi^*)|_{\varepsilon=0} = (x, t, \psi). \end{cases} \quad (2.9)$$

Then we acquire the corresponding invariant groups  $G_{[i]}$  ( $i = 1, 2, 3$ ).

$$\begin{cases} G_{[1]} : (x, t, \psi) \mapsto (x, te^\varepsilon, -\psi e^\varepsilon), \\ G_{[2]} : (x, t, \psi) \mapsto (x, t + \varepsilon, \psi), \\ G_{[3]} : (x, t, \psi) \mapsto (x + \varepsilon, t, \psi). \end{cases}$$

If  $\psi = g(x, t)$  is a solution of Eq. (2.1), then the following functions are also the group-invariant solutions

$$\begin{cases} \psi^{(1)} = e^\varepsilon g(x, te^\varepsilon), \\ \psi^{(2)} = g(x, t - \varepsilon), \\ \psi^{(3)} = g(x - \varepsilon, t). \end{cases}$$

### 3. Traveling wave solutions of Eq. (2.1)

To study the traveling wave solution of the equation, consider the linear combination  $\mathcal{X}_2 + c\mathcal{X}_3$ . For this linear combination, we give the traveling wave transform

$$\xi = x - ct, \quad (3.1)$$

in which  $c$  is the traveling wave speed. Substituting (3.1) into Eq. (2.1), we have

$$-c\psi' + \beta\psi\psi' + 6\psi'\psi'' + 2\psi\psi''' = 0, \quad (3.2)$$

where  $\beta \neq 0$ ,  $c \neq 0$ ,  $\psi' = \frac{d\psi}{d\xi}$ . Integrating Eq. (3.2) we get

$$\frac{1}{2}\beta\psi^2 - c\psi + 2(\psi')^2 + 2\psi\psi'' = k, \quad (3.3)$$

in which  $k$  is a integral constant. Then, letting  $y = \psi'$ , Eq. (3.3) can be written as a singular system of the following form

$$\begin{cases} \frac{d\psi}{d\xi} = y, \\ \frac{dy}{d\xi} = \frac{k - \frac{1}{2}\beta\psi^2 + c\psi - 2y^2}{2\psi}. \end{cases} \quad (3.4)$$

It is obvious that there is a singular line  $\psi = 0$ , so perform the transformation  $d\xi = 2\psi d\rho$ . Eq. (3.4) can be rewritten as

$$\begin{cases} \frac{d\psi}{d\rho} = 2\psi y, \\ \frac{dy}{d\rho} = k - \frac{1}{2}\beta\psi^2 + c\psi - 2y^2, \end{cases} \quad (3.5)$$

with the first integral

$$H(\psi, y) = \psi^2(2y^2 + \frac{1}{4}\beta\psi^2 - \frac{2}{3}c\psi - k) = m, \quad (3.6)$$

in which  $m$  is a Hamiltonian constant.

In order to study the distribution of the equilibrium points of the system (3.5), let

$$f(\psi) = c\psi - \frac{1}{2}\beta\psi^2 + k. \quad (3.7)$$

Thus we can derive

- (i) When  $k = 0$ ,  $f(\psi) = 0$  has two zero points  $\bar{\psi}_1 = 0$ ,  $\bar{\psi}_2 = \frac{c}{\beta}$ ;
- (ii) When  $k = -\frac{c^2}{2\beta}$ ,  $f(\psi) = 0$  has two zero points  $\bar{\psi}_3 = \bar{\psi}_4 = \frac{c}{\beta}$ ;
- (iii) When  $\beta > 0$ ,  $k > -\frac{c^2}{2\beta}$  ( $\beta < 0$ ,  $k < -\frac{c^2}{2\beta}$ ),  $f(\psi) = 0$  has two zero points

$$\bar{\psi}_5 = \frac{c + \sqrt{c^2 + 2\beta k}}{\beta}, \quad \bar{\psi}_6 = \frac{c - \sqrt{c^2 + 2\beta k}}{\beta}.$$

Let  $\mathcal{M}(\bar{\psi}_e, y_e)$  be the coefficient matrix of the system (3.5) at the equilibrium point  $(\bar{\psi}_e, y_e)$ ,

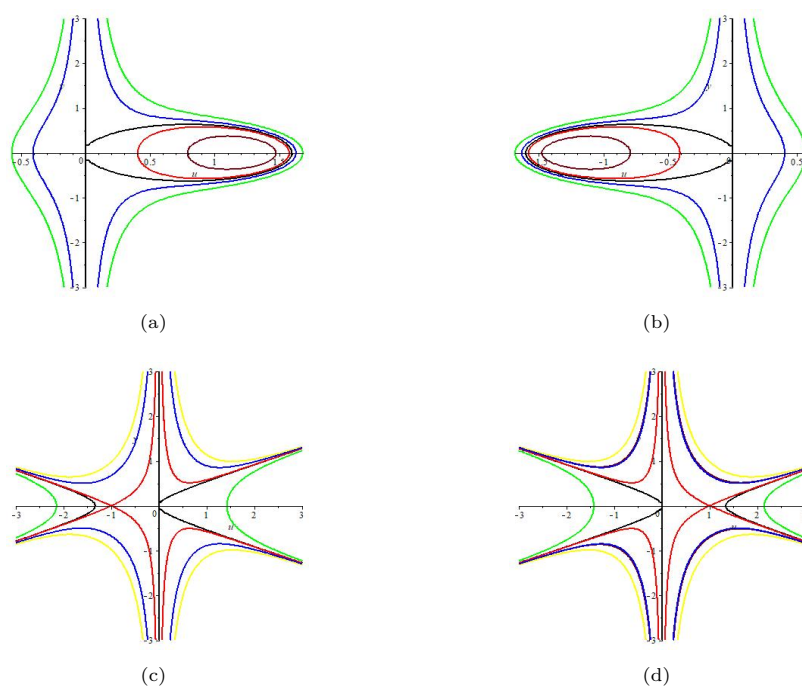
$$\mathcal{M}(\bar{\psi}_e, y_e) = \begin{bmatrix} 2y_e & 2\bar{\psi}_e \\ -\beta\bar{\psi}_e + c & -4y_e \end{bmatrix}. \quad (3.8)$$

This results in the determinant of the coefficient at the point  $(\bar{\psi}_e, 0)$  as

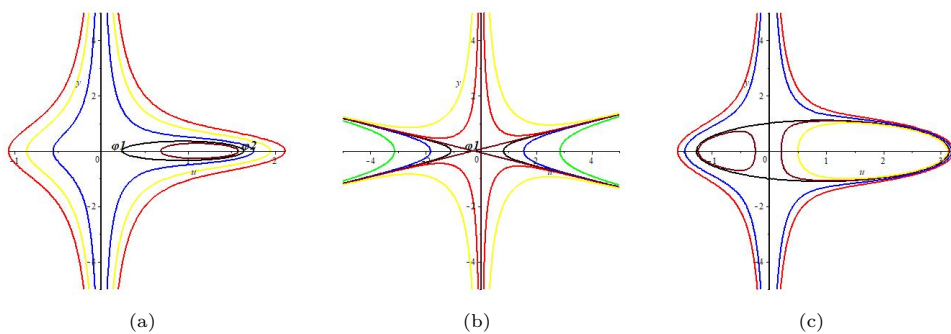
$$\mathcal{J}(\bar{\psi}_e, 0) = \begin{vmatrix} 0 & 2\bar{\psi}_e \\ -\beta\bar{\psi}_e + c & 0 \end{vmatrix} = 2\beta\bar{\psi}_e^2 - 2c\bar{\psi}_e. \quad (3.9)$$

From the dynamical system theory, when  $\mathcal{J} > 0$ ,  $(\bar{\psi}_e, y_e)$  is a central point; when the Poincaré index is 0 and  $\mathcal{J} = 0$ ,  $(\bar{\psi}_e, y_e)$  is a cusp; when  $\mathcal{J} < 0$ ,  $(\bar{\psi}_e, y_e)$  is a saddle point.

In the following, part of phase portraits of the system (3.5) are given.



**Figure 1.** phase portraits of (3.5) for  $k = 0$ . (a)  $c > 0$ ,  $\beta > 0$ ; (b)  $c < 0$ ,  $\beta > 0$ ; (c)  $c > 0$ ,  $\beta < 0$ ; (d)  $c < 0$ ,  $\beta < 0$ .



**Figure 2.** phase portraits of (3.5) for  $k \neq 0$ . (a)  $c > 0$ ,  $\beta > 0$ ,  $-\frac{4c^2}{9\beta} < k < 0$ ; (b)  $\beta < 0$ ,  $c > 0$ ,  $k = -\frac{4c^2}{9\beta}$ ; (c)  $\beta > 0$ ,  $c > 0$ ,  $k > -\frac{4c^2}{9\beta}$ .

In the following, we study the traveling wave solution corresponding to the habit of the  $H(\psi, y) = 0$ . From (3.6), we get

$$y^2 = -\frac{1}{8}\beta\psi^2 + \frac{1}{3}c\psi + \frac{k}{2}. \quad (3.10)$$

Thus, according to (3.4) and (3.10), we have

$$\begin{aligned}\sqrt{\frac{\beta}{8}}\xi &= \int_{\psi_0}^{\psi} \sqrt{\frac{-\psi^4 + \frac{8c}{3\beta}\psi^3 + \frac{4k}{\beta}\psi^2}{\psi^2}} d\psi \\ &= \int_{\psi_0}^{\psi} \sqrt{\frac{\mathcal{K}(\psi)}{\psi^2}} d\psi.\end{aligned}\quad (3.11)$$

**Case 1**  $k = 0$ .

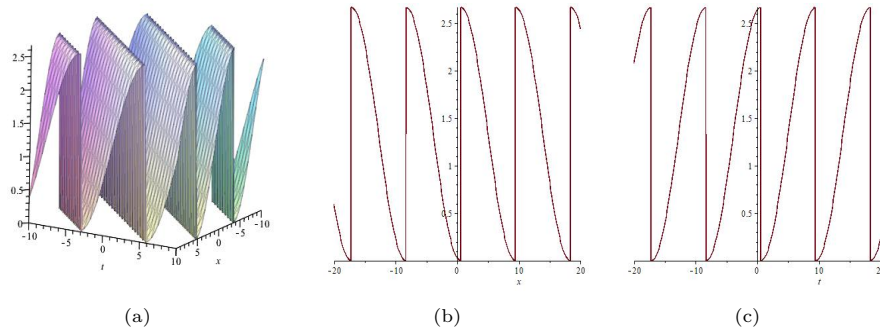
(i) When  $\beta > 0$ ,  $c > 0$  or  $\beta > 0$ ,  $c < 0$  (**Fig.1(a)–(b)**), considering the  $H(\psi, y) = 0$  orbit, it follows that

$$\begin{aligned}y^2 &= -\frac{1}{8}\beta\psi^2 + \frac{1}{3}c\psi \\ &= \frac{1}{8}\beta\psi(\psi_1 - \psi).\end{aligned}\quad (3.12)$$

From  $y = \frac{d\psi}{d\xi}$ , the periodic peakon solution of Eq. (2.1) is obtained

$$\psi(x, t) = \pm \frac{1}{2} \tan\left(\frac{\sqrt{2\beta}}{4}(x - ct)\right) \sqrt{\frac{\psi_1^2}{\tan^2\left(\frac{\sqrt{2\beta}}{4}(x - ct)\right) + 1}} + \frac{1}{2}\psi_1, \quad (3.13)$$

where  $\psi_1 = \frac{8c}{3\beta}$ .



**Figure 3.** (a) The 3D plot of  $\psi$  via (3.13) for  $\beta > 0$ ,  $c > 0$ ; (b) Wave propagation along the  $x$ -axis; (c) Wave propagation along the  $t$ -axis.

(ii) When  $\beta < 0$ ,  $c > 0$  or  $\beta < 0$ ,  $c < 0$  (**Fig.1(c)–(d)**), the orbit determined by  $H(\psi, y) = 0$  yields  $\mathcal{K}(\psi) = \psi^3(\psi - \psi_1)$ ,  $\psi_1 = \frac{8c}{3\beta}$ . Therefore, we get from (3.11) that

$$\sqrt{\frac{\beta}{8}}\xi = \int \sqrt{\frac{\mathcal{K}(\psi)}{\psi^2}} d\psi. \quad (3.14)$$

Thus, we get the solution of Eq. (2.1)

$$\psi(x, t) = \frac{4e^{\delta^2} + 4e^{\delta}\psi_1 + (\psi_1)^2}{8e^{\delta}}, \quad (3.15)$$

in which  $\delta = \frac{\sqrt{2\beta(x-t)}}{4}$ .

**Case 2**  $k \neq 0$

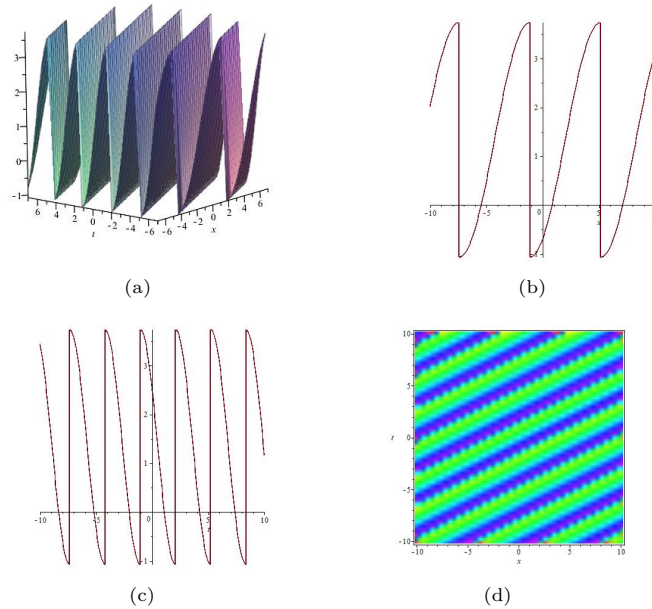
(i) When  $c > 0$ ,  $\beta > 0$ ,  $-\frac{4c^2}{9\beta} < k < 0$  (**Fig.2(a)**), from the orbit defined by  $H(\psi, y) = 0$ , we obtain

$$\frac{\psi d\psi}{\sqrt{\psi^2(\psi - \psi_1)(\psi_2 - \psi)}} = \sqrt{\frac{\beta}{8}} d\xi. \quad (3.16)$$

Integrating the above equation, we have single period wave solution

$$\psi(x, t) = \frac{1}{2}\delta \sqrt{\frac{(\psi_1 - \psi_2)^2}{\delta^2 + 1}} + \frac{1}{2}(\psi_1 + \psi_2), \quad 0 < \psi_1 < \psi < \psi_2, \quad (3.17)$$

where  $\delta = \tan(\frac{\sqrt{2\beta}}{4}(x - ct))$ ,  $\psi_1 = \frac{-2(-2c + \sqrt{9\beta k + 4c^2})}{3\beta}$ ,  $\psi_2 = \frac{2(2c + \sqrt{9\beta k + 4c^2})}{3\beta}$ .



**Figure 4.** (a) The 3D plot of  $\psi$  via (3.17) for  $\beta > 0$ ,  $c > 0$ ; (b) Wave propagation along the x-axis; (c) Wave propagation along the t-axis; (d) Density plot.

(ii) When  $c > 0$ ,  $\beta < 0$ ,  $k = -\frac{4c^2}{9\beta}$  (**Fig.2(b)**), considering the  $H(\psi, y) = 0$  orbit, it follows that

$$\sqrt{\frac{\beta}{8}} \xi = \int_{\psi}^{+\infty} \sqrt{\frac{\psi^2(\psi - \psi_1)^2}{\psi^2}} d\psi, \quad \psi_1 < 0 < \psi. \quad (3.18)$$

Solving Eq. (3.18), we acquire the solution of Eq.(2.1):

$$\psi(x, t) = e^{\delta} + \psi_1, \quad (3.19)$$

where  $\delta = \frac{\sqrt{-2\beta}(x-ct)}{4}$ ,  $\psi_1 = \frac{4c}{3\beta}$ .

(iii) When  $c > 0$ ,  $\beta > 0$ ,  $k > -\frac{4c^2}{9\beta}$  (**Fig.2(c)**), from the orbit defined by  $H(\psi, y) = 0$ , we get

$$\sqrt{\frac{\beta}{8}} d\xi = \frac{\psi d\psi}{\sqrt{\psi^2(\psi - \psi_2)(\psi_1 - \psi)}}, \quad \psi_2 < \psi < 0 < \psi_1. \quad (3.20)$$

Integrating Eq. (3.20), we obtain the periodic solution of Eq. (2.1)

$$\begin{aligned} \psi(x, t) = & -\frac{1}{2} \tan \left( \delta_1 + \arctan(\delta_2) \sqrt{\frac{(\psi_1 - \psi_2)^2}{\tan^2(\delta_1 + \arctan(\delta_2)) + 1}} \right) \\ & + \frac{1}{2} (\psi_1 + \psi_2), \end{aligned} \quad (3.21)$$

where  $\delta_1 = \frac{\sqrt{2\beta}(x-ct)}{4}$ ,  $\delta_2 = \frac{\psi_1 + \psi_2}{2\sqrt{-\psi_1\psi_2}}$ .

## 4. Power series solutions

In this section, we consider linear combinations of generators and reduce Eq. (2.1) to ordinary differential equations by symmetric reduction, thereby constructing power series solutions of Eq. (2.1).

### 4.1. Symmetric reductions

**4.1.1** Considering the linear combination  $\mathcal{X}_1 + \mathcal{X}_2 = (1+t)\frac{\partial}{\partial t} - \psi\frac{\partial}{\partial \psi}$ , the corresponding characteristic equation is

$$\frac{dx}{0} = \frac{dt}{1+t} = \frac{d\psi}{-\psi}. \quad (4.1)$$

Solving Eq. (4.1), we get

$$\psi(x, t) = \frac{\phi(v)}{t+1}, \quad (4.2)$$

where  $v = x$ . Substituting (4.2) into Eq. (2.1), we obtain

$$\beta\phi\phi' + 2\phi\phi''' + 6\phi'\phi'' - \phi = 0. \quad (4.3)$$

**4.1.2** For the linear combination  $\mathcal{X}_1 + \mathcal{X}_3 = \frac{\partial}{\partial x} + t\frac{\partial}{\partial t} - \psi\frac{\partial}{\partial \psi}$ , the corresponding characteristic equation is

$$\frac{dx}{1} = \frac{dt}{t} = \frac{d\psi}{-\psi}. \quad (4.4)$$

Then we get

$$\psi(x, t) = \frac{\phi(v)}{t}, \quad (4.5)$$

in which  $v = \frac{t}{e^x}$ . Substituting (4.5) into Eq. (2.1), we have

$$6\phi'\phi'' + 2\phi\phi''' + 6(\phi')^2 + 6\phi\phi'' + (2+\beta)\phi\phi' - \phi' + \phi = 0. \quad (4.6)$$



## 4.2. Power series solutions

In the following we first consider Eq. (4.3). Suppose that the power series solution of Eq. (4.3) takes the form

$$\phi(v) = \sum_{n=0}^{\infty} q_n v^n, \quad (4.7)$$

in which  $q_n$  are the coefficients to be determined. Substituting (4.7) into Eq. (4.3), we get

$$\begin{aligned} & \beta \sum_{n=0}^{\infty} \sum_{k=0}^n (n+1-k) q_k q_{n+1-k} v^n + 6 \sum_{n=0}^{\infty} \sum_{k=0}^n (k+1)(n-k+1) \\ & \times (n-k+2) v^n q_{k+1} q_{n-k+2} + 2 \sum_{n=0}^{\infty} \sum_{k=0}^n (n+1-k)(n+2-k) \\ & \times (n+3-k) q_k q_{n+3-k} v^n - \sum_{n=0}^{\infty} q_n v^n = 0. \end{aligned} \quad (4.8)$$

Comparing coefficients for Eq. (4.8),  $q_{n+3}$  ( $n \geq 0$ ) is obtained as follows:

$$\begin{aligned} q_{n+3} = & \frac{-1}{2(n+1)(n+2)(n+3)q_0} \left\{ \beta(n+1)q_0q_{n+1} + 6(n+1) \right. \\ & \times (n+2)q_1q_{n+2} - q_n + \sum_{k=1}^n [\beta(n+1-k)q_kq_{n+1-k} \\ & + 6(k+1)(n+1-k)(n+2-k)q_kq_{n+2-k} \\ & \left. + 2 \sum_{k=0}^{\infty} (n+1-k)(n+2-k)(n+3-k)q_kq_{n+3-k}] \right\}. \end{aligned} \quad (4.9)$$

According to (4.8), we get

$$q_3 = \frac{q_0 - \beta q_0 q_1}{12q_0}. \quad (4.10)$$

If  $q_0 \neq 0$  and  $q_1, q_2$  are arbitrary constants,  $q_{n+3}$  are determined by (4.9). In this way, we obtain all the coefficients of (4.7). Next, the convergence of the power series solution (4.7) is proved for Eq. (4.3). According to (4.9), we have following inequality

$$\begin{aligned} |q_{n+3}| \leq & M \left\{ \sum_{k=1}^n [|q_k| |q_{n+1-k}| + (k+1) |q_{k+1}| |q_{n+2-k}| + |q_k| |q_{n+3-k}|] \right. \\ & \left. + |q_n| + |q_{n+1}| + |q_{n+2}| \right\}, \end{aligned} \quad (4.11)$$

where  $M = \max \left\{ \left| \frac{\beta}{2} \right|, \left| \frac{3q_1}{q_0} \right|, \left| \frac{1}{2q_0} \right| \right\}$ .

Defining a power series

$$\mathcal{R} = \mathcal{R}(v) = \sum_{n=0}^{\infty} r_n v^n, r_i = |q_i|, i = 0, 1, 2, \dots, \quad (4.12)$$

and

$$\begin{aligned} r_{n+3} = & M \left\{ \sum_{k=1}^n [(k+1)r_{k+1}r_{n+2-k} + r_k r_{n+1-k} + r_k r_{n+3-k}] \right. \\ & \left. + r_n + r_{n+1} + r_{n+2} \right\}, \end{aligned} \quad (4.13)$$

in which  $n = 0, 1, 2, \dots$ ,  $|q_n| \leq r_n$ . Therefore,  $\mathcal{R} = \mathcal{R}(v) = \sum_{n=0}^{\infty} r_n v^n$  is a majorant series of (4.7). Then, we prove  $\mathcal{R} = \mathcal{R}(v)$  has a positive radius of convergence.

$$\begin{aligned}
 \mathcal{R}(v) &= r_0 + r_1 v + r_2 v^2 + \sum_{n=0}^{\infty} r_{n+3} v^{n+3} \\
 &= r_0 + r_1 v + r_2 v^2 \\
 &\quad + M \left\{ \sum_{n=0}^{\infty} r_n v^{n+3} + \sum_{n=0}^{\infty} r_{n+1} v^{n+3} + \sum_{n=0}^{\infty} r_{n+2} v^{n+3} \right. \\
 &\quad \left. + \sum_{n=0}^{\infty} \sum_{k=1}^n [(k+1) r_{k+1} r_{n+2-k} + r_k r_{n+1-k} + r_k r_{n+2-k}] v^{n+3} \right\} \\
 &= r_0 + r_1 v + r_2 v^2 + M \{ v^3 \mathcal{R} + (\mathcal{R} - r) v^2 + (\mathcal{R} - r_0 - r_1 v) v \\
 &\quad + (\mathcal{R} - r_0 - r_1 v)' (\mathcal{R} - r_0 - r_1 v) v + v(R - r_0)^2 \\
 &\quad + (\mathcal{R} - r_0) (\mathcal{R} - r_0 - r_1 v - r_2 v^2) \}.
 \end{aligned} \tag{4.14}$$

Considering the implicit functional equation about  $v$ ,

$$\begin{aligned}
 F(v, R) &= R - r_0 - r_1 v - r_2 v^2 - M \left[ v^3 R + (R - r_0) v^2 \right. \\
 &\quad \left. + (R - r_0 - r_1 v) v + (R - r_0 - r_1 v)' (R - r_0 - r_1 v) v \right. \\
 &\quad \left. + v(R - r_0)^2 + (R - r_0) (R - r_0 - r_1 v - r_2 v^2) \right].
 \end{aligned} \tag{4.15}$$

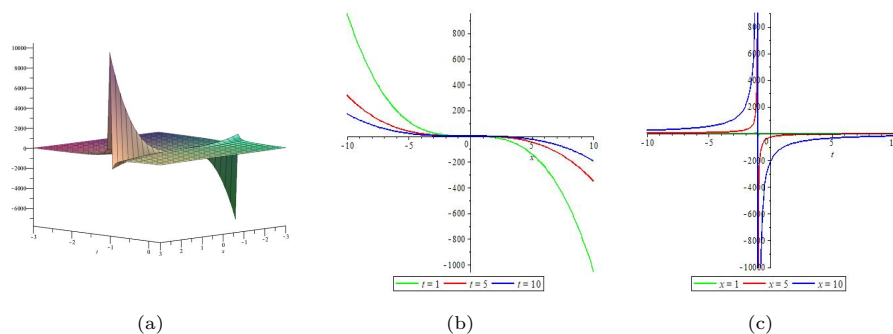
Since  $F(0, r_0) = 0$ ,  $F'_R(0, r_0) = 1 \neq 0$ , by the implicit function theorem, the series (4.7) is convergent.

Hence, the explicit power series solution of Eq. (2.1) is

$$\begin{aligned}
 \psi(x, t) &= \frac{1}{t+1} \left\{ q_0 + q_1 x + q_2 x^2 + \sum_{n=0}^{\infty} \frac{-(x)^{n+3}}{2(n+1)(n+2)(n+3)q_0} \right. \\
 &\quad \left\{ \beta(n+1)q_0 q_{n+1} - q_n + 6(n+1)(n+2)q_1 q_{n+2} \right. \\
 &\quad \left. + \sum_{k=1}^n \left[ 6(k+1)(n-1+k)(n+2-k)q_k q_{n+2-k} \right. \right. \\
 &\quad \left. \left. + \beta(n+1-k)q_k q_{n+1-k} + 2 \sum_{k=0}^{\infty} (n+1-k) \right. \right. \\
 &\quad \left. \left. (n+2-k)(n+3-k)q_k q_{n+3-k} \right] \right\} \Bigg\}.
 \end{aligned} \tag{4.16}$$

Using the same method we acquire the power series solution of Eq. (4.6) as follows

$$\begin{aligned}
 \phi(v) &= q_0 + q_1 v + q_2 v^2 + \sum_{n=0}^{\infty} \frac{v^{n+3}}{2(n+1)(n+2)(n+3)q_0} \left\{ (n+1)q_{n+1} \right. \\
 &\quad \left. - 6(n+1)(n+2)q_1 q_{n+2} - 6(n+1)q_1 q_{n+1} - q_n - 6(n+1)(n+2) \right. \\
 &\quad \left. \times q_0 q_{n+2} - 2(2+\beta)(n+1)q_0 q_{n+1} - \sum_{k=1}^n \left[ 6(k+1)(n-k+1) \right. \right.
 \end{aligned}$$



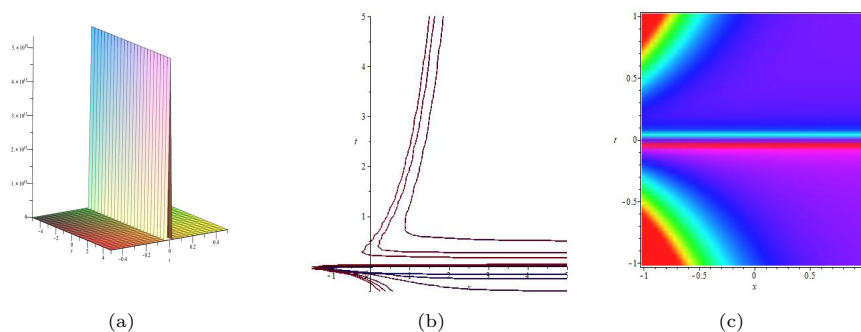
**Figure 5.** (a) The 3D plot of  $\psi$  via (4.16); (b) The plot of  $\psi$  via (4.16) for  $t = 1, t = 5, t = 10$ ; (c) The plot of  $\psi$  via (4.16) for  $x = 1, x = 5, x = 10$ .

$$\begin{aligned} & \times (n - k + 2) q_{k+1} q_{n-k+2} + 2(n - k + 1)(n - k + 2)(n - k + 3) \\ & \times q_k q_{n+3-k} + 6(k + 1)(n - k + 1) q_{k+1} q_{n-k+1} + 6(n - k + 1) \\ & \times (n - k + 2) \times q_k q_{n-k+2} + (2 + \beta)(n + 1 - k) q_k q_{n+1-k} \Big] \Big\}. \end{aligned} \quad (4.17)$$

Substituting (4.17) into (4.5), we have

$$\psi(x, t) = \frac{\phi(v)}{t}, \quad (4.18)$$

in which  $v = \frac{t}{e^x}$ .



**Figure 6.** (a) The 3D plot of  $\psi$  via (4.18); (b) Contour plot ; (c) Density plot.

## 5. Conservation laws

In this section, we give the conservation laws of the  $K(2, 2)$  equation by Ibragimov's method.

Firstly, considering the  $K(2, 2)$  equation

$$\mathcal{F} = \psi_t + \beta \psi \psi_x + 4\psi_x \psi_{xx} + (2\psi \psi_{xx})_x = 0. \quad (5.1)$$

Defining the Lagrangian function of Eq. (5.1)

$$\mathcal{L} = \theta \mathcal{F} = \theta[\psi_t + \beta\psi\psi_x + 4\psi_x\psi_{xx} + (2\psi\psi_{xx})_x], \quad (5.2)$$

where  $\theta(x, t, \psi)$  is dependent variable.

The adjoint equation of Eq. (5.1) has the following form

$$\mathcal{F}^* = \frac{\delta \mathcal{L}}{\delta \psi} = 0, \quad (5.3)$$

in which  $\frac{\delta}{\delta \psi} = \frac{\partial}{\partial \psi} - D_t \left( \frac{\partial}{\partial \psi_t} \right) - D_x \left( \frac{\partial}{\partial \psi_x} \right) + D_x^2 \left( \frac{\partial}{\partial \psi_{xx}} \right) - D_x^3 \left( \frac{\partial}{\partial \psi_{xxx}} \right)$ .

Because  $\theta(2\psi\psi_{xx})_x = (2\theta\psi\psi_{xx})_x - \theta_x(2\psi\psi_{xx})$ , Eq. (5.2) is equivalent to the second-order form

$$\mathcal{L} = \theta\psi_t + \theta\beta\psi\psi_x + 4\theta\psi_x\psi_{xx} - \theta_x(2\psi\psi_{xx}). \quad (5.4)$$

Therefore, the adjoint equation to Eq. (2.1) is

$$\mathcal{F}^* = -\theta_t - \beta\psi\theta_x - 2\psi\theta_{xx}. \quad (5.5)$$

If the adjoint equation satisfies

$$\mathcal{F}^* = \lambda \mathcal{F}, \quad (5.6)$$

in which  $\lambda$  is an undetermined coefficient, solving Eq. (5.6) yields

$$\theta(x, t, \psi) = c_1 + c_2 \sin\left(\frac{\sqrt{2\beta}}{2}x\right) + c_3 \cos\left(\frac{\sqrt{2\beta}}{2}x\right), \quad (5.7)$$

where  $c_1, c_2, c_3$  are arbitrary constants. Therefore, according to [8], Eq. (2.1) is nonlinearly self-adjoint.

Next, we give the definition and theorem related to the conservation laws.

**Definition 5.1.** A vector field  $\mathcal{C}(x, t, \psi, \psi_x, \psi_t, \dots)$  has two components,

$$\mathcal{C} = \mathcal{C}(\mathcal{C}^1, \mathcal{C}^2). \quad (5.8)$$

If each solution  $\psi = \psi(x, t)$  of Eq. (2.1) satisfies

$$D_i(\mathcal{C}^i) = D_t \mathcal{C}^t + D_x \mathcal{C}^x = 0, \quad (5.9)$$

then the vector field  $\mathcal{C}(x, t, \psi, \psi_x, \psi_t, \dots)$  is a conserved vector. Eq. (5.9) is said to be a conservation law of Eq. (2.1).

**Theorem 5.1.** For the generator

$$\mathcal{X} = \zeta_x \frac{\partial}{\partial x} + \zeta_t \frac{\partial}{\partial t} + \varsigma \frac{\partial}{\partial \psi}, \quad (5.10)$$

the conservation law of Eq. (2.1) is expressed as

$$D_x \mathcal{C}^x + D_t \mathcal{C}^t = 0, \quad (5.11)$$

the conserved vector  $\mathcal{C} = \mathcal{C}(\mathcal{C}^x, \mathcal{C}^t)$  is given by

$$\begin{aligned}\mathcal{C}^x &= \zeta_x \mathcal{L} + \mathcal{W} \left( \frac{\partial \mathcal{L}}{\partial \psi_x} - D_x \frac{\partial \mathcal{L}}{\partial \psi_{xx}} + D_{xx} \frac{\partial \mathcal{L}}{\partial \psi_{xxx}} \right) + (D_x \mathcal{W}) \left[ \frac{\partial \mathcal{L}}{\partial \psi_{xx}} \right. \\ &\quad \left. - D_x \left( \frac{\partial \mathcal{L}}{\partial \psi_{xxx}} \right) \right] + (D_{xx} \mathcal{W}) \left( \frac{\partial \mathcal{L}}{\partial \psi_{xxx}} \right), \\ \mathcal{C}^t &= \zeta_t \mathcal{L} + \mathcal{W} \left( \frac{\partial \mathcal{L}}{\partial \psi_t} - D_t \frac{\partial \mathcal{L}}{\partial \psi_{tt}} \right) + (D_t \mathcal{W}) \frac{\partial \mathcal{L}}{\partial \psi_{tt}},\end{aligned}\quad (5.12)$$

in which

$$\begin{aligned}\mathcal{W} &= \varsigma - \zeta_x \psi_x - \zeta_t \psi_t, \\ \mathcal{L} &= \left[ c_1 + c_2 \sin \left( \frac{\sqrt{2\beta}}{2} x \right) + c_3 \cos \left( \frac{\sqrt{2\beta}}{2} x \right) \right] (\psi_t + \beta \psi \psi_x + 6 \psi_x \psi_{xx} + 2 \psi \psi_{xxx}).\end{aligned}$$

Then, by applying **Theorem 5.1** to the conserved vector  $\mathcal{C} = \mathcal{C}(\mathcal{C}^x, \mathcal{C}^t)$ , the conservation laws are obtained.

(I) For the generator  $\chi = t \frac{\partial}{\partial t} - \psi \frac{\partial}{\partial \psi}$ , we have  $\mathcal{W} = -\psi - t\psi_t$ . According to (5.11), we obtain

$$\begin{aligned}\mathcal{C}^x &= \sqrt{2\beta} (t\psi_x \psi_t + \psi \psi_{xt} + 2\psi \psi_x) \left[ c_2 \cos \left( \frac{\sqrt{2\beta}}{2} x \right) - c_3 \sin \left( \frac{\sqrt{2\beta}}{2} x \right) \right] \\ &\quad - 2t (\psi_t \psi_{xx} + 2\psi_x \psi_{xt} + \psi \psi_{xxt}) \left[ c_2 \sin \left( \frac{\sqrt{2\beta}}{2} x \right) + c_3 \cos \left( \frac{\sqrt{2\beta}}{2} x \right) \right] \\ &\quad - 4 (\psi_x^2 + \psi \psi_{xx}) \left[ c_1 + c_2 \sin \left( \frac{\sqrt{2\beta}}{2} x \right) + c_3 \cos \left( \frac{\sqrt{2\beta}}{2} x \right) \right] \\ &\quad - c_1 t (\beta \psi \psi_t + 2\psi_t \psi_{xx} + 4\psi_x \psi_{xt} + 2\psi \psi_{xxt}) - c_1 \beta \psi^2, \\ \mathcal{C}^t &= (2t\psi \psi_{xxx} + 6t\psi_x \psi_{xx} + \beta t\psi \psi_x - \psi) \left[ c_1 + c_2 \sin \left( \frac{\sqrt{2\beta}}{2} x \right) \right. \\ &\quad \left. + c_3 \cos \left( \frac{\sqrt{2\beta}}{2} x \right) \right].\end{aligned}\quad (5.13)$$

(II) For the generator  $\chi = \frac{\partial}{\partial t}$ . From (5.11) we get

$$\begin{aligned}\mathcal{C}^x &= -2 (\psi_t \psi_{xx} + 2\psi_x \psi_{xt} + \psi \psi_{xxt}) \left[ c_1 + c_2 \sin \left( \frac{\sqrt{2\beta}}{2} x \right) \right. \\ &\quad \left. + c_3 \cos \left( \frac{\sqrt{2\beta}}{2} x \right) \right] + \sqrt{2\beta} (\psi_x \psi_t + \psi \psi_{xt}) \left[ c_2 \cos \left( \frac{\sqrt{2\beta}}{2} x \right) \right. \\ &\quad \left. - c_3 \sin \left( \frac{\sqrt{2\beta}}{2} x \right) \right] - c_1 \beta \psi \psi_t, \\ \mathcal{C}^t &= (6t\psi_x \psi_{xx} + 2t\psi \psi_{xxx} + \beta t\psi \psi_x + t\psi_t - \psi_t) \left[ c_1 + c_2 \sin \left( \frac{\sqrt{2\beta}}{2} x \right) \right. \\ &\quad \left. + c_3 \cos \left( \frac{\sqrt{2\beta}}{2} x \right) \right].\end{aligned}\quad (5.14)$$

(III) For the generator  $\chi = \frac{\partial}{\partial x}$ . In the same way as above, we obtain

$$\begin{aligned} C^x &= -2(3\psi_x\psi_{xx} + \psi\psi_{xxx}) \left[ c_1 + c_2 \sin\left(\frac{\sqrt{2\beta}}{2}x\right) + c_3 \cos\left(\frac{\sqrt{2\beta}}{2}x\right) \right] \\ &\quad + \sqrt{2\beta}(\psi_x^2 + \psi\psi_{xx}) \left[ c_2 \cos\left(\frac{\sqrt{2\beta}}{2}x\right) - c_3 \sin\left(\frac{\sqrt{2\beta}}{2}x\right) \right] - c_1\beta\psi\psi_x, \\ C^t &= (t\psi_t + \beta t\psi\psi_x + 6t\psi_x\psi_{xx} + 2t\psi\psi_{xxx} - \psi_x) \left[ c_1 + c_2 \sin\left(\frac{\sqrt{2\beta}}{2}x\right) \right. \\ &\quad \left. + c_3 \cos\left(\frac{\sqrt{2\beta}}{2}x\right) \right]. \end{aligned} \quad (5.15)$$

## 6. Conclusions

In this paper, the nonlinear dispersion equation is considered. We obtain the generators using the Lie symmetry analysis method. Then we give partial phase portraits to obtain exact periodic peakon solutions, single period solutions and other forms of traveling wave solutions. In addition, the analytic power series solutions of the equation are given. Finally, we prove that the equation is nonlinearly self-adjoint and construct the conservation laws.

## Acknowledgement

The authors would like to appreciate the comments and suggestions given by the referees on this work.

## References

- [1] A. R. Adem, *Symbolic computation on exact solutions of a coupled Kadomtsev-Petviashvili equation: Lie symmetry analysis and extended tanh method*, Comput. Math. with Appl., 2017, 74(8), 1897–1902.
- [2] M. A. Abdou, *The extended tanh method and its applications for solving nonlinear physical models*, Appl. Math. Comput., 2007, 190(1), 988–996.
- [3] M. R. Ali, W. Ma and R. Sadat, *Lie Symmetry Analysis and Wave Propagation in Variable-Coefficient Nonlinear Physical Phenomena*, East Asian J. Appl. Math., 2022, 12(1), 201–212.
- [4] A. Biswas, *1-soliton solution of the equation with generalized evolution*, Physics Letters A, 2008, 372(25), 4601–4602.
- [5] G. Domairry, M. Ahangari and M. Jamshidi, *Exact and analytical solution for nonlinear dispersive  $K(m, p)$  equations using homotopy perturbation method*, Physics Letters A, 2007, 368(3-4), 266–270.
- [6] G. Ebadi and A. Biswas, *The  $(G'/G)$  method and topological soliton solution of the  $K(m, n)$  equation*, Commun Nonlinear Sci Numer Simul, 2011, 16(6), 2377–2382.
- [7] Q. Feng and B. Zheng, *Traveling wave solutions for the fifth-order Kdv equation and the BBM equation by  $(G'/G)$ -expansion method*, Wseas Transactions on Mathematics, 2010, 9(3), 171–180.

- [8] B. Gao and Y. Wang, *Invariant Solutions and Nonlinear Self-Adjointness of the Two-Component Chaplygin Gas Equation*, Discrete Dyn Nat Soc, 2019, 2019(6), 1–9.
- [9] M. Inc, *Exact and numerical solitons with compact support for nonlinear dispersive  $K(m, p)$  equations by the variational iteration method*, Physica A, 2007, 375(2), 447–456.
- [10] M. S. Ismail and T. R. Taha, *A numerical study of compactons*, Math Comput Simul, 1998, 47(6), 519–530.
- [11] C. Li, S. Tang and Z. Ma, *Analytic and loop solutions for the  $K(2, 2)$  equation (focusing branch)*, J. Nonlinear Sci. Appl., 2016, 9(3), 1334–1340.
- [12] C. Liu, *A method of Lie-symmetry  $GL(n, R)$  for solving non-linear dynamical systems*, Int J Non Linear Mech, 2013, 52, 85–95.
- [13] S. Li, T. Xia and J. Li,  *$N$ -soliton solutions of the generalized mixed nonlinear Schrödinger equation through the Riemann-Hilbert method*, Modern Physics Letters B, 2022, 36(8), 2150627.
- [14] Z. Li and R. Liu, *Bifurcations and Exact Solutions in a Nonlinear Wave Equation*, Int J Bifurcat Chaos, 2019, 29(7), 1950098.
- [15] W. Ma, *Conservation laws by symmetries and adjoint symmetries*, Discrete Contin Dyn Syst Ser A, 2018, 11, 707–721.
- [16] W. Ma, *Nonlocal  $PT$ -symmetric integrable equations and related Riemann-Hilbert problems*, Commun. Partial. Differ. Equ., 2021, 4, 100190.
- [17] W. Ma, *Binary Darboux transformation for general matrix mKdV equations and reduced counterparts*, Chaos Solitons Fractals, 2021, 146, 110824.
- [18] W. Ma, *Soliton solutions by means of Hirota bilinear forms*, Commun. Partial. Differ. Equ., 2022, 5, 100220.
- [19] W. Ma, *Integrable nonlocal nonlinear Schrödinger equations associated with  $so(3, R)$* , Proceedings of the American Mathematical Society Series B, 2022, 9, 1–11.
- [20] W. Ma, *Reduced Non-Local Integrable NLS Hierarchies by Pairs of Local and Non-Local Constraints*, J. Comput. Appl. Math., 2022, 8, 206.
- [21] E. J. Parkes, B. R. Duffy and P. C. Abbott, *The Jacobi elliptic-function method for finding periodic-wave solutions to nonlinear evolution equations*, Physics Letters A, 2002, 295(s5-6), 280–286.
- [22] P. Rosenau and J. M. Hyman, *Compactons: Solitons with finite wavelength*, Physical Review Letters, 1993, 70(5), 564–567.
- [23] H. Triki and A. M. Wazwaz, *Soliton solutions for  $(2 + 1)$ -dimensional and  $(3 + 1)$ -dimensional  $K(m, n)$  equations*, Appl. Math. Comput., 2010, 217(4), 1733–1740.
- [24] A. M. Wazwaz, *New solitary-wave special solutions with compact support for the nonlinear dispersive  $K(m, n)$  equations*, Chaos Solitons Fractals, 2002, 13(2), 321–330.
- [25] S. Xie, X. Hong and Y. Tan, *Exact Loop Wave Solutions and Cusp Wave Solutions of the Fujimoto-Watanabe Equation*, Journal of Nonlinear Modeling and Analysis, 2022, 4(3), 443–453.

- [26] J. Yang, S. Tian and Z. Li, *Riemann-Hilbert method and multi-soliton solutions of an extended modified Korteweg-de Vries equation with  $N$  distinct arbitrary-order poles*, J. Math. Anal. Appl., 2022, 511(2), 126103.
- [27] J. Yin and L. Tian, *Classification of the travelling waves in the nonlinear dispersive KdV equation*, Nonlinear Analysis, 2010, 73(2), 465–470.
- [28] L. Zhang and J. Li, *Dynamical behavior of loop solutions for the equation*, Physics Letters A, 2011, 375(33), 2965–2968.