

# SOME COMMON FIXED-POINT RESULTS IN GENERALIZED $\mathcal{F}$ -METRIC SPACES

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**Abstract** In this paper, we establish a new common fixed-point theorem for multivalued mappings with the greatest lower bound property in generalized  $\mathcal{F}$ -metric spaces. Also, we propose some new theorems via more general contractions.

**Keywords** Generalized  $\mathcal{F}$ -metric space, multivalued mappings, fixed-point.

**MSC(2010)** 47H10, 54H25, 54D99, 54E99.

## 1. Introduction

In 2013, Ahmad et al. proposed the concept of a complex-valued metric space, and obtained common fixed-point results for multivalued mappings with the greatest lower bound property [3]. As a generalization of the  $b$ -metric spaces [8], the notion of a complex-valued double-controlled metric space was presented in [17]; After that, Amiri et al. have established common fixed-point theorems for multivalued mappings with the greatest lower bound property in this space [6]. Recently, with the establishment of the concept of a  $\mathcal{F}$ -metric space [11], there are also many interesting results appeared. For instance, by using orbital  $\alpha$ -admissibility, Aydi et al. have improved the fixed-point theorem for  $\alpha$ - $\psi$ -contractive mappings [7], or several generalizations of the fixed-point results of Reich and Jungck were given in [15]. Furthermore, numerous authors aim to extend and innovate many known results in the corresponding papers, such as Zhu et al. introduced the concept of a generalized  $\mathcal{F}$ -metric space [20], and proved some fixed-point theorems satisfying Geraghty contraction or JS-contraction, etc, which generalized many fixed-point results in  $\mathcal{F}$ -metric spaces. For more details, see [1, 2, 4, 5, 9, 10, 12–14, 16, 18, 19]. Inspired by the above results, we have some new opinions with generalized  $\mathcal{F}$ -metric space, some examples and corollaries are used to enrich our results, and we apply one of the results to solve a class of linear algebraic equation problems, which satisfies all the conditions of Corollary 3.5.

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## 2. Preliminaries

Firstly, let  $F$  be the family of all functions  $f : (0, +\infty) \rightarrow \mathbb{R}$ , satisfying

- ( $F_1$ ):  $f$  is nondecreasing;  
 ( $F_2$ ):  $\lim_{n \rightarrow \infty} S_n = 0$  if and only if  $\lim_{n \rightarrow \infty} f(S_n) = -\infty$ , where  $\{S_n\} \subseteq (0, +\infty)$ .

**Definition 2.1** ([20]). Let  $X$  be a non-empty set, consider the mapping  $D : X \times X \rightarrow [0, +\infty)$ . For all  $\xi_1, \xi_2, \xi_3$  in  $X$ , suppose that there exist  $(\delta, f) \in [0, +\infty) \times F$ , such that

- ( $D_1$ )  $D(\xi_1, \xi_2) = 0$  if and only if  $\xi_1 = \xi_2$ ;  
 ( $D_2$ )  $D(\xi_1, \xi_2) = D(\xi_2, \xi_1)$ ;  
 ( $D_3$ )  $f(D(\xi_1, \xi_2)) \leq f(D(\xi_1, \xi_3) + D(\xi_3, \xi_2)) + \delta$ , if  $D(\xi_1, \xi_2) > 0$ ,

then the function  $D$  is called a generalized  $\mathcal{F}$ -metric on  $X$ , and  $(X, D)$  is called a generalized  $\mathcal{F}$ -metric space.

**Example 2.1.** Let  $X = \mathbb{R}$ ,  $f(\xi) = -\frac{1}{2\xi}$ ,  $\delta = \frac{1}{2}$ , and

$$D(\xi_1, \xi_2) = \begin{cases} \frac{1}{2}e^{|\xi_1 - \xi_2|}, & \xi_1 \neq \xi_2, \\ 0, & \xi_1 = \xi_2. \end{cases}$$

**Definition 2.2** ([20]). Let  $(X, D)$  be a generalized  $\mathcal{F}$ -metric space and  $\{\xi_n\}$  be a sequence in  $X$ .

- (1) For any  $\epsilon > 0$ , if there exists a positive integer  $N$  such that  $D(\zeta, \xi_n) < \epsilon$  for all  $n \geq N$ , then  $\{\xi_n\}$  is called  $\mathcal{F}$ -convergent to  $\zeta \in X$ ;  
 (2) For any  $\epsilon > 0$ , if there exists a positive integer  $N$  such that  $D(\xi_n, \xi_m) < \epsilon$  for all  $n, m \geq N$ , then  $\{\xi_n\}$  is called a  $\mathcal{F}$ -Cauchy sequence;  
 (3) A generalized  $\mathcal{F}$ -metric space  $(X, D)$  is called  $\mathcal{F}$ -complete if any  $\mathcal{F}$ -Cauchy sequence in  $(X, D)$  is  $\mathcal{F}$ -convergent.

From [3], we investigate the multivalued mappings with the greatest lower bound property in generalized  $\mathcal{F}$ -metric spaces, some similar definitions are given as follows:

**Definition 2.3.** Let  $(X, D)$  be a generalized  $\mathcal{F}$ -metric space and  $NCB(X)$  be the set of non-empty, bounded and closed subsets of  $X$ . For each  $\xi_1$  in  $\mathbb{R}$ , we denote  $\Delta(\xi_1) = \{\xi_2 \in \mathbb{R} : \xi_1 \leq \xi_2\}$ .

In addition, for each  $x \in X$  and  $A, B \in NCB(X)$ ,

- (i)  $\Delta(x, B) = \bigcup_{b \in B} \Delta(D(x, b)) = \bigcup_{b \in B} \{u \in \mathbb{R} : D(x, b) \leq u\}$ ;  
 (ii)  $\Delta(A, B) = (\bigcap_{a \in A} \Delta(a, B)) \cap (\bigcap_{b \in B} \Delta(b, A))$ .

**Definition 2.4.** Let  $(X, D)$  be a generalized  $\mathcal{F}$ -metric space and  $R : X \rightarrow NCB(X)$  be a multi-valued mapping. For all  $x, y \in X$ , define  $A_x(Ry) = \{u \in \mathbb{R} | u = D(x, z) : z \in Ry\}$ .

- (i) The multi-valued mapping  $R$  has the lower bound on  $(X, D)$  if for all  $x, y \in X$  there exists  $u_0 \in \mathbb{R}$  such that  $u_0 \leq u$  for all  $u \in A_x(Ry)$ ;  
 (ii) The multi-valued mapping  $R$  has the greatest lower bound on  $(X, D)$  if there exists a greatest lower bound of  $A_x(Ry)$  in  $\mathbb{R}$ , and we write  $D(x, Ry) = \inf\{D(x, z) : z \in Ry\}$ .

### 3. Main results

In this section, we introduce a new common fixed-point theorem for the multivalued mappings. In addition, we obtain other fixed-point results in this space, which satisfy more general contractive conditions.

In [20], let  $\Phi$  be the set of all functions  $\phi : [0, \infty) \rightarrow [0, \infty)$ , where  $\phi$  satisfies:

- (1) continuous and nondecreasing;
- (2) for any  $t > 0$ ,  $\lim_{n \rightarrow \infty} \phi^n(t) = 0$ .

Obviously,  $\phi(0) = 0$ , and  $\phi(t) < t$  for any  $t > 0$ .

**Theorem 3.1.** *Let  $(X, D)$  be a  $\mathcal{F}$ -complete generalized  $\mathcal{F}$ -metric space and  $R, S : X \rightarrow NCB(X)$  be multi-valued mappings. Suppose that there exists  $\phi \in \Phi$ ,  $R$  and  $S$  have the greatest lower bound on  $(X, D)$  such that*

$$\phi(\theta(x, y)) \in \Delta(Rx, Sy) \quad (3.1)$$

for all  $x, y$  in  $X$ , where  $\theta(x, y) = \frac{\lambda}{a^b} D(x, y) + \frac{\mu}{a^b} \frac{D(x, Rx)D(y, Sy)}{1 + D(x, Rx)}$ ,  $a, b > 1$  and  $\lambda, \mu > 0$  with  $\lambda + \mu < 1$ . Then  $R$  and  $S$  have a common fixed-point.

**Proof.** By selecting any  $x_0 \in X$ , from (3.1), there exists  $x_1 \in Rx_0$  such that

$$\phi(\theta(x_0, x_1)) \in \Delta(Rx_0, Sx_1).$$

Thus for all  $a \in Rx_0, b \in Sx_1$ , we have

$$\phi(\theta(x_0, x_1)) \in \Delta(a, Sx_1) = \bigcup_{b \in Sx_1} \{u \in \mathbb{R} : D(a, b) \leq u\},$$

and

$$\phi(\theta(x_0, x_1)) \in \Delta(Rx_0, b) = \bigcup_{a \in Rx_0} \{u \in \mathbb{R} : D(a, b) \leq u\}.$$

Since  $x_1 \in Rx_0$ , then there exists  $x_2 \in Sx_1$  such that  $D(x_1, x_2) \leq \phi(\theta(x_0, x_1))$ . In addition, by using (3.1), we obtain

$$\phi(\theta(x_2, x_1)) \in \Delta(Rx_2, Sx_1).$$

Similarly, owing to  $x_2 \in Sx_1$ , thus there exists  $x_3 \in Rx_2$  such that  $D(x_2, x_3) \leq \phi(\theta(x_2, x_1))$ . By repeating the above process, we can construct a sequence  $\{x_n\}$ , where  $x_{2n+1} \in Rx_{2n}$ ,  $x_{2n+2} \in Sx_{2n+1}$  for all  $n \in \mathbb{N}$ , thus we have

$$D(x_{2n+1}, x_{2n+2}) \leq \phi(\theta(x_{2n}, x_{2n+1})), \quad (3.2)$$

and

$$D(x_{2n+2}, x_{2n+3}) \leq \phi(\theta(x_{2n+2}, x_{2n+1})), \quad (3.3)$$

where

$$\theta(x_{2n}, x_{2n+1}) = \frac{\lambda}{a^b} D(x_{2n}, x_{2n+1}) + \frac{\mu}{a^b} \frac{D(x_{2n}, Rx_{2n})D(x_{2n+1}, Sx_{2n+1})}{1 + D(x_{2n}, Rx_{2n})}, \quad (3.4)$$

and

$$\theta(x_{2n+2}, x_{2n+1}) = \frac{\lambda}{a^b} D(x_{2n+2}, x_{2n+1}) + \frac{\mu}{a^b} \frac{D(x_{2n+2}, Rx_{2n+2})D(x_{2n+1}, Sx_{2n+1})}{1 + D(x_{2n+2}, Rx_{2n+2})}. \quad (3.5)$$

Suppose that there exists  $n \in \mathbb{N}$  such that  $x_{2n} = x_{2n+1}$ , it can be proved that  $x_{2n+1} = x_{2n+2}$ . If not, consider Definition 2.2, we have

$$\begin{aligned} 0 &< D(x_{2n+1}, x_{2n+2}) \\ &\leq \phi(\theta(x_{2n}, x_{2n+1})) \\ &\leq \phi\left(\frac{\mu}{a^b} D(x_{2n+1}, Sx_{2n+1})\right) \\ &< \frac{\mu}{a^b} D(x_{2n+1}, x_{2n+2}), \end{aligned}$$

contradiction. As a result,  $x_{2n+1}$  is a common fixed-point of  $R$  and  $S$ .

On the other hand, if  $x_{2n+1} = x_{2n+2}$  for some  $n \in \mathbb{N}$ , then  $x_{2n+2} = x_{2n+3}$  and  $x_{2n+2}$  is a common fixed-point of  $R$  and  $S$ . If not, it can be deduced that

$$\begin{aligned} 0 &< D(x_{2n+2}, x_{2n+3}) \\ &\leq \phi(\theta(x_{2n+2}, x_{2n+1})) \\ &\leq \phi\left(\frac{\mu}{a^b} D(x_{2n+1}, Sx_{2n+1})\right) \\ &< \frac{\mu}{a^b} D(x_{2n+1}, x_{2n+2}) \\ &= 0. \end{aligned}$$

Therefore, we assume that  $x_n \neq x_{n+1}$  for all  $n \in \mathbb{N}$ . By using (3.2) and (3.4), we have

$$\begin{aligned} D(x_{2n+1}, x_{2n+2}) &\leq \phi(\theta(x_{2n}, x_{2n+1})) \\ &\leq \phi\left(\frac{\lambda}{a^b} D(x_{2n}, x_{2n+1}) + \frac{\mu}{a^b} D(x_{2n+1}, Sx_{2n+1})\right) \\ &< \frac{\lambda}{a^b} D(x_{2n}, x_{2n+1}) + \frac{\mu}{a^b} D(x_{2n+1}, x_{2n+2}), \end{aligned}$$

and so  $D(x_{2n+1}, x_{2n+2}) < \frac{\lambda}{a^b - \mu} D(x_{2n}, x_{2n+1})$ , where  $0 < \frac{\lambda}{a^b - \mu} < 1$ .

Similarly, using (3.3) and (3.5), we obtain

$$\begin{aligned} D(x_{2n+2}, x_{2n+3}) &\leq \phi(\theta(x_{2n+2}, x_{2n+1})) \\ &\leq \phi\left(\frac{\lambda}{a^b} D(x_{2n+2}, x_{2n+1}) + \frac{\mu}{a^b} D(x_{2n+1}, Sx_{2n+1})\right) \\ &< \frac{\lambda}{a^b} D(x_{2n+2}, x_{2n+1}) + \frac{\mu}{a^b} D(x_{2n+1}, x_{2n+2}), \end{aligned}$$

thus  $D(x_{2n+2}, x_{2n+3}) < \frac{\lambda + \mu}{a^b} D(x_{2n+1}, x_{2n+2})$ , where  $0 < \frac{\lambda + \mu}{a^b} < 1$ .

As a consequence,  $D(x_n, x_{n+1}) < \frac{\lambda + \mu}{a^b} D(x_{n-1}, x_n)$ . Then,

$$D(x_n, x_{n+1}) < \frac{\lambda + \mu}{a^b} D(x_{n-1}, x_n) < \dots < \left\{ \frac{\lambda + \mu}{a^b} \right\}^n D(x_0, x_1),$$

it follows that

$$\lim_{n \rightarrow \infty} D(x_n, x_{n+1}) = 0. \quad (3.6)$$

Now, it will be shown that  $\{x_n\}$  is a  $\mathcal{F}$ -Cauchy sequence. According to mathematical induction, suppose that  $\lim_{n \rightarrow \infty} D(x_n, x_{n+k}) = 0$  for some  $k \in \mathbb{N}$ , consider  $(D_3)$ , we have

$$f(D(x_n, x_{n+k+1})) \leq f(D(x_n, x_{n+k}) + D(x_{n+k}, x_{n+k+1})) + \delta.$$

From (3.6), we can get  $\lim_{n \rightarrow \infty} D(x_n, x_{n+k}) + D(x_{n+k}, x_{n+k+1}) = 0$ . Moreover, according to  $(F_2)$ , we obtain

$$\lim_{n \rightarrow \infty} f(D(x_n, x_{n+k+1})) \leq \lim_{n \rightarrow \infty} f(D(x_n, x_{n+k}) + D(x_{n+k}, x_{n+k+1})) + \delta \leq -\infty,$$

hence,

$$\lim_{n \rightarrow \infty} D(x_n, x_{n+k+1}) = 0.$$

As a result,  $\lim_{n \rightarrow \infty} D(x_n, x_{n+k}) = 0$  for all  $k \in \mathbb{N}$ , thus  $\{x_n\}$  is a  $\mathcal{F}$ -Cauchy sequence and there exists an element  $\beta$  in  $X$  such that  $x_n \rightarrow \beta$ .

Finally, we will prove  $\beta$  is a common fixed-point of  $R$  and  $S$ . From (3.1), we obtain

$$\phi(\theta(x_{2n}, \beta)) \in \Delta(Rx_{2n}, S\beta) \subseteq \Delta(x_{2n+1}, S\beta),$$

and

$$\phi(\theta(\beta, x_{2n+1})) \in \Delta(R\beta, Sx_{2n+1}) \subseteq \Delta(R\beta, x_{2n+2}),$$

where

$$\theta(x_{2n}, \beta) = \frac{\lambda}{a^b} D(x_{2n}, \beta) + \frac{\mu}{a^b} \frac{D(x_{2n}, Rx_{2n})D(\beta, S\beta)}{1 + D(x_{2n}, Rx_{2n})},$$

and

$$\theta(\beta, x_{2n+1}) = \frac{\lambda}{a^b} D(\beta, x_{2n+1}) + \frac{\mu}{a^b} \frac{D(\beta, R\beta)D(x_{2n+1}, Sx_{2n+1})}{1 + D(\beta, R\beta)}.$$

Therefore, there exist two sequences  $\{u_n\} \subseteq R\beta$  and  $\{v_n\} \subseteq S\beta$ , such that

$$D(x_{2n+1}, v_n) \leq \phi\left(\frac{\lambda}{a^b} D(x_{2n}, \beta) + \frac{\mu}{a^b} \frac{D(x_{2n}, Rx_{2n})D(\beta, S\beta)}{1 + D(x_{2n}, Rx_{2n})}\right),$$

and

$$D(u_n, x_{2n+2}) \leq \phi\left(\frac{\lambda}{a^b} D(\beta, x_{2n+1}) + \frac{\mu}{a^b} \frac{D(x_{2n+1}, Sx_{2n+1})D(\beta, R\beta)}{1 + D(\beta, R\beta)}\right).$$

It follows that

$$\lim_{n \rightarrow \infty} D(x_{2n+1}, v_n) \leq \lim_{n \rightarrow \infty} \phi\left(\frac{\lambda}{a^b} D(x_{2n}, \beta) + \frac{\mu}{a^b} \frac{D(x_{2n}, Rx_{2n})D(\beta, S\beta)}{1 + D(x_{2n}, Rx_{2n})}\right) = \phi(0) = 0,$$

and

$$\begin{aligned} \lim_{n \rightarrow \infty} D(u_n, x_{2n+2}) &\leq \lim_{n \rightarrow \infty} \phi\left(\frac{\lambda}{a^b} D(\beta, x_{2n+1}) + \frac{\mu}{a^b} \frac{D(x_{2n+1}, Sx_{2n+1})D(\beta, R\beta)}{1 + D(\beta, R\beta)}\right) \\ &= \phi(0) \\ &= 0, \end{aligned}$$

i.e.

$$\lim_{n \rightarrow \infty} D(x_{2n+1}, v_n) = 0, \quad (3.7)$$

and

$$\lim_{n \rightarrow \infty} D(u_n, x_{2n+2}) = 0. \quad (3.8)$$

According to  $(D_3)$ , we have

$$f(D(\beta, v_n)) \leq f(D(\beta, x_{2n+1}) + D(x_{2n+1}, v_n)) + \delta,$$

from (3.7), we get  $\lim_{n \rightarrow \infty} f(D(\beta, v_n)) \leq \lim_{n \rightarrow \infty} f(D(\beta, x_{2n+1}) + D(x_{2n+1}, v_n)) + \delta \leq -\infty$ , then

$$\lim_{n \rightarrow \infty} D(\beta, v_n) = 0,$$

i.e.  $v_n \rightarrow \beta$ .

Similarly,

$$f(D(u_n, \beta)) \leq f(D(u_n, x_{2n+2}) + D(x_{2n+2}, \beta)) + \delta,$$

from (3.8), we get

$$\lim_{n \rightarrow \infty} D(u_n, \beta) = 0,$$

i.e.  $u_n \rightarrow \beta$ .

Owing to  $R\beta$  and  $S\beta$  are closed subsets, it follows that  $\beta \in (R\beta \cap S\beta)$ , thus the proof is completed.  $\square$

**Example 3.1.** Let  $X = [0, 1]$ ,  $D(\xi_1, \xi_2) = (\xi_1 - \xi_2)^2$  for all  $\xi_1, \xi_2$  in  $X$ ,  $f(x) = \ln x$  and  $\delta = \ln 2$ .

In addition, let  $R\xi_1 = [0, \frac{\xi_1}{10}]$ ,  $S\xi_2 = [0, \frac{\xi_2}{20}]$ ,  $\phi(\xi) = \frac{\xi}{2}$ ,  $a = \sqrt{2}$ ,  $b = 2$  and  $\lambda = \mu = \frac{1}{100}$ . Anyone can easily check that  $D(\xi_1, R\xi_1) = \frac{81}{100}\xi_1^2$ ,  $D(\xi_2, S\xi_2) = \frac{361}{400}\xi_2^2$  and  $\Delta(R\xi_1, S\xi_2) = \Delta((\frac{\xi_1}{10} - \frac{\xi_2}{20})^2)$ .

Suppose that  $2\xi_1 < \xi_2$ , we have

$$\begin{aligned} (\frac{\xi_1}{10} - \frac{\xi_2}{20})^2 &\leq \frac{1}{400}(\xi_1 - \xi_2)^2 \\ &\leq \frac{1}{400}(\xi_1 - \xi_2)^2 + \frac{1}{400} \frac{\frac{81}{100}\xi_1^2}{1 + \frac{81}{100}\xi_1^2} \frac{361}{400}\xi_2^2 \\ &= \frac{1}{2} \left( \frac{\frac{1}{100}}{(\sqrt{2})^2} D(\xi_1, \xi_2) + \frac{\frac{1}{100}}{(\sqrt{2})^2} \frac{D(\xi_1, R\xi_1)}{1 + D(\xi_1, R\xi_1)} D(\xi_2, S\xi_2) \right) \\ &= \phi(\theta(\xi_1, \xi_2)), \end{aligned}$$

then  $\phi(\theta(\xi_1, \xi_2)) \in \Delta(R\xi_1, S\xi_2)$ .

Therefore, the conditions of Theorem 3.1 are satisfied,  $R$  and  $S$  have a common fixed-point  $\xi = 0$ .

If two multi-valued mappings  $R$  and  $S$  are supposed to be equal, then Theorem 3.1 reduces to below corollary.

**Corollary 3.1.** Let  $(X, D)$  be a  $\mathcal{F}$ -complete generalized  $\mathcal{F}$ -metric space and  $R : X \rightarrow NCB(X)$  be a multi-valued mapping. Suppose that there exists  $\phi \in \Phi$ , and  $R$  has the greatest lower bound on  $(X, D)$ , such that

$$\phi(\theta(x, y)) \in \Delta(Rx, Ry)$$

for all  $x, y$  in  $X$ , where  $\theta(x, y) = \frac{\lambda}{a^b} D(x, y) + \frac{\mu}{a^b} \frac{D(x, Rx)D(y, Ry)}{1 + D(x, Rx)}$ ,  $a, b > 1$  and  $\lambda, \mu > 0$  with  $\lambda + \mu < 1$ . Then  $R$  has a fixed-point.

Obviously, if two multi-valued mappings  $R$  and  $S$  are supposed to be self-mappings, then the following corollary holds.

**Corollary 3.2.** Let  $(X, D)$  be a  $\mathcal{F}$ -complete generalized  $\mathcal{F}$ -metric space and  $R, S : X \rightarrow X$  be self-mappings. Suppose that there exists  $\phi \in \Phi$  such that

$$D(Rx, Sy) \leq \phi(\theta(x, y))$$

for all  $x, y$  in  $X$ , where  $\theta(x, y) = \frac{\lambda}{a^b} D(x, y) + \frac{\mu}{a^b} \frac{D(x, Rx)D(y, Sy)}{1 + D(x, Rx)}$ ,  $a, b > 1$  and  $\lambda, \mu > 0$  with  $\lambda + \mu < 1$ . Then  $R$  and  $S$  have a common fixed-point.

In [12], let  $L$  be the family of all continuous and nondecreasing functions  $\omega : [0, +\infty) \rightarrow [0, +\infty)$ , where  $\omega$  satisfies:

- (1)  $\omega(0) = 0$ , and  $\omega(x) > 0$  for each  $x > 0$ ;
- (2)  $\lim_{n \rightarrow \infty} x_n = 0$  if and only if  $\lim_{n \rightarrow \infty} \omega(x_n) = 0$ , where  $\{x_n\} \subseteq (0, +\infty)$ .

**Theorem 3.2.** Let  $(X, D)$  be a  $\mathcal{F}$ -complete generalized  $\mathcal{F}$ -metric space and  $R, S : X \rightarrow X$  be self-mappings. Suppose that there exists  $\omega \in L$  such that

$$D(Rx, Sy) \leq M(x, y) - \omega(M(x, y)) \quad (3.9)$$

for all  $x, y$  in  $X$ , where

$$M(x, y) = \max\{D(x, Rx), D(y, Sy), D(x, y)\}.$$

Then  $R$  and  $S$  have a unique common fixed-point.

**Proof.** By selecting any  $x_0 \in X$ , we can construct a sequence  $\{x_n\}$  such that  $x_{2n+1} = Rx_{2n}$  and  $x_{2n+2} = Sx_{2n+1}$ . If  $x_{2n} = x_{2n+1}$  for some  $n \in \mathbb{N}$ , then  $x_{2n+1} = x_{2n+2}$ , and so  $x_{2n+1}$  is a common fixed-point of  $R$  and  $S$ .

In fact, if  $x_{2n+1} \neq x_{2n+2}$ , from (3.9), we have

$$D(x_{2n+1}, x_{2n+2}) = D(Rx_{2n}, Sx_{2n+1}) \leq M(x_{2n}, x_{2n+1}) - \omega(M(x_{2n}, x_{2n+1})),$$

where

$$\begin{aligned} M(x_{2n}, x_{2n+1}) &= \max\{D(x_{2n}, x_{2n+1}), D(x_{2n+1}, x_{2n+2}), D(x_{2n}, x_{2n+1})\} \\ &= D(x_{2n+1}, x_{2n+2}). \end{aligned}$$

It follows that

$$0 < D(x_{2n+1}, x_{2n+2}) \leq D(x_{2n+1}, x_{2n+2}) - \omega(D(x_{2n+1}, x_{2n+2})) < D(x_{2n+1}, x_{2n+2}),$$

contradiction. Similarly, if  $x_{2n+1} = x_{2n+2}$  for some  $n \in \mathbb{N}$  and  $x_{2n+2} \neq x_{2n+3}$ , then

$$\begin{aligned} D(x_{2n+2}, x_{2n+3}) &= D(x_{2n+3}, x_{2n+2}) \\ &= D(Rx_{2n+2}, Sx_{2n+1}) \\ &\leq M(x_{2n+2}, x_{2n+1}) - \omega(M(x_{2n+2}, x_{2n+1})), \end{aligned}$$

where

$$\begin{aligned} M(x_{2n+2}, x_{2n+1}) &= \max\{D(x_{2n+2}, x_{2n+3}), D(x_{2n+1}, x_{2n+2}), D(x_{2n+2}, x_{2n+1})\} \\ &= D(x_{2n+2}, x_{2n+3}). \end{aligned}$$

So we have

$$0 < D(x_{2n+2}, x_{2n+3}) \leq D(x_{2n+2}, x_{2n+3}) - \omega(D(x_{2n+2}, x_{2n+3})) < D(x_{2n+2}, x_{2n+3}),$$

contradiction, thus we get  $x_{2n+2} = x_{2n+3}$ , and  $x_{2n+2}$  is a common fixed-point of  $R$  and  $S$ .

As a consequence, we suppose that  $x_n \neq x_{n+1}$  for all  $n \in \mathbb{N}$ , and it can be easily deduced that

$$D(x_{2n+1}, x_{2n+2}) \leq D(x_{2n}, x_{2n+1}), \quad (3.10)$$

and

$$D(x_{2n+2}, x_{2n+3}) \leq D(x_{2n+1}, x_{2n+2}). \quad (3.11)$$

Owing to (3.10) and (3.11), we obtain  $D(x_n, x_{n+1}) \leq D(x_{n-1}, x_n)$  for all  $n \in \mathbb{N}$ . Moreover,  $\{D(x_n, x_{n+1})\}$  is a monotonous nonincreasing sequence and we assume that  $\lim_{n \rightarrow \infty} D(x_n, x_{n+1}) = e \geq 0$ .

If  $e > 0$ , so by letting  $n \rightarrow \infty$  at both sides of (3.10) and (3.11), we get

$$e < e - \omega(e) < e,$$

contradiction. It can be easily shown that  $\lim_{n \rightarrow \infty} D(x_n, x_{n+1}) = 0$ , following the proof process of Theorem 3.1, we get  $\{x_n\}$  is a  $\mathcal{F}$ -Cauchy sequence and there exists an element  $\beta$  in  $X$  such that  $x_n \rightarrow \beta$ .

Now, we will prove  $\beta$  is a unique common fixed-point of  $R$  and  $S$ . If  $\beta \neq R\beta$ , then

$$\begin{aligned} 0 &< \inf\{D(x, \beta) + D(x, Rx) : x \in X\} \\ &\leq \inf\{D(x_{2n}, \beta) + D(x_{2n}, Rx_{2n}) : n \in \mathbb{N}\} \\ &\leq 0 \text{ as } n \rightarrow \infty, \end{aligned}$$

contradiction, thus  $\beta = R\beta$ .

Uniqueness: Suppose that  $\beta$  and  $\eta$  are two common fixed-points of  $R$  and  $S$ ,  $\beta \neq \eta$ , so that

$$0 < D(\beta, \eta) = D(R\beta, S\eta) \leq M(\beta, \eta) - \omega(M(\beta, \eta)),$$

where

$$M(\beta, \eta) = \max\{D(\beta, R\beta), D(\eta, S\eta), D(\beta, \eta)\} = D(\beta, \eta).$$

Hence,

$$0 < D(\beta, \eta) \leq D(\beta, \eta) - \omega(D(\beta, \eta)) < D(\beta, \eta),$$

contradiction.

It follows that  $D(\beta, \eta) = 0$ , i.e.  $\beta = \eta$ , the proof is completed.  $\square$

**Example 3.2.** Let  $X = \mathbb{R}$ , for all  $x, y$  in  $\mathbb{R}$ ,  $Rx = \frac{(x-1)}{4} + x$ ,  $Sy = \frac{(y-1)}{4} + 1$ , and  $\omega(t) = 1 - \frac{1}{e^t}$  for all  $t \geq 0$ .

Furthermore, let  $f(t) = -\frac{1}{t}$ ,  $\delta = 1$ , and

$$D(x, y) = \begin{cases} e^{|x-y|}, & x \neq y, \\ 0, & x = y. \end{cases}$$

It can be proved that  $(X, D)$  is a generalized  $\mathcal{F}$ -metric space (see [11]), and

$$D(Rx, Sy) = \begin{cases} e^{|\frac{x-y}{4} + x - 1|}, & Rx \neq Sy, \\ 0, & Rx = Sy. \end{cases}$$



Suppose that  $2 \leq 4|x - 1| \leq |x - y|$ , we have

$$e^{\left|\frac{x-y}{4} + x - 1\right|} \leq e^{\frac{|x-y|}{2}},$$

and

$$e^{\frac{|x-y|}{2}} + 1 \leq e^{|x-y|}.$$

Thus,

$$D(Rx, Sy) \leq D(x, y) - \omega(M(x, y)) \leq M(x, y) - \omega(M(x, y)),$$

where  $M(x, y) = \max\{D(x, Rx), D(y, Sy), D(x, y)\}$ .

Obviously, the conditions of Theorem 3.2 are satisfied,  $R$  and  $S$  have a unique common fixed-point  $\xi = 1$ .

It is clear that if  $R$  and  $S$  be equal, then Theorem 3.2 reduces to the following corollary.

**Corollary 3.3.** *Let  $(X, D)$  be a  $\mathcal{F}$ -complete generalized  $\mathcal{F}$ -metric space and  $R : X \rightarrow X$  be a self-mapping. Suppose that there exist  $\phi \in \Phi$  and  $\omega \in L$ , such that*

$$D(Rx, Ry) \leq \phi(M(x, y)) - \omega(M(x, y))$$

for all  $x, y$  in  $X$ , where

$$M(x, y) = \max\{D(x, Rx), D(y, Sy), D(x, y)\}.$$

Then  $R$  has a unique fixed-point.

**Theorem 3.3.** *Let  $(X, D)$  be a  $\mathcal{F}$ -complete generalized  $\mathcal{F}$ -metric space  $R, S : X \rightarrow X$  be nondecreasing mappings. Suppose that there exists a continuous and nonincreasing mapping  $T : X \rightarrow [0, 1)$ , such that*

$$D(Rx, Sy) \leq (Tx - Ty)M(x, y) \tag{3.12}$$

for all  $x, y$  in  $X$ , where

$$M(x, y) = \max\{D(x, y), D(x, Rx), D(y, Sy)\}.$$

If  $f \in F$  is an invertible function, then  $R$  and  $S$  have a unique common fixed-point.

**Proof.** By selecting any  $x_0 \in X$ , according to the property of  $R$  and  $S$ , we can construct a nondecreasing sequence  $\{x_n\}$ , such that  $x_{2n+1} = Rx_{2n} \geq x_{2n}$  and  $x_{2n+2} = Sx_{2n+1} \geq x_{2n+1}$  for all  $n \in \mathbb{N}$ . Inspired by the proof process of Theorem 3.1 and Theorem 3.2, we also assume that  $x_n \neq x_{n+1}$  for all  $n \in \mathbb{N}$ . From (3.12), we get

$$D(x_{2n+1}, x_{2n+2}) = D(Rx_{2n}, Sx_{2n+1}) \leq (Tx_{2n} - Tx_{2n+1})M(x_{2n}, x_{2n+1}),$$

where

$$\begin{aligned} M(x_{2n}, x_{2n+1}) &= \max\{D(x_{2n}, x_{2n+1}), D(x_{2n}, x_{2n+1}), D(x_{2n+1}, x_{2n+2})\} \\ &= \max\{D(x_{2n}, x_{2n+1}), D(x_{2n+1}, x_{2n+2})\}. \end{aligned}$$

If  $M(x_{2n}, x_{2n+1}) = D(x_{2n+1}, x_{2n+2})$ , then

$$D(x_{2n+1}, x_{2n+2}) \leq (Tx_{2n} - Tx_{2n+1})D(x_{2n+1}, x_{2n+2}),$$

contradiction. Hence,

$$D(x_{2n+1}, x_{2n+2}) \leq (Tx_{2n} - Tx_{2n+1})D(x_{2n}, x_{2n+1}).$$

Similarly, we have

$$D(x_{2n+3}, x_{2n+2}) = D(Rx_{2n+2}, Sx_{2n+1}) \leq (Tx_{2n+2} - Tx_{2n+1})M(x_{2n+2}, x_{2n+1}),$$

where

$$\begin{aligned} M(x_{2n+2}, x_{2n+1}) &= \max\{D(x_{2n+2}, x_{2n+1}), D(x_{2n+2}, x_{2n+3}), D(x_{2n+1}, x_{2n+2})\} \\ &= \max\{D(x_{2n+2}, x_{2n+1}), D(x_{2n+2}, x_{2n+3})\}. \end{aligned}$$

Obviously,  $M(x_{2n+2}, x_{2n+1}) = D(x_{2n+2}, x_{2n+1})$ , hence,

$$D(x_{2n+3}, x_{2n+2}) \leq (Tx_{2n+2} - Tx_{2n+1})D(x_{2n+2}, x_{2n+1}).$$

As a result,  $D(x_n, x_{n+1}) \leq (Tx_{n-1} - Tx_n)D(x_{n-1}, x_n)$  for all  $n \in \mathbb{N}$ , we obtain

$$\frac{D(x_n, x_{n+1})}{D(x_{n-1}, x_n)} \leq Tx_{n-1} - Tx_n,$$

and so

$$\sum_{k=1}^n \frac{D(x_k, x_{k+1})}{D(x_{k-1}, x_k)} \leq \sum_{k=1}^n (Tx_{k-1} - Tx_k) = Tx_0 - Tx_n < \infty,$$

then

$$\lim_{k \rightarrow \infty} \frac{D(x_k, x_{k+1})}{D(x_{k-1}, x_k)} = 0,$$

which implies there exist  $\kappa \in (0, 1)$  and  $n_0 \in \mathbb{N}$  such that  $D(x_n, x_{n+1}) \leq \kappa D(x_{n-1}, x_n)$  for all  $n \geq n_0$ , it can be easily proved that

$$\lim_{n \rightarrow \infty} D(x_{n-1}, x_n) = 0.$$

By continuing the proof process of Theorem 3.1, we get  $\{x_n\}$  is a  $\mathcal{F}$ -Cauchy sequence and there exists an element  $\beta$  in  $X$  such that  $x_n \rightarrow \beta$ .

Now, we will prove  $R\beta = \beta$ , if not, owing to  $(D_3)$ , we have

$$\begin{aligned} f(D(\beta, R\beta)) &\leq f(D(\beta, x_{2n+2}) + D(x_{2n+2}, R\beta)) + \delta \\ &= f(D(\beta, x_{2n+2}) + D(R\beta, Sx_{2n+1})) + \delta \\ &\leq f(D(\beta, x_{2n+2}) + (T\beta - Tx_{2n+1})M(\beta, x_{2n+1})) + \delta, \end{aligned}$$

where

$$\begin{aligned} M(\beta, x_{2n+1}) &= \max\{D(\beta, x_{2n+1}), D(\beta, R\beta), D(x_{2n+1}, x_{2n+2})\} \\ &= D(\beta, R\beta) \text{ as } n \rightarrow \infty. \end{aligned}$$

It yields that

$$f^{-1}[f(D(\beta, R\beta)) - \delta] \leq D(\beta, x_{2n+1}) + (T\beta - Tx_{2n+1})D(\beta, R\beta),$$

by using the property of  $T$ , we obtain  $\lim_{n \rightarrow \infty} f^{-1}[f(D(\beta, R\beta)) - \delta] \leq 0$ , then

$$\lim_{n \rightarrow \infty} f(D(\beta, R\beta)) \leq -\infty,$$

which is contradict with  $D(\beta, R\beta) > 0$ . Therefore,  $\beta = R\beta$ .

Similarly, owing to the continuity of  $T$ , we have

$$\begin{aligned} f(D(\beta, S\beta)) &\leq f(D(\beta, x_{2n+1}) + D(x_{2n+1}, S\beta)) + \delta \\ &= f(D(\beta, x_{2n+1}) + D(Rx_{2n}, S\beta)) + \delta \\ &\leq f(D(\beta, x_{2n+1}) + (Tx_{2n} - T\beta)M(x_{2n}, \beta)) + \delta \\ &= -\infty \text{ as } n \rightarrow \infty, \end{aligned}$$

as a result,  $\beta = S\beta$ .

Uniqueness: Assume that  $\beta$  and  $\gamma$  are two common fixed-points of  $R$  and  $S$ ,  $\gamma \neq \beta$ , and so

$$0 < D(\beta, \gamma) = D(R\beta, S\gamma) \leq (T\beta - T\gamma)M(\beta, \gamma),$$

clearly,  $M(\beta, \gamma) = D(\beta, \gamma)$ , thus,

$$0 < D(\beta, \gamma) \leq (T\beta - T\gamma)D(\beta, \gamma), \quad (3.13)$$

and

$$0 < D(\gamma, \beta) \leq (T\gamma - T\beta)D(\gamma, \beta). \quad (3.14)$$

According to  $(D_2)$ , if  $T\beta \neq T\gamma$ , it can be proved that (3.13) and (3.14) cannot be established at the same time. As a consequence,  $D(\beta, \gamma) = 0$ , i.e.  $\beta = \gamma$ , the proof is completed.

Using Theorem 3.3 with  $R = S$ , we can easily obtain the following corollary.  $\square$

**Corollary 3.4.** *Let  $(X, D)$  be a  $\mathcal{F}$ -complete generalized  $\mathcal{F}$ -metric space and  $R : X \rightarrow X$  be a nondecreasing mapping. Suppose that there exists a continuous and nonincreasing mapping  $T : X \rightarrow [0, 1)$ , such that*

$$D(Rx, Ry) \leq (Tx - Ty)M(x, y)$$

for all  $x, y$  in  $X$ , where

$$M(x, y) = \max\{D(x, y), D(x, Rx), D(y, Ry)\},$$

then  $R$  has a unique fixed-point.

Since  $0 \leq T(x) < 1$ , thus Theorem 3.3 can reduce below corollary.

**Corollary 3.5.** *Let  $(X, D)$  be a  $\mathcal{F}$ -complete generalized  $\mathcal{F}$ -metric space and  $R, S : X \rightarrow X$  be self-mappings. Suppose that there exists  $k \in [0, 1)$  such that*

$$D(Rx, Sy) \leq kM(x, y)$$

for all  $x, y$  in  $X$ , where

$$M(x, y) = \max\{D(x, y), D(x, Rx), D(y, Sy)\},$$

then  $R$  and  $S$  have a unique common fixed-point.

Let  $R = S$  in Corollary 3.5, it follows that

**Corollary 3.6** ([20]). *Let  $(X, D)$  be a  $\mathcal{F}$ -complete generalized  $\mathcal{F}$ -metric space and  $R : X \rightarrow X$  be a self-mapping. Suppose that there exists  $k \in [0, 1)$  such that*

$$D(Rx, Ry) \leq kD(x, y)$$

*for all  $x, y$  in  $X$ , then  $R$  has a unique fixed-point.*

## 4. Application

In this section, we will apply Corollary 3.5 to solve a system of linear algebraic equations as follows:

Consider the following linear algebraic equations:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n + \beta_1 = 0, \\ \dots \\ a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n + \beta_n = 0, \end{cases} \quad (4.1)$$

and

$$\begin{cases} c_{11}y_1 + c_{12}y_2 + \dots + c_{1n}y_n + \beta_1 = 0, \\ \dots \\ c_{n1}y_1 + c_{n2}y_2 + \dots + c_{nn}y_n + \beta_n = 0. \end{cases} \quad (4.2)$$

Then (4.1) can be written as  $Ax + \beta = O$ , where  $A = (a_{ij})_{n \times n}$ ,  $O = (0, 0, \dots, 0)^T$ ,  $x = (x_1, x_2, \dots, x_n)^T$  and  $\beta = (\beta_1, \beta_2, \dots, \beta_n)^T$ . Similarly, (4.2) can be written as  $Cy + \beta = O$ , where  $y = (y_1, y_2, \dots, y_n)^T$  and  $C = (c_{ij})_{n \times n}$ .

Let  $X = \mathbb{R}^n$ , for all  $x, y$  in  $X$ ,  $D(x, y) = \max_{1 \leq i \leq n} |x_i - y_i|^2$ ,  $f(x) = \ln x$  and  $\delta = \ln 2$ . Moreover, we define two self-mappings  $R, S : \mathbb{R}^n \rightarrow \mathbb{R}^n$  as

$$Rx = Bx + \beta, \quad (4.3)$$

and

$$Sy = Dy + \beta, \quad (4.4)$$

where  $B = (b_{ij})_{n \times n}$ ,  $b_{ii} = a_{ii} + 1$  and  $b_{ij} = a_{ij}$  if  $i \neq j$ , and also  $D = (d_{ij})_{n \times n}$ ,  $d_{ii} = c_{ii} + 1$  and  $d_{ij} = c_{ij}$  if  $i \neq j$ .

Clearly, the linear algebraic equations (4.1) and (4.2) have a common solution  $x^*$  in  $X$  if and only if  $x^*$  is a common fixed-point of  $R$  and  $S$ . For all  $1 \leq i \leq n$ , suppose that

$$\sum_{j=1}^n (b_{ij}x_j - d_{ij}y_j) \leq \max_{1 \leq j \leq n} \sqrt{k}(x_j - y_j), \quad (4.5)$$

where  $0 \leq k < 1$ . From (4.3)-(4.5), we get

$$D(Rx, Sy) = \max_{1 \leq i \leq n} \left[ \sum_{j=1}^n (b_{ij}x_j - d_{ij}y_j) \right]^2 \leq \max_{1 \leq j \leq n} k(x_j - y_j)^2 \leq kM(x, y).$$

Obviously, all conditions of Corollary 3.5 are satisfied,  $R$  and  $S$  have a common fixed-point  $x^*$ , and so  $x^*$  is a common solution of the linear algebraic equations (4.1) and (4.2).

## 5. Conclusion

In short, we have obtained some interesting and latest fixed-point results in generalized  $\mathcal{F}$ -metric spaces, and also an application for solving the linear algebraic equations. Applying these results to the field of integral equation or differential equation is worth spending more time to study.

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